





Christoph Erath Institute for Numerical Mathematics 10. June 2008 joint work with S. Funken (Ulm), D. Praetorius (Vienna)

### Adaptive Finite Volume Method

A posteriori error estimate and adaptive mesh refinement for the cell-centered FVM and coupling with BEM

Page 1/16 Adaptive Finite Volume Method

## **Elliptic Model Problem**

 $\Omega \subset \mathbb{R}^2$  : bounded, connected domain with Lipschitz boundary  $\Gamma := \partial \Omega$ 

$$-\Delta u = f \in L^2(\Omega)$$
 in  $\Omega$ 

with mixed boundary conditions

$$u = u_D \in H^1(\Gamma_D)$$
 on  $\Gamma_D$   
 $\partial u / \partial \mathbf{n} = g \in L^2(\Gamma_N)$  on  $\Gamma_N$ 

where  $\Gamma_D$  as well as  $\Gamma_N$  are connected.

Discretization by cell-centered Finite Volume Method using the Diamond Path [Coudiére, Villedieu, M2AN 2000].

Page 1/16 Adaptive Finite Volume Method

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Discretization by cell-centered Finite Volume Method using the Diamond Path [Coudiére, Villedieu, M2AN 2000].

Develop a posteriori estimator based on a so-called Morley Interpolant,

Extended from [Nicaise, SIAM 2005] to the case of hanging nodes and mixed boundary conditions.

#### **Discretization** Find $u_h \in \mathcal{P}_0(\mathcal{T})$ such that



#### **Node Evaluation** For each node $a \in \mathcal{N}$ , we define

$$u_{a} = \begin{cases} \sum_{T \in \widetilde{\omega}_{a}} \psi_{T}(a) \, u_{T}, & \text{ for all } a \in \mathcal{N}_{I} \\ \\ u_{D}(a), & \text{ for all } a \in \mathcal{N}_{D} \\ \\ \\ \overline{u}_{a} + \overline{g}_{a}, & \text{ for all } a \in \mathcal{N}_{N} \end{cases}$$

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For example (special case):

$$\overline{u}_{a} = \frac{u_{T_{2}} - u_{T_{1}}}{|x_{T_{2}} - x_{T_{1}}|} |x_{a} - x_{T_{1}}| + u_{T_{1}}$$

If  $\mathbf{n}_{E_1} = \mathbf{n}_{E_2}$ :

$$\overline{g}_a = |x_a - a| \Big( \frac{1}{|E_1|} \int_{E_1} g \, ds + \frac{1}{|E_2|} \int_{E_2} g \, ds \Big) / 2$$



•  $\mathcal{I}u_h \in \mathcal{P}^2(\mathcal{T})$  is uniquely defined (defined on Morley Element).

- *I*u<sub>h</sub> ∈ *P*<sup>2</sup>(*T*) is uniquely defined (defined on Morley Element).
- *I* u<sub>h</sub> is continuous in all nodes a ∈ N but not globally continuous in Ω.



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- Some more properties such as jump-relations which are needed for the proof of an error estimator.

#### Reliability Helmholtz Decomposition

Given  $\Phi \in L^2(\Omega)^2$ , there are  $v, w \in H^1(\Omega)$  with  $\Phi = \nabla v + \text{curl } w$  such that  $v|_{\Gamma_D} = 0$  as well as  $w|_{\Gamma_N} = 0$ . In particular, there holds

$$\|\Phi\|_{L^{2}(\Omega)}^{2} = \|\nabla v\|_{L^{2}(\Omega)}^{2} + \|\operatorname{curl} w\|_{L^{2}(\Omega)}^{2}.$$

Refinement indicator

$$\eta_T^2 := h_T^2 \|f - f_T\|_{L^2(T)}^2 + \sum_{E \in \mathcal{E}_T \cap \mathcal{E}_E} h_E \| \left[ \nabla_T (\mathcal{I} u_h) \right] \|_{L^2(E)}^2 \\ + \sum_{E \in \mathcal{E}_T \cap \mathcal{E}_N} h_E \left\| \frac{\partial (u - \mathcal{I} u_h)}{\partial \mathbf{n}_E} \right\|_{L^2(E)}^2 + \sum_{E \in \mathcal{E}_T \cap \mathcal{E}_D} h_E \left\| \frac{\partial (u - \mathcal{I} u_h)}{\partial \mathbf{t}_E} \right\|_{L^2(E)}^2.$$

#### Theorem

There holds ( $C_{rel} > 0$  only depends on the shape of the elements in T)

$$oldsymbol{C}_{rel}^{-1} \| 
abla_{\mathcal{T}}(oldsymbol{u} - \mathcal{I}oldsymbol{u}_h) \|_{L^2(\Omega)} \leq \eta := \Big(\sum_{\mathcal{T} \in \mathcal{T}} \eta_{\mathcal{T}}^2 \Big)^{1/2}$$

### Efficiency

#### Bubble Functions b<sub>E</sub>



Triangulation.





Edge Lifting Operator:  $F_{ext} : \mathcal{P}_{p}(E) \rightarrow H^{1}(\omega_{E}^{*})$ 

#### Theorem

There is a constant  $C_{eff} > 0$  which depends only on  $c_E$  and the shape of the elements in T but neither on the size nor the number of elements such that

$$\eta_T^2 \leq C_{\text{eff}} \big( \|\nabla_{\mathcal{T}} (u - \mathcal{I} u_h)\|_{L^2(\omega_T)}^2 + h_T^2 \|f - f_{\mathcal{T}}\|_{L^2(\omega_T)}^2 \big), \quad \text{for all } T \in \mathcal{T}. \quad \Box$$

# Laplace Problem with Generic Singularity

L-shaped domain

$$\Omega = (-1,1)^2 \backslash \big( [0,1] \times [-1,0] \big)$$

 $u(x,y) = r^{2/3} \sin(2\varphi/3)$  with  $(x,y) = r(\cos\varphi,\sin\varphi)$ .



Page 8/16 Adaptive Finite Volume Method

#### **Error Comparison (Rectangle)**



Page 8/16 Adaptive Finite Volume Method

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#### 9510 elements







 $\Gamma_c$ 

 $\Omega_c$ 

Ω

### **Coupling Problem**

$$\begin{aligned} -\Delta u &= f & \text{in } \Omega \\ \Delta v &= 0 & \text{in } \Omega_c \end{aligned}$$
$$\begin{aligned} \lim_{|x| \to \infty} \left\{ v(x) - b \log(|x|) \right\} &= a \\ u &= v + u_0 & \text{on } \Gamma_c \\ \frac{\partial u}{\partial \mathbf{n}_{ext}} &= \frac{\partial v}{\partial \mathbf{n}_{ext}} + t_0 & \text{on } \Gamma_c \end{aligned}$$

 $a, b \in \mathbb{R}$  for the radiation condition

 $u_0$  and  $t_0$  denote jumps

# **The Coupling**

#### FVM part:

Apply divergence theorem and we get for all  $T \in \mathcal{T}$ 

$$-\int_{\partial T} \nabla u \cdot \mathbf{n}_T \, d\mathbf{s} = \int_T f \, d\mathbf{x}.$$
$$-\int_{\partial T \setminus \Gamma_C} \nabla u \cdot \mathbf{n}_T \, d\mathbf{s} - \int_{\partial T \cap \Gamma_C} \nabla u \cdot \mathbf{n}_T \, d\mathbf{s} = \int_T f \, d\mathbf{x},$$

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BEM part: Calderon System (exterior problem)

Cauchy data  $(\xi, \phi) := (v, \partial v / \partial \mathbf{n}_{ext})$ 

$$\left(\begin{array}{c} \xi \\ \phi \end{array}\right) := \left(\begin{array}{c} 1/2 + \mathcal{K} & -\mathcal{V} \\ -\mathcal{W} & 1/2 - \mathcal{K}^* \end{array}\right) \left(\begin{array}{c} \xi \\ \phi \end{array}\right) + \left(\begin{array}{c} a \\ 0 \end{array}\right)$$

 $\mathcal{V}$  single layer op.,  $\mathcal{K}$  double layer op.,

 $\mathcal{K}^*$  adjoint double layer op.,  $\mathcal{W}$  hypersingular op.

Page 12/16 Adaptive Finite Volume Method

### **Linear System of Equation**

The discrete problem reads:

Find  $u_h \in \mathcal{P}_0(\mathcal{T})$ ,  $u_{h,\Gamma_C} \in \mathcal{S}_1(\mathcal{E}_C)$ ,  $\xi_h \in \mathcal{S}_1(\mathcal{E}_C)$ ,  $\phi_h \in \mathcal{S}_0(\mathcal{E}_C)$  and  $\lambda \in \mathbb{R}$  such that

$$-\sum_{E\in\mathcal{E}_{T}\setminus\Gamma_{C}}\sigma_{T,E}F_{E}^{D}(u_{h})-\int_{\partial T\cap\Gamma_{C}}\phi_{h}\,ds=\int_{T}f\,dx+\int_{\partial T\cap\Gamma_{C}}t_{0}\,ds\quad\forall T\in\mathcal{T}$$
$$\overline{u}_{h,a}-u_{h,\Gamma_{C}}(a)+\overline{\varsigma}_{a,\phi_{h}}=\overline{\varsigma}_{a,t_{0}}\qquad\forall a\in\mathcal{N}_{C},$$

 $-\langle u_{h,\Gamma_{\mathcal{C}}},\psi_{h}\rangle-\langle \mathcal{V}\phi_{h},\psi_{h}\rangle+\langle (1/2+\mathcal{K})\xi_{h},\psi_{h}\rangle=-\langle u_{0},\psi_{h}\rangle \qquad \forall \psi_{h}\in \mathcal{S}_{0}(\mathcal{E}_{\mathcal{C}}),$ 

 $\langle (1/2 + \mathcal{K}^*)\phi_h, \theta_h \rangle + \langle \mathcal{W}\xi_h, \theta_h \rangle + \langle \lambda, \theta_h \rangle = 0 \qquad \qquad \forall \theta_h \in S_1(\mathcal{E}_C),$ 

$$\langle \xi_h, \mu \rangle = \mathbf{0} \qquad \qquad \forall \mu \in \mathbb{R}.$$

Page 12/16 Adaptive Finite Volume Method

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$$\begin{split} -\sum_{E\in\mathcal{E}_{T}\backslash\Gamma_{C}}\sigma_{T,E}F_{E}^{D}(u_{h}) - \int_{\partial T\cap\Gamma_{C}}\phi_{h}\,d\mathbf{s} &= \int_{T}f\,d\mathbf{x} + \int_{\partial T\cap\Gamma_{C}}t_{0}\,d\mathbf{s} \quad \forall T\in\mathcal{T}\\ \overline{u}_{h,a} - u_{h,\Gamma_{C}}(a) + \overline{\varsigma}_{a,\phi_{h}} &= \overline{\varsigma}_{a,t_{0}} \quad \forall a\in\mathcal{N}_{C},\\ -\langle u_{h,\Gamma_{C}},\psi_{h}\rangle - \langle \mathcal{V}\phi_{h},\psi_{h}\rangle + \langle (1/2+\mathcal{K})\xi_{h},\psi_{h}\rangle &= -\langle u_{0},\psi_{h}\rangle \quad \forall\psi_{h}\in\mathcal{S}_{0}(\mathcal{E}_{C}),\\ \langle (1/2+\mathcal{K}^{*})\phi_{h},\theta_{h}\rangle + \langle \mathcal{W}\xi_{h},\theta_{h}\rangle + \langle \lambda,\theta_{h}\rangle &= 0 \quad \forall\theta_{h}\in\mathcal{S}_{1}(\mathcal{E}_{C}),\\ \langle \xi_{h},\mu\rangle &= 0 \quad \forall\mu\in\mathbb{R}. \end{split}$$

Page 13/16 Adaptive Finite Volume Method

### **Quantities in A Posteriori Error Estimate**

Let  $\mathbf{n}_E$  and  $\mathbf{t}_E$  denote the normal and tangential vector of an edge E. Define

$$\begin{aligned} R_{1}^{2} &:= h_{T}^{2} \| f - f_{T} \|_{L^{2}(T)}^{2} \\ R_{2}^{2} &:= \sum_{E \in \mathcal{E}_{T}} h_{E} \| [\nabla_{\mathcal{T}}(\mathcal{I}u_{h}) \cdot \mathbf{n}_{E}] \|_{L^{2}(E)}^{2} ds \\ R_{3}^{2} &:= \sum_{E \in \mathcal{E}_{T}} h_{E} \| [\nabla_{\mathcal{T}}(\mathcal{I}u_{h}) \cdot \mathbf{t}_{E}] \|_{L^{2}(E)}^{2} ds \\ R_{4}^{2} &:= \sum_{E \in \mathcal{E}_{T} \cap \Gamma_{C}} h_{E} \| \mathcal{W}\xi_{h} + (1/2 + \mathcal{K}^{*})\phi_{h} \|_{L^{2}(E)}^{2} \end{aligned}$$

where

$$\begin{bmatrix} \nabla_{\mathcal{T}}(\mathcal{I}u_h) \cdot \mathbf{n}_E \end{bmatrix} := \begin{cases} (\nabla(\mathcal{I}u_h)|_{\mathcal{T}'} - \nabla(\mathcal{I}u_h)|_{\mathcal{T}}) \cdot \mathbf{n}_E, & \text{if } E \subset \Omega, \\ \nabla(\mathcal{I}u_h)|_{\mathcal{T}} \cdot \mathbf{n}_E - \phi_h - t_0, & \text{if } E \subset \Gamma_C, \end{cases}$$
$$\begin{bmatrix} \nabla_{\mathcal{T}}(\mathcal{I}u_h) \cdot \mathbf{t}_E \end{bmatrix} := \begin{cases} (\nabla(\mathcal{I}u_h)|_{\mathcal{T}'} - \nabla(\mathcal{I}u_h)|_{\mathcal{T}}) \cdot \mathbf{t}_E, & \text{if } E \subset \Omega, \\ \nabla(\mathcal{I}u_h)|_{\mathcal{T}}) \cdot \mathbf{t}_E - \frac{d}{ds}(u_0 + (1/2 + \mathcal{K})\xi_h - \mathcal{V}\phi_h), & \text{if } E \subset \Gamma_C, \end{cases}$$

#### **Error Estimator** Refinement indicator for all $T \in T$

$$\eta_T^2 := R_1^2 + R_2^2 + R_3^2 + R_4^2$$

and Error Estimator

$$\eta := \Big(\sum_{T \in \mathcal{T}} \eta_T^2 \Big)^{1/2}$$

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### Theorem (in work)

There holds

$$\| 
abla_{\mathcal{T}}(u - \mathcal{I}u_h) \|_{L^2(\Omega)} \leq C_{rel}^{-1}\eta$$

and

$$C_{\text{eff}}^{-1}\eta \leq \|\nabla_{\mathcal{T}}(u-\mathcal{I}u_h)\|_{L^2(\Omega)} + \|h(f-f_{\mathcal{T}})\|_{L^2(\Omega)},$$

where  $C_{rel}, C_{eff} > 0$  only depend on the shape of the elements in  $\mathcal{T}$ .

Proof: Ideas from above and [Carstensen, Funken, Computing 1999].

### Error Lshape (Triangle)

Choose a = 0, b = 1, the jumps  $u_0$  and  $t_0$  appropriate to

 $u = r^{2/3} \sin(2\varphi/3),$   $v = \log(|(x + 0.5, y - 0.5)|),$  f = 0.



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# **Further Questions?**

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