

Mixed finite volume method for anisotropic problems

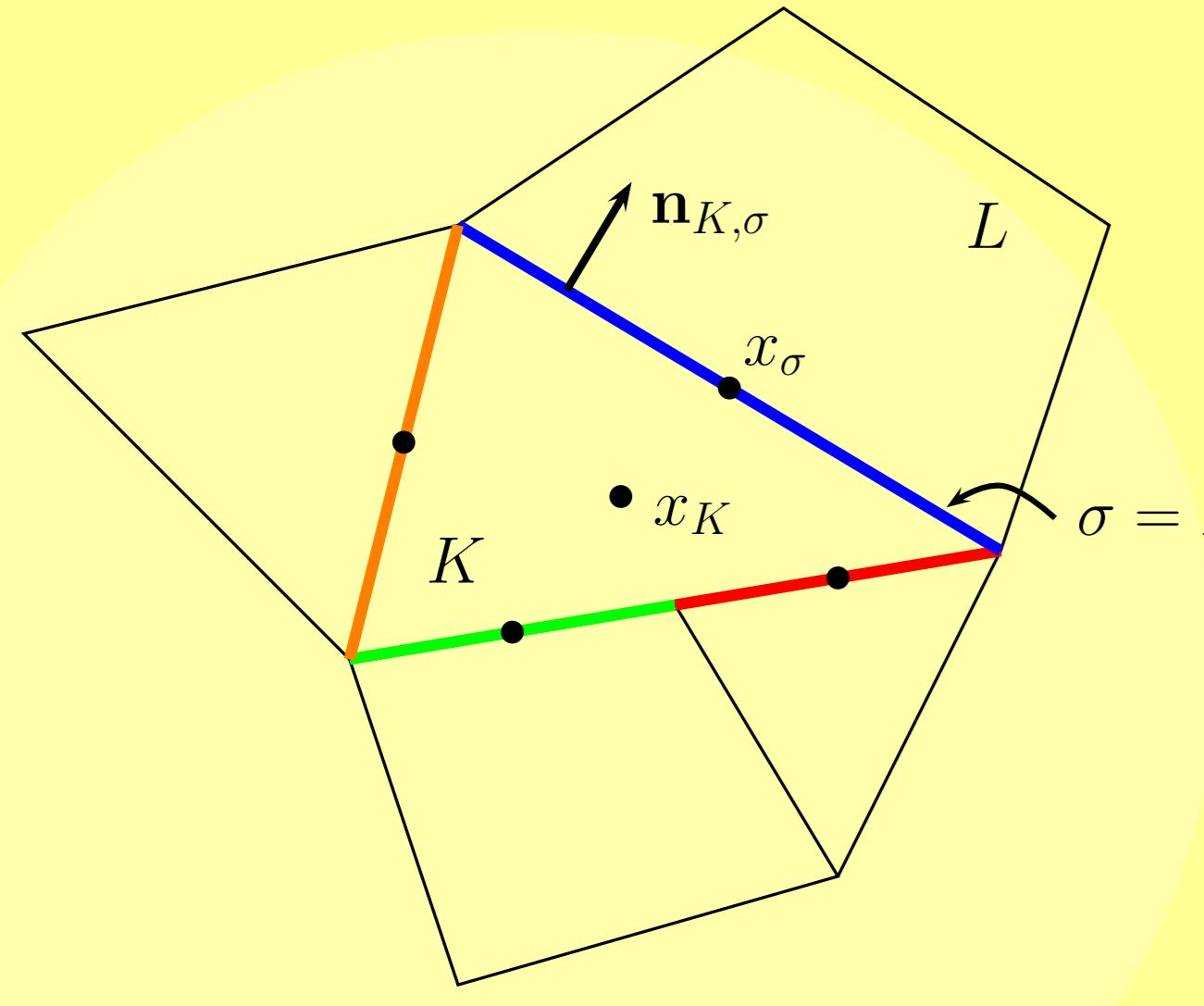
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Presentation of the scheme

- Problem : $-\operatorname{div}(\mathbb{K}\nabla u) = f$ with Dirichlet-Neumann boundary conditions

- Discrete unknowns :



- Scheme : ($h > 0$: size of the mesh ; $r_{K,\sigma} = \sum_{\sigma' \in \mathcal{E}_K} \alpha_{K,\sigma,\sigma'} F_{K,\sigma'}$: penalization term)

$$\mathbf{v}_K \cdot (x_\sigma - x_K) + r_{K,\sigma} = u_\sigma - u_K, \quad \forall K, \forall \sigma \text{ edge of } K$$

$$F_{K,\sigma} + F_{L,\sigma} = 0, \quad \forall \sigma = K|L \text{ interior edge}$$

$$u_\sigma = 0 \text{ (Dirichlet B.C.) or } F_{K,\sigma} = 0 \text{ (Neumann B.C.)}, \quad \forall \sigma \text{ exterior edge}$$

$$\left(\int_K \mathbb{K}(x) dx \right) \mathbf{v}_K = \sum_{\sigma \in \mathcal{E}_K} F_{K,\sigma} (x_\sigma - x_K), \quad \forall K$$

$$- \sum_{\sigma \in \mathcal{E}_K} F_{K,\sigma} = \int_K f(x) dx, \quad \forall K$$

Comments on the numerical results of the benchmark

- General remarks

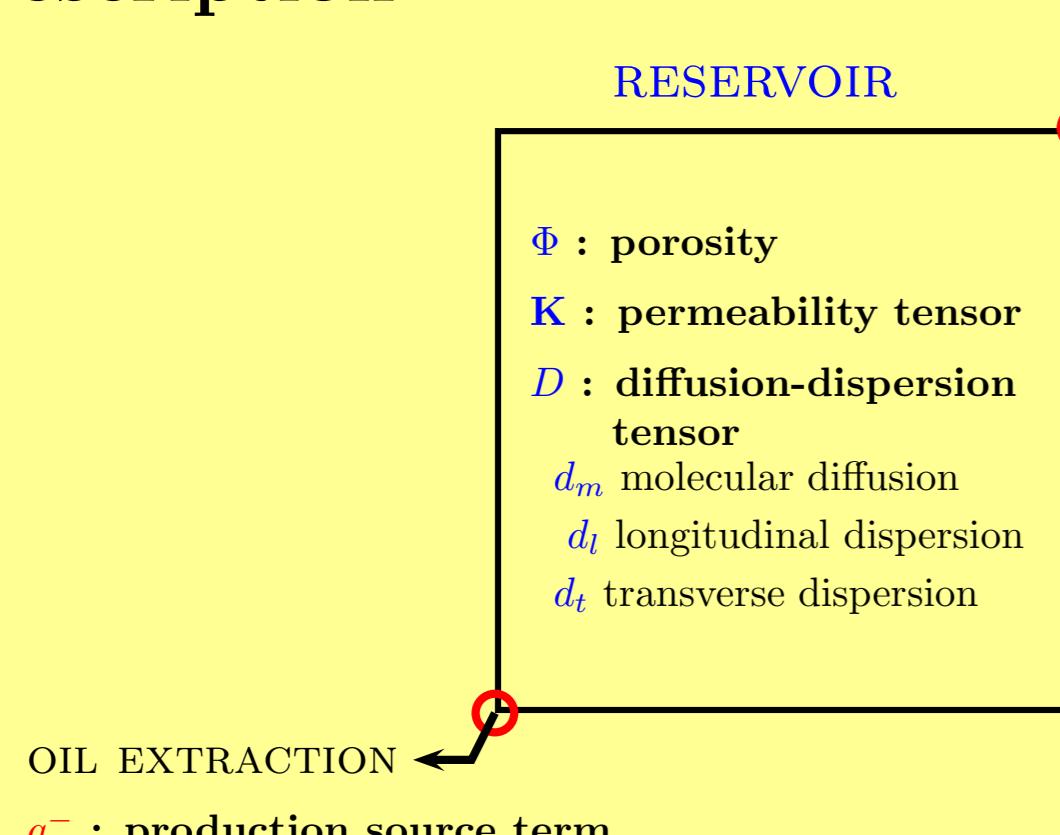
- Convergence of order 2 for the L^2 -norm of the function
- Convergence of order 1 for the L^2 -norm of the gradient
- Adaptability for the discretization of other kind of equations or coupled systems
- Usable method for 3D simulations

- Difference between strong and weak penalizations

- Perturbed parallelograms [Test 8, mesh8] (exact min=0, exact sumflux=0).
Strong penalization *Weak penalization*
 $\min=-8.08E-03, \text{sumflux}=8.46E-11$ $\min=-2.86E-01, \text{sumflux}=2.82E-15$

Miscible displacement in porous media

- Description



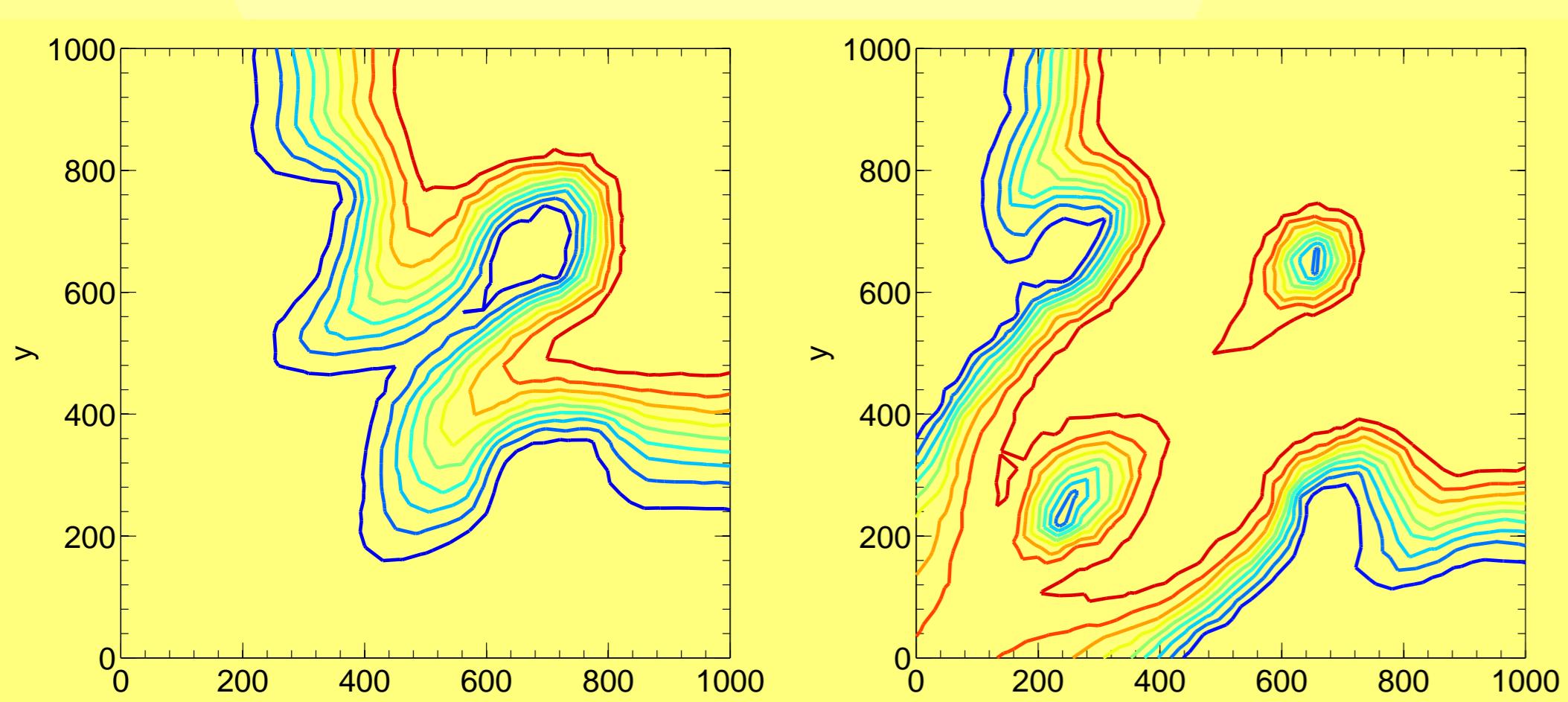
Unknowns

- p : pressure in the mixture
- \mathbf{U} : Darcy velocity
- c : concentration of the invading fluid

- Equations

$$\begin{aligned} \operatorname{div}(\mathbf{U}) &= q^+ - q^-, \quad \mathbf{U} = -\frac{\mathbf{K}(x)}{\mu(c)} \nabla p \\ \Phi(x) \partial_t c - \operatorname{div}(D(x, \mathbf{U}) \nabla c - c \mathbf{U}) + q^- c &= q^+ \hat{c} \\ D(x, \mathbf{U}) &= \Phi(x) \left(d_m \mathbf{I} + |\mathbf{U}| \left(d_l E(\mathbf{U}) + d_t (\mathbf{I} - E(\mathbf{U})) \right) \right), \quad E(\mathbf{U}) = \left(\frac{\mathbf{U}_i \mathbf{U}_j}{|\mathbf{U}|^2} \right)_{1 \leq i, j \leq d} \end{aligned}$$

- Numerical experiments, $t = 3$ years and $t = 10$ years



Practical implementation

- Hybridization :

- Elimination of the (\mathbf{v}_K)

- Rewriting the $(F_{K,\sigma})$ and the (u_K) in fonction of the (u_σ) :

$$\begin{pmatrix} B_K & (1)_{\sigma \in \mathcal{E}_K} \\ (1)_{\sigma \in \mathcal{E}_K}^T & 0 \end{pmatrix} \begin{pmatrix} (F_{K,\sigma})_{\sigma \in \mathcal{E}_K} \\ u_K \end{pmatrix} = \begin{pmatrix} (u_\sigma)_{\sigma \in \mathcal{E}_K} \\ - \int_K f(x) dx \end{pmatrix}$$

where B_K is defined by :

$$(B_K)_{\sigma, \sigma'} = \left(\int_K \mathbb{K}(x) dx \right)^{-1} (x_\sigma - x_K) \cdot (x_\sigma - x_K) + \alpha_{K,\sigma,\sigma'}$$

• \Rightarrow Linear system of size $\text{Card}(\mathcal{E}_{\text{int}})$ on $(u_\sigma)_{\sigma \in \mathcal{E}_{\text{int}}}$

- Two separate implementations for the benchmark : FORTRAN and MATLAB

- Recursive elimination of the unknowns

- Penalization :

- no penalization on triangular meshes ($r_{K,\sigma} = 0$)

- “strong penalization” : $r_{K,\sigma} = 6 \cdot 10^{-3} \frac{\operatorname{diam}(K)}{\operatorname{m}(\sigma)} F_{K,\sigma}$ or $r_{K,\sigma} = 10^{-7} F_{K,\sigma}$

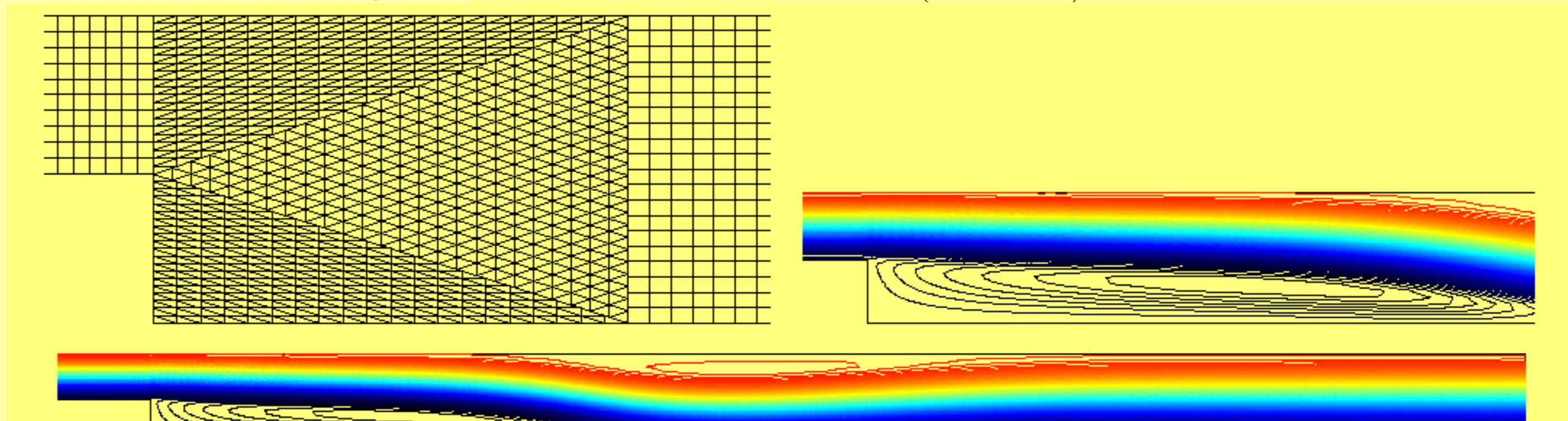
- “weak” penalization, which vanishes at order 1 :

$$r_{K,\sigma} = \sum_{\sigma' \in \mathcal{E}_K} l_{K,\sigma,\sigma'} \left(\frac{F_{K,\sigma'}}{\operatorname{m}(\sigma')} - \left(\int_K \mathbb{K}(x) dx \right) \mathbf{v}_K \cdot \mathbf{n}_{K,\sigma'} \right)$$

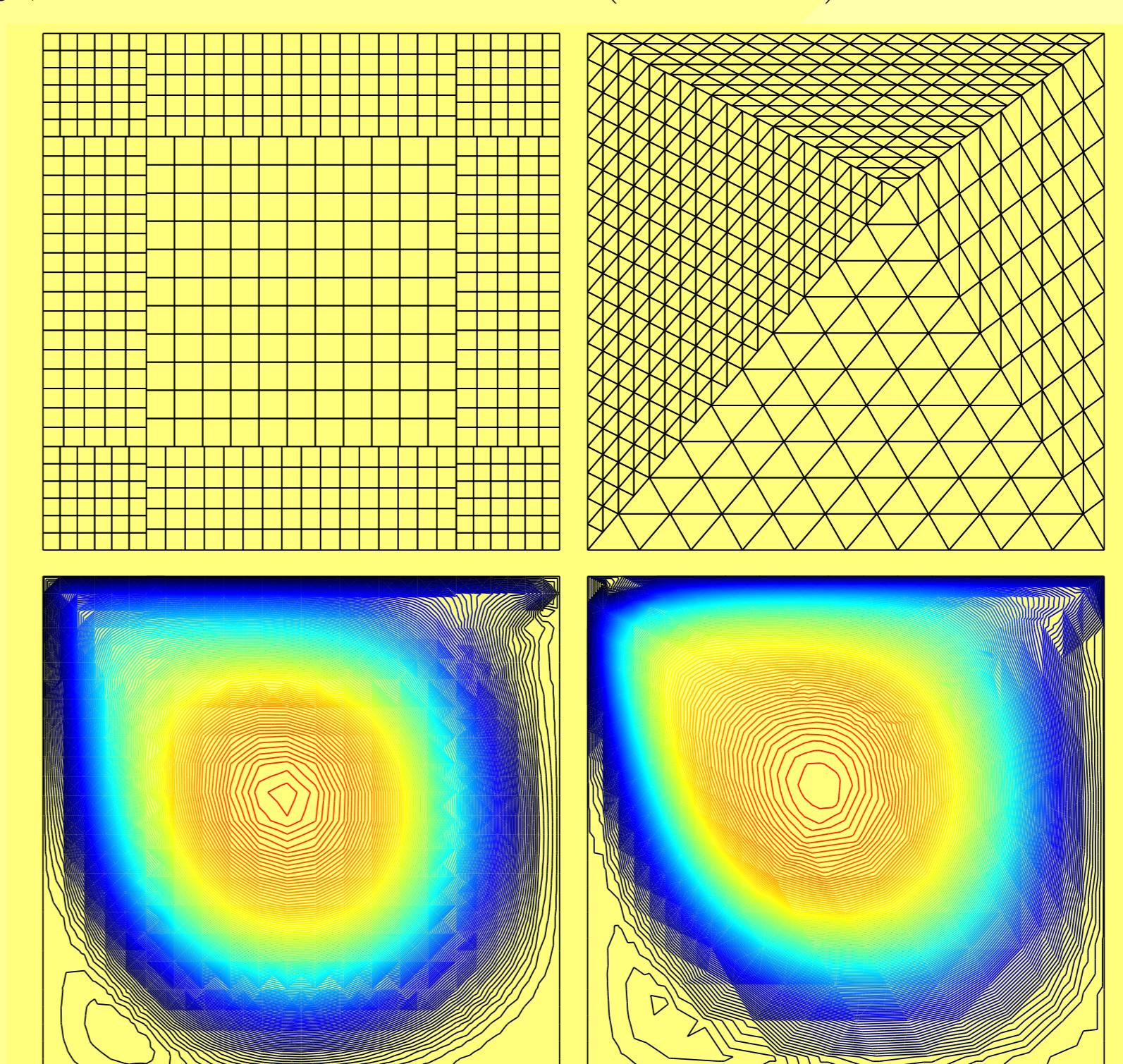
Navier-Stokes equations

- Description : incompressible Navier-Stokes equations without temperature

- Backward facing step, mesh and streamlines (Re=800)



- Lid driven cavity, meshes and streamlines (Re=1000)



Remark : proofs of convergence for all these implementations.