

# Some notes on the article “A robust *a posteriori* error estimate for $h_p$ -adaptive DG methods for convection–diffusion equations”

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**Abstract:** The authors consider a model for convection–diffusion equations in two dimensions. They derived a robust *a posteriori* error estimate for  $h_p$ -adaptive DG methods for the problem under consideration. The ratio of the constants in the reliability and efficiency bounds is independent of the Péclet number  $\varepsilon$  of the equation, and hence the estimate is fully robust. It is applied the estimates as an error indicator in an  $h_p$ -adaptive refinement algorithm. Numerical examples show that the indicator is effective in locating and resolving the interior and boundary layers. Once the local mesh size is of the same order as the width of the boundary or interior layer, both the energy error and the error indicator were observed to convergence exponentially.

**Key words and phrases:** robust *a posteriori* error estimate;  $h_p$ -adaptive DG methods; convection–diffusion equations

**Subject Classification:** 65N30; 65N15

## 1 what i have learned...

1. **boundary or internal layers:** it is well known that solutions to convections–diffusion equation may have boundary or internal layers of small width where their gradients change extremely rapidly.
2. **how to approximate effciently such cases:** is to use adaptive finite element methods that are capable of locally refining the meshes in the vicinity of these layers
3. **where we refine:** the decision when to refine an element is usually based on *a posteriori* estimates of the error. For excelent surveys, as the authors advise, we refer to [VER 94, AIN 00]
4. **robust *a posteriori* estimates:** the design of robust *a posteriori* estimates has attracted a lot of attention. By robustness, we mean that estimates yield upper and lower bounds for the errors measured in suitable norms that differ by a factor independent of the *Péclet number* of the problem.

5. **literature:** there is already a literature concerning the a posteriori estimates in finite element and discontinuous Galerkin method. However, these methods are based on the use of a fixed, usually low polynomial degree. As a consequence, adaptive  $h$ -version methods yield at **most algebraic rates of convergence**. This is in contrast to  $h_p$ -version finite element methods, where the combination of  $h$ -refinement and  $h_p$ -refinement typically results in exponential rates of convergence; more details can be found in [SCH 98] and the references therein.
6. **DG (discontinuous Galerkin) methods and  $h_p$ -adaptivity:** DG methods are naturally suited for realizing  $h_p$ -adaptivity. Indeed, being based on discontinuous finite element spaces, these methods can easily deal with irregularly refined meshes and locally varying polynomial degrees.
7. **aim...:** the present article is an extension of the work [SCH 09] done by the same author. Indeed, [SCH 09] treats a posteriori estimates of the  $h$  version of DG methods.

## 2 problem to be solved

$$-\varepsilon \Delta u + a \cdot \nabla u = f(x), \quad x \in \Omega, \tag{1}$$

with

$$u(x) = 0, \quad x \in \partial\Omega, \tag{2}$$

where  $\Omega$  is a bounded Lipschitz polygon in  $\mathbb{R}^2$ .

It is assumed that  $\|a\|_{L^\infty(\Omega)}$  and the length scale of  $\Omega$  are one, so that  $\varepsilon^{-1}$  is the Péclet number of the problem.

## 3 meshes

It is assumed that the computational domain can be partitioned into shape-regular meshes  $\mathcal{T} = \{K\}$  of parallelograms  $K$ .

## 4 headlines of the article

- definition of the scheme
- definition of a robust a posteriori estimate
- Theorem of reliability
- Theorem of efficiency

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