

# Discretization schemes for linear diffusion operators on general nonconforming meshes

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## 1. Objectives

Approximation of the solution  $u$  to

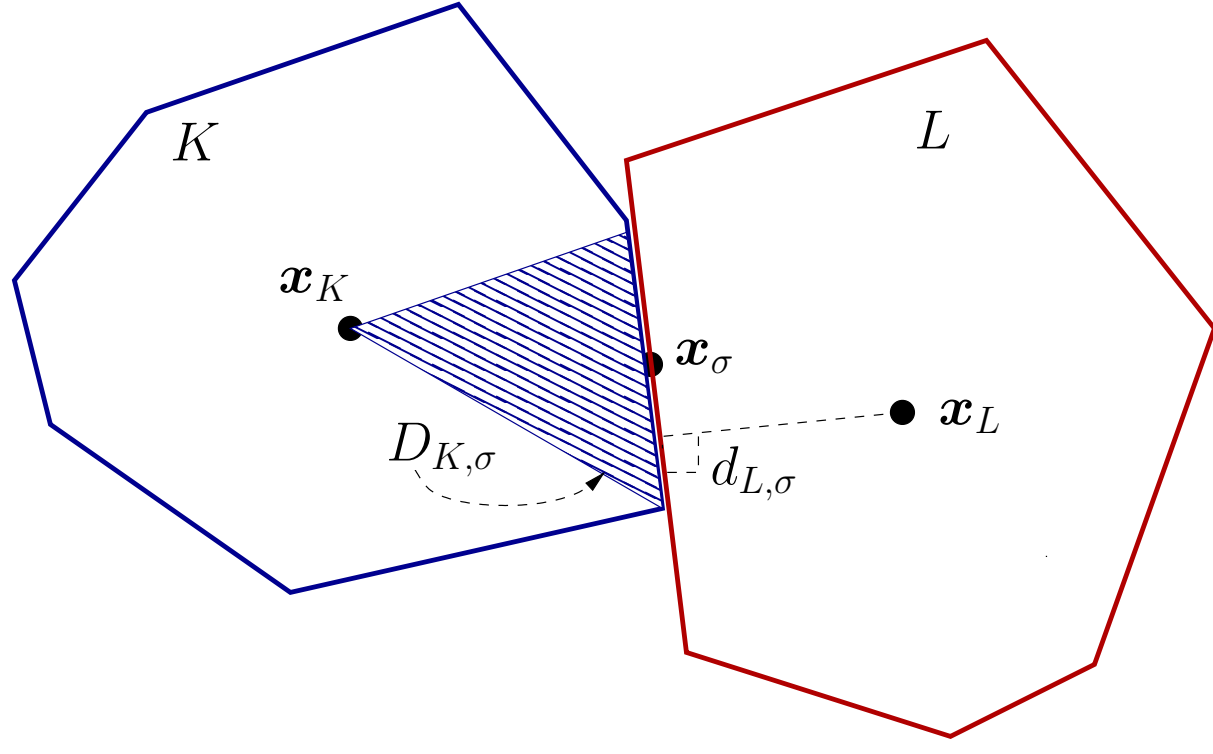
$$\begin{cases} u \in H_0^1(\Omega), \\ \int_{\Omega} \Lambda(\mathbf{x}) \nabla u(\mathbf{x}) \cdot \nabla v(\mathbf{x}) d\mathbf{x} = \int_{\Omega} f(\mathbf{x}) v(\mathbf{x}) d\mathbf{x} \quad \forall v \in H_0^1(\Omega) \end{cases}$$

with constraints:

- Any type of grid (conforming or not), 2D or 3D
- sparse, symmetric, positive and definite matrix
- approximation of  $u$  and  $\nabla u$  (with convergence and error estimate)

## 2. Discrete unknowns

**Discretization:**  $\mathcal{D} = (\mathcal{M}, \mathcal{E}, \mathcal{P})$  (control volumes, interfaces and points)



**Discrete unknowns:**  $(v_K)_{K \in \mathcal{M}}$  and  $(v_\sigma)_{\sigma \in \mathcal{E}}$

$$X_{\mathcal{D}} = \{v = ((v_K)_{K \in \mathcal{M}}, (v_\sigma)_{\sigma \in \mathcal{E}}), v_K \in \mathbb{R}, v_\sigma \in \mathbb{R}\}$$

$$X_{\mathcal{D},0} = \{v \in X_{\mathcal{D}} \text{ such that } v_\sigma = 0, \forall \sigma \in \mathcal{E}_{\text{ext}}\}$$

$H_{\mathcal{M}}(\Omega) \subset L^2(\Omega)$ : set of piecewise constant functions on the control volumes

$\Pi_{\mathcal{M}} v \in H_{\mathcal{M}}(\Omega)$ : piecewise constant function  $\Pi_{\mathcal{M}} v(\mathbf{x}) = v_K$  for a.e.  $\mathbf{x} \in K$

## 3. Discrete gradient

For  $u \in X_{\mathcal{D}}$ , construction of a discrete gradient:

- **Geometric formula.** For  $K \in \mathcal{M}$  (using  $x_\sigma$ , center of  $\sigma$ ):

$$\sum_{\sigma \in \mathcal{E}_K} m(\sigma) \mathbf{n}_{K,\sigma} (x_\sigma - x_K)^T = m(K) \text{Id}$$

- **Rough gradient.** For  $K \in \mathcal{M}$ :

$$\nabla_K u = \frac{1}{m(K)} \sum_{\sigma \in \mathcal{E}_K} m(\sigma) (u_\sigma - u_K) \mathbf{n}_{K,\sigma}$$

- **Stabilized gradient.** For  $K \in \mathcal{M}$  and  $\sigma \in \mathcal{E}_K$ :

$$\nabla_{K,\sigma} u = \nabla_K u + R_{K,\sigma} u \mathbf{n}_{K,\sigma},$$

with

$$R_{K,\sigma} u = \frac{\sqrt{d}}{d_{K,\sigma}} (u_\sigma - u_K - \nabla_K u \cdot (x_\sigma - x_K))$$

$$\nabla_{\mathcal{D}} u(\mathbf{x}) = \nabla_{K,\sigma} u \text{ for a.e. } \mathbf{x} \in D_{K,\sigma}$$

## 4. Numerical scheme, SUSHI

- **Reduction of the number of unknowns.**  $\mathcal{E}_{\text{int}} = \mathcal{B} \cup \mathcal{H}, \mathcal{H} = \mathcal{E}_{\text{int}} \setminus \mathcal{B}$ .

$$X_{\mathcal{D},\mathcal{B}} = \{v \in X_{\mathcal{D},0}, v_\sigma = \sum_{K \in \mathcal{M}} \beta_\sigma^K v_K, \sum_{K \in \mathcal{M}} \beta_\sigma^K = 1 \text{ \& } \mathbf{x}_\sigma = \sum_{K \in \mathcal{M}} \beta_\sigma^K \mathbf{x}_K, \forall \sigma \in \mathcal{B}\}$$

- **Discrete equations.**

$\text{card}(\mathcal{M}) + \text{card}(\mathcal{H})$  equations and unknowns  $u_K$  for  $K \in \mathcal{M}$  and  $u_\sigma$  for  $\sigma \in \mathcal{H}$

$$\begin{cases} \text{Find } u \in X_{\mathcal{D},\mathcal{B}} \text{ such that:} \\ \int_{\Omega} \Lambda \nabla_{\mathcal{D}} u \cdot \nabla_{\mathcal{D}} v d\mathbf{x} = \int_{\Omega} f \Pi_{\mathcal{M}} v d\mathbf{x}, \forall v \in X_{\mathcal{D},\mathcal{B}} \end{cases}$$

The so-called "local conservativity" is ensured for all  $\sigma \in \mathcal{H}$  (taking in the scheme  $v$  associated to  $\sigma$ ) but not for  $\sigma \in \mathcal{B}$

In 2d, for  $\Lambda = Id$  and with triangles or rectangles, the scheme is the classical finite volume scheme

## 5. Convergence of the approximate solution

**Non degeneracy of the discretization.**  $h_{\mathcal{D}} = \sup\{\text{diam}(K), K \in \mathcal{M}\}$

$$\theta_{\mathcal{D}} = \max \left( \max_{\sigma \in \mathcal{E}_{\text{int}}, K, L \in \mathcal{M}_\sigma} \frac{d_{K,\sigma}}{d_{L,\sigma}}, \max_{K \in \mathcal{M}, \sigma \in \mathcal{E}_K} \frac{h_K}{d_{K,\sigma}} \right)$$

$$\theta_{\mathcal{D},\mathcal{B}} = \max \left( \theta_{\mathcal{D}}, \max_{K \in \mathcal{M}, \sigma \in \mathcal{E}_K \cap \mathcal{B}} \frac{\sum_{L \in \mathcal{M}} |\beta_\sigma^K| |\mathbf{x}_L - \mathbf{x}_\sigma|^2}{h_K^2} \right)$$

Let  $\theta > 0$  and  $u_{\mathcal{D}}$  the approximate solution with  $\mathcal{D}$  and  $\mathcal{B}$  such that  $\theta_{\mathcal{D},\mathcal{B}} \leq \theta$ . Then  $\Pi_{\mathcal{M}} u_{\mathcal{D}}$  converges in  $L^2(\Omega)$  to the unique solution  $u$  and  $\nabla_{\mathcal{D}} u_{\mathcal{D}}$  converges to  $\nabla u$  in  $L^2(\Omega)^d$  as  $h_{\mathcal{D}} \rightarrow 0$ .

## 6. Proof of the convergence result

- **Discrete norms**

– Norm in  $X_{\mathcal{D}}$ :

$$\forall v \in X_{\mathcal{D}}, |v|_X^2 = \sum_{K \in \mathcal{M}} \sum_{\sigma \in \mathcal{E}_K} \frac{m(\sigma)}{d_{K,\sigma}} (v_\sigma - v_K)^2$$

– Norm in  $H_{\mathcal{M}}(\Omega)$  (Discrete  $H_0^1$ -norm)

For  $v \in H_{\mathcal{M}}(\Omega)$  and for  $\sigma \in \mathcal{E}_{\text{int}}$  with  $\mathcal{M}_\sigma = \{K, L\}$ ,  $D_\sigma v = |v_K - v_L|$  and  $d_\sigma = d_{K,\sigma} + d_{L,\sigma}$

For  $\sigma \in \mathcal{E}_{\text{ext}}$  with  $\mathcal{M}_\sigma = \{K\}$ ,  $D_\sigma v = |v_K|$  and  $d_\sigma = d_{K,\sigma}$

$$\forall v \in H_{\mathcal{M}}(\Omega), \|v\|_{1,2,\mathcal{M}} = \sum_{K \in \mathcal{M}} \sum_{\sigma \in \mathcal{E}_K} m_\sigma d_{K,\sigma} \left( \frac{D_\sigma v}{d_\sigma} \right)^2$$

– Comparison of the norms in  $X_{\mathcal{D},0}$

Thanks to the Cauchy-Schwarz inequality:

$$\|\Pi_{\mathcal{M}} v\|_{1,2,\mathcal{M}}^2 \leq |v|_X^2, \forall v \in X_{\mathcal{D},0}.$$

- **Equivalence of norms**

Thanks to

$$(R_{K,\sigma} u)^2 \geq \frac{\lambda d}{1 + \lambda} \left( \frac{u_\sigma - u_K}{d_{K,\sigma}} \right)^2 - \lambda d |\nabla_K u|^2 \left( \frac{|x_\sigma - x_K|}{d_{K,\sigma}} \right)^2.$$

Equivalence of norms:

$$\alpha |u|_X \leq \|\nabla_{\mathcal{D}} u\|_{L^2(\Omega)} \leq \beta |u|_X, \forall u \in X_{\mathcal{D}}$$

- **Estimate on  $u_{\mathcal{D}}$ , solution of the scheme**

Taking  $v = u_{\mathcal{D}}$  in the scheme and using the preceding equivalence of norms and a discrete Sobolev inequality lead to an estimate on  $u_{\mathcal{D}}$  in  $L^2$  and for the norm of  $X_{\mathcal{D}}$

- **Regularity of the possible limit and convergence of the gradient**

Let  $\mathcal{F}$  be a family of discretization and, for  $\mathcal{D} \in \mathcal{F}$ ,  $u_{\mathcal{D}}$  (not necessarily solution of the scheme) such that:

- $u_{\mathcal{D}} \in X_{\mathcal{D},0}$
- $|u_{\mathcal{D}}|_X \leq C$
- $\exists u \in L^2(\Omega)$  with  $\lim_{h_{\mathcal{D}} \rightarrow 0} \|\Pi_{\mathcal{M}} u_{\mathcal{D}} - u\|_{L^2(\Omega)} = 0$

Then  $u \in H_0^1(\Omega)$  and  $\nabla_{\mathcal{D}} u_{\mathcal{D}}$  weakly converges in  $L^2(\Omega)^d$  to  $\nabla u$  as  $h_{\mathcal{D}} \rightarrow 0$

- **Passing to the limit in the discrete equation**

For  $\varphi \in C^2_c(\Omega, \mathbb{R})$ , let:

1.  $P_{\mathcal{D}} \varphi = ((\varphi(\mathbf{x}_K))_{K \in \mathcal{M}}, (\varphi(\mathbf{x}_\sigma))_{\sigma \in \mathcal{E}})$  (so that  $P_{\mathcal{D}} \varphi \in X_{\mathcal{D}}$ )
2.  $P_{\mathcal{D},\mathcal{B}} \varphi$  the element  $v \in X_{\mathcal{D},\mathcal{B}}$  such that  $v_K = \varphi(\mathbf{x}_K)$  for all  $K \in \mathcal{M}$ ,  $v_\sigma = 0$  for all  $\sigma \in \mathcal{E}_{\text{ext}}$ ,  $v_\sigma = \sum_{K \in \mathcal{M}} \beta_\sigma^K \varphi(\mathbf{x}_K)$  for all  $\sigma \in \mathcal{B}$  and  $v_\sigma = \varphi(\mathbf{x}_\sigma)$  for all  $\sigma \in \mathcal{E}_{\text{int}} \setminus \mathcal{B}$
3.  $P_{\mathcal{M}} \varphi(\mathbf{x}) = \varphi(\mathbf{x}_K)$  for a.e.  $\mathbf{x} \in K$ , for all  $K \in \mathcal{M}$

Taking  $v = P_{\mathcal{D},\mathcal{B}} \varphi$  as test function in the scheme and using  $\Pi_{\mathcal{M}}(P_{\mathcal{D},\mathcal{B}} \varphi) = P_{\mathcal{M}} \varphi$ , the conclusion follows with the two following consistency results:

$$\|\nabla_{\mathcal{D}} P_{\mathcal{D}} \varphi - \nabla \varphi\|_{(L^\infty(\Omega))^d} \leq C h_{\mathcal{D}}$$

$$\lim_{h_{\mathcal{D}} \rightarrow 0} \|P_{\mathcal{D},\mathcal{B}} \varphi - P_{\mathcal{D}} \varphi\|_X = 0$$

Leading to:

$$\lim_{h_{\mathcal{D}} \rightarrow 0} \|\nabla_{\mathcal{D}} P_{\mathcal{D},\mathcal{B}} \varphi - \nabla \varphi\|_{(L^2(\Omega))^d} = 0$$