

# Finite Volumes Method on Evolving Surfaces

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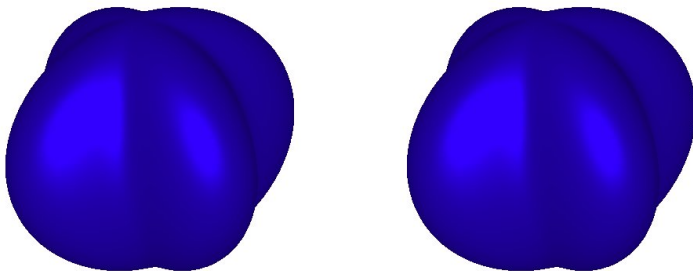
joint work with:

Martin Lenz, INS, University of Bonn  
Martin Rumpf, INS, University of Bonn

Aussois, 2008-06-10

- Motivation
- Aim
- Problem setting
- Recall: Finite Volumes on flat and fixed domain
- Discretization
- Existence and uniqueness
- Stability
- Error estimate
- Numerical Results

## Partial differential equation on surfaces



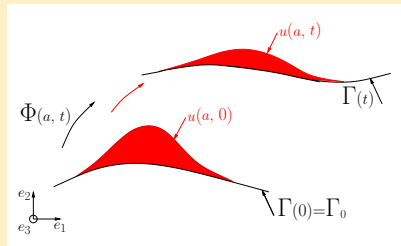
**Aim:** Finite volume approximation for advection dominated flow on evolving surfaces.

**cf.:**

G. Dziuk, C. M. Elliott "Finite elements on evolving surfaces" [2006]

Our approach is in addition based on:

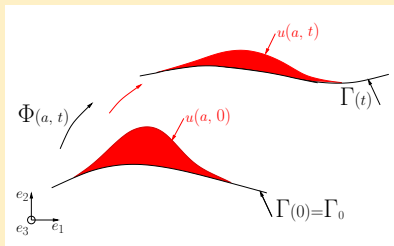
R. Eymard, T. Gallouët, R. Herbin "Finite Volume Method" [1997]



$\Gamma(t)$  : Family of 2-d smooth surfaces

$\Phi(\cdot, t)$  : Sufficiently smooth map,  $\Phi(\Gamma(0), t) = \Gamma(t)$

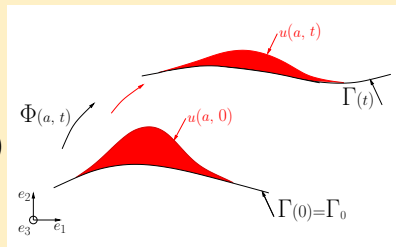
$u(a, t)$  : density of a scalar quantity on  $\Gamma(t)$



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$\Phi(\cdot, t)$  : Sufficiently smooth map,  $\Phi(\Gamma(0), t) = \Gamma(t)$

$u(a, t)$  : density of a scalar quantity on  $\Gamma(t)$



Find  $u(\cdot, t)$  such that

$$\dot{u} + u \nabla_{\Gamma(t)} \cdot v - \nabla_{\Gamma(t)} \cdot (\mathcal{D}_0 \nabla_{\Gamma(t)} u) = g \quad \text{on } \Gamma(t)$$

$$u(\cdot, 0) = u_0(\cdot) \quad \text{on } \Gamma_0$$

+BC

$v(\cdot, t)$  : Velocity field on  $\Gamma(t)$ ,  $g$  : source term

$\mathcal{D}_0$  : Symmetric elliptic diffusion tensor on the tangent plane

## Finite Volumes Method on Evolving Surfaces

R. Eymard, T. Gallouët and R. Herbin, Finite Volume Methods [1997]

Find  $u(\cdot, t)$  such that

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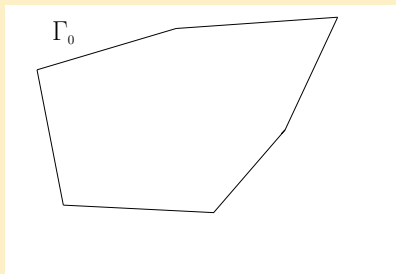
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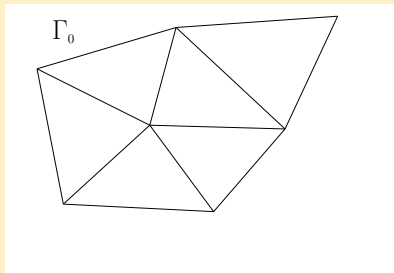
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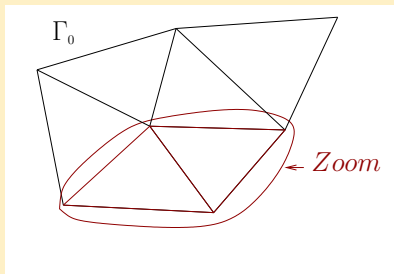
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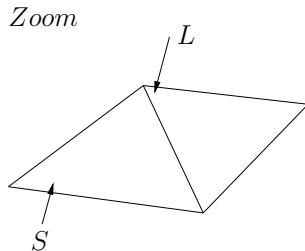
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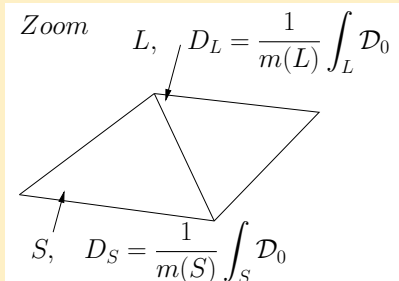
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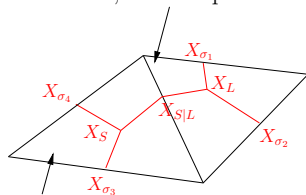
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Zoom  $L$ , scalar product:  $(D_L)^{-1}$



$S$ , scalar product:  $(D_S)^{-1}$

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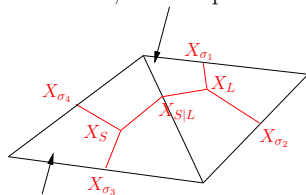
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Zoom  $L$ , scalar product:  $(D_L)^{-1}$



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$$\int_S \int_{t_k}^{t_{k+1}} \dot{u} - \int_S \int_{t_k}^{t_{k+1}} \nabla \cdot (\mathcal{D}_0 \nabla u) = \int_S \int_{t_k}^{t_{k+1}} g$$

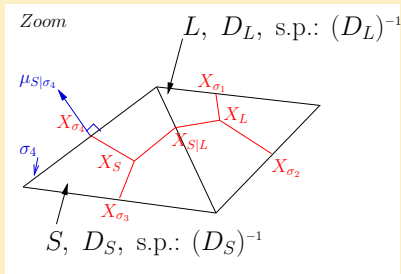
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$$\int_S \int_{t_k}^{t_{k+1}} \dot{u} \approx m(S) (u_S^{k+1} - u_S^k)$$

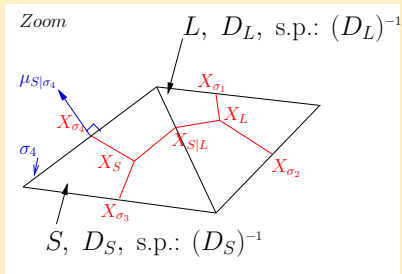
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$$- \underbrace{\int_S \int_{t_k}^{t_{k+1}} \nabla \cdot (\mathcal{D}_0 \nabla u)}_{\approx} - \tau \sum_{\sigma_i \subset \partial S} m(\sigma_i) \parallel D_S \mu_{S|\sigma_i} \parallel \frac{u_{\sigma_i}^{k+1} - u_S^{k+1}}{\parallel \overrightarrow{X_S X_{\sigma_i}} \parallel}$$

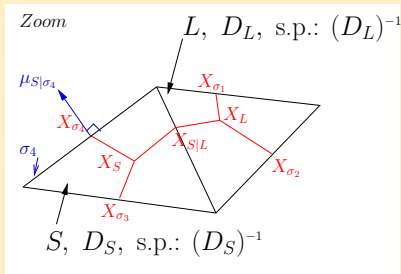
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$$- \tau \underbrace{\sum_{\sigma_i \in \partial S} m(\sigma_i) \| D_S \mu_{S|\sigma_i} \| \left\| \frac{u_{\sigma_i}^{k+1} - u_S^{k+1}}{\overrightarrow{X_S X_{\sigma_i}}} \right\|}_{\approx}$$

$\Rightarrow$

Using flux balance at interfaces

$$- \tau \sum_{\sigma_i \in \partial S} m(\sigma_i) \frac{\| D_S \mu_{S|\sigma_i} \| \| D_{L_i} \mu_{L_i|\sigma_i} \| \cdot (u_{L_i}^{k+1} - u_S^{k+1})}{\| D_{L_i} \mu_{L_i|\sigma_i} \| \left\| \overrightarrow{X_S X_{\sigma_i}} \right\| + \| D_S \mu_{S|\sigma_i} \| \left\| \overrightarrow{X_{L_i} X_{\sigma_i}} \right\|}$$

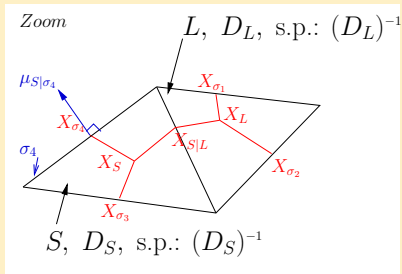
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$$\int_S \int_{t_k}^{t_{k+1}} g \approx m(S) \tau g_S^{k+1}$$

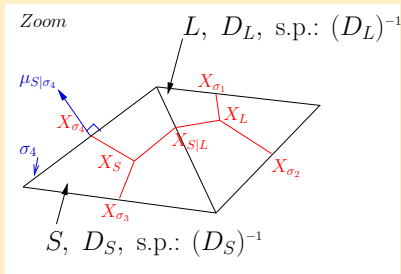
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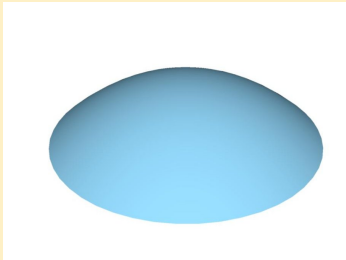
Find  $u(\cdot, t)$  such that

$$m(S) (u_S^{k+1} - u_S^k)$$

$$+ \tau \sum_{\sigma_i \in \partial S} m(\sigma_i) \frac{\| D_S \mu_{S|\sigma_i} \| \| D_{L_i} \mu_{L_i|\sigma_i} \| \cdot (u_{L_i}^{k+1} - u_S^{k+1})}{\| D_{L_i} \mu_{L_i|\sigma_i} \| \| \overrightarrow{X_S X_{\sigma_i}} \| + \| D_S \mu_{S|\sigma_i} \| \| \overrightarrow{X_{L_i} X_{\sigma_i}} \|}$$

$$= m(S) \tau g_S^{k+1}$$

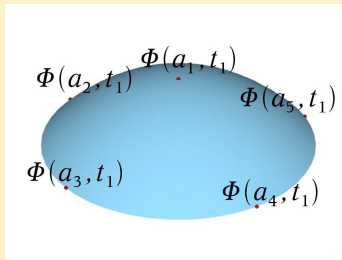
1



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<sup>1</sup>cf. G. Dziuk and C. M. Elliott, Finite Element on evolving surfaces [2006]

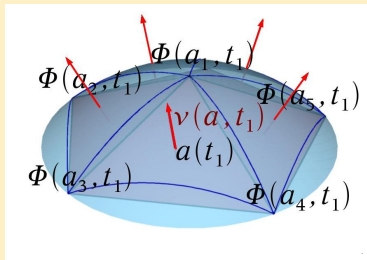
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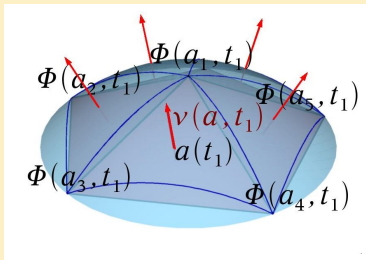
1



$$x(t) = a(t) - d(a(t))\nu(a(t))$$

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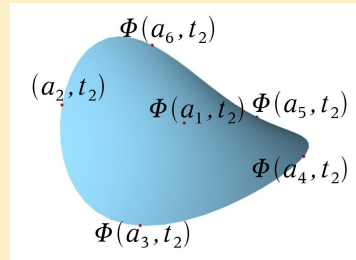
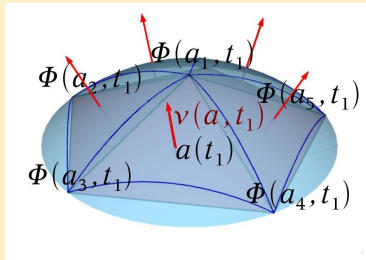
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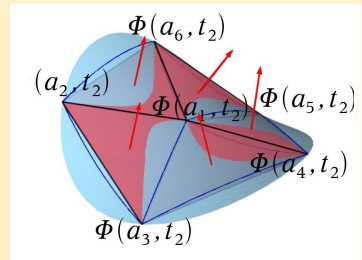
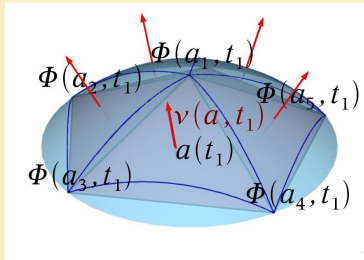
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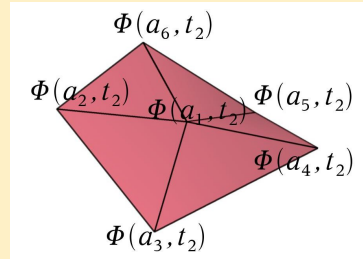
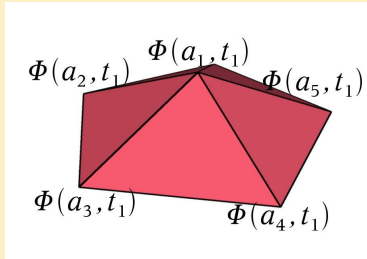
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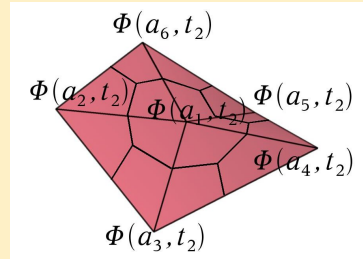
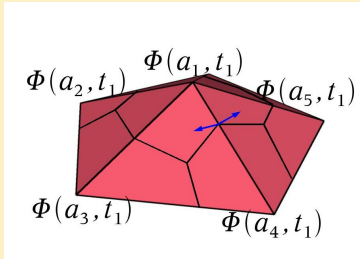
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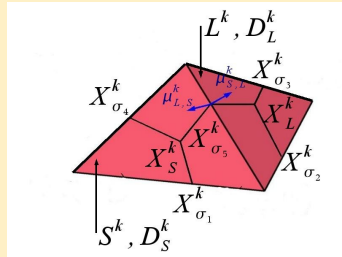
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A 3D diagram of a simplex (tetrahedron) with vertices labeled  $X^k_{\sigma_1}$ ,  $X^k_{\sigma_2}$ ,  $X^k_{\sigma_3}$ , and  $X^k_{\sigma_4}$ . The edges are labeled with vectors  $L^k$  and  $D_L^k$ . The faces are labeled with vectors  $S^k$  and  $D_S^k$ . A blue arrow indicates the direction of movement from  $X^k_{\sigma_1}$  towards the opposite face.

A 3D diagram of a simplex (a tetrahedron-like shape) with vertices labeled  $X^k_{\sigma_1}$ ,  $X^k_{\sigma_2}$ ,  $X^k_{\sigma_3}$ ,  $X^k_{\sigma_4}$ , and  $X^k_S$ . A blue arrow labeled  $\mu_{S,L}$  points from  $X^k_S$  towards the opposite face. Labels  $L^k, D_L^k$  and  $S^k, D_S^k$  are shown with arrows pointing to the simplex.

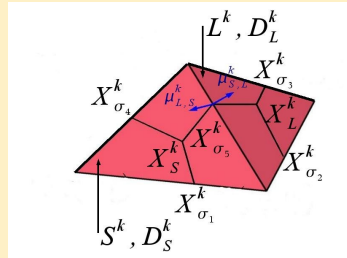
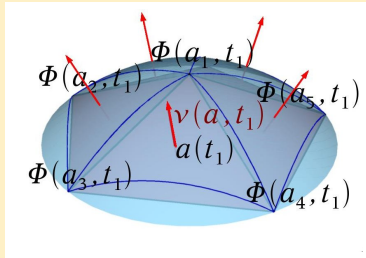
## Finite Volumes Method on Evolving Surfaces

*Zoom of two cells at  $t_k$*



For the simplicity, we assume  $\mathcal{D} = \mathcal{I}_d$

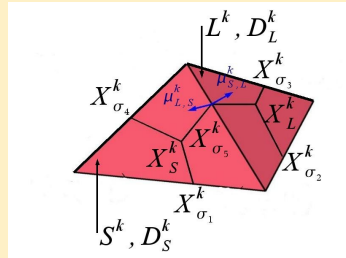
$$\begin{aligned} & \int_{t_k}^{t_{k+1}} \int_{S^l(t)} \left( \dot{u} + u \nabla_{\Gamma(t)} \cdot v \right) - \int_{t_k}^{t_{k+1}} \int_{S^l(t)} \nabla \cdot (\mathcal{D}_0 \nabla u) \\ &= \int_{t_k}^{t_{k+1}} \int_{S^l(t)} g \end{aligned}$$



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$$\begin{aligned} & \int_{t_k}^{t_{k+1}} \int_{S^l(t)} (\dot{u} + u \nabla_{\Gamma(t)} \cdot v) - \int_{t_k}^{t_{k+1}} \int_{S^l(t)} \nabla \cdot (\mathcal{D}_0 \nabla u) \\ &= \int_{t_k}^{t_{k+1}} \int_{S^l(t)} g \end{aligned}$$

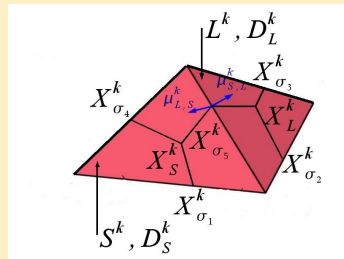
*Zoom* of two cells at  $t_k$



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$$\int_{t_k}^{t_{k+1}} \int_{S^l(t)} (\dot{u} + u \nabla_{\Gamma(t)} \cdot v) = \int_{t_k}^{t_{k+1}} \frac{d}{dt} \int_{S^l(t)} u$$

*Zoom* of two cells at  $t_k$



For the simplicity, we assume  $\mathcal{D} = \mathcal{I}_d$

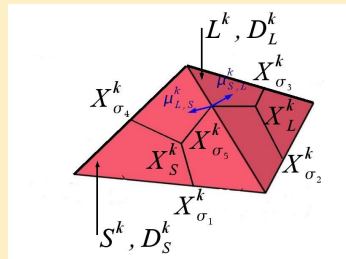
$$\begin{aligned} \int_{t_k}^{t_{k+1}} \int_{S^l(t)} (\dot{u} + u \nabla_{\Gamma(t)} \cdot v) &= \int_{t_k}^{t_{k+1}} \frac{d}{dt} \int_{S^l(t)} u \\ &\approx m(S(t_{k+1})) u_S^{k+1} - m(S(t_k)) u_S^k \end{aligned}$$

A 3D simplex (tetrahedron) is shown, representing a probability simplex. The vertices are labeled  $X^k_{\sigma_1}$ ,  $X^k_{\sigma_2}$ ,  $X^k_{\sigma_3}$ , and  $X^k_{\sigma_4}$ . The edges are labeled with  $L^k$  and  $D_L^k$ . The faces are labeled with  $S^k$  and  $D_S^k$ . The interior is labeled with  $\mu^k_{L,S}$  and  $\mu^k_{S,L}$ .

$$- \underbrace{\int_{t_k}^{t_{k+1}} \int_{S^l(t)} \nabla \cdot (\mathcal{D}_0 \nabla u)}_{\approx}$$

$$- \underbrace{\int_{t_k}^{t_{k+1}} \int_{S^l(t)} \nabla \cdot (\mathcal{D}_0 \nabla u)}_{\approx} \\ \tau \sum_{\sigma_i \subset \partial S(t_{k+1})} m(\sigma_i) \frac{u_{\sigma_i}^{k+1} - u_S^{k+1}}{\| \overrightarrow{X_S^{k+1} X_{\sigma_i}^{k+1}} \|}$$

Zoom of two cells at  $t_k$



For the simplicity, we assume  $\mathcal{D} = \mathcal{I}_d$

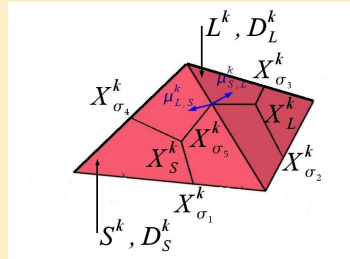
$$\underbrace{\tau \sum_{\sigma_i \in \partial S(t_{k+1})} m(\sigma_i) \frac{u_{\sigma_i}^{k+1} - u_S^{k+1}}{\| \overrightarrow{X_S^{k+1} X_{\sigma_i}^{k+1}} \|}}_{\approx}$$

$\implies$

Using flux balance at interfaces

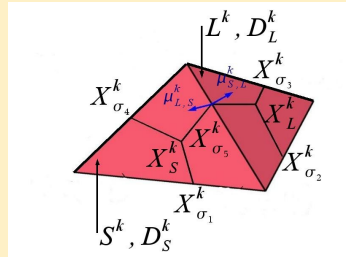
$$\tau \sum_{\sigma_i \in \partial S} m(\sigma_i) \frac{1}{\| \overrightarrow{X_S^{k+1} X_{\sigma_i}^{k+1}} \| + \| \overrightarrow{X_{L_i}^{k+1} X_{\sigma_i}^{k+1}} \|} \cdot (u_{L_i}^{k+1} - u_S^{k+1})$$

*Zoom* of two cells at  $t_k$



$$\int_{t_k}^{t_{k+1}} \int_{S^l(t)} g \approx \tau m(S(t_{k+1})) g_S^{k+1}$$

Zoom of two cells at  $t_k$



Find  $\left\{ u_S^{k+1} \right\}_{S, k}$  such that:

$$\begin{aligned}
 & m(S(t_{k+1})) u_S^{k+1} - m(S(t_k)) u_S^k \\
 & - \tau \sum_{\sigma_i \subset \partial S} m(\sigma_i) \frac{1}{\| \overrightarrow{X_S^{k+1} X_{\sigma_i}^{k+1}} \| + \| \overrightarrow{X_{L_i}^{k+1} X_{\sigma_i}^{k+1}} \|} \cdot \\
 & \cdot \left( u_{L_i}^{k+1} - u_S^{k+1} \right) = \tau m(S(t_{k+1})) g_S^{k+1}
 \end{aligned}$$

Find  $\left\{ u_S^{k+1} \right\}_{S, k}$  such that:

$$m(S(t_{k+1})) u_S^{k+1} - m(S(t_k)) u_S^k - \tau \sum_{\sigma_i \subset \partial S} m(\sigma_i) \frac{1}{\| \overrightarrow{X_S^{k+1} X_{\sigma_i}^{k+1}} \| + \| \overrightarrow{X_{L_i}^{k+1} X_{\sigma_i}^{k+1}} \|} \cdot (u_{L_i}^{k+1} - u_S^{k+1}) = \tau m(S(t_{k+1})) g_S^{k+1}$$

**Interpretation:**  $u^k = \{ u_S^k \} \equiv \sum_S u_S^k \chi_S$

$$(u^l)^k = \left\{ (u^l)_S^k \right\} \equiv \sum_S (u^l)_S^k \chi_S$$

where  $u^l(a, t_k) = (u^l)_S^k = u_S^k$  on  $S^l(t_k)$

**Theorem:** The above system has a unique solution

**Sketch of proof:**

**Recall scheme:**

Find  $\{u_S^{k+1}\}_{S,k}$  such that:

$$m(S(t_{k+1})) u_S^{k+1} - m(S(t_k)) u_S^k - \tau \sum_{\sigma_i \subset \partial S} m(\sigma_i) \frac{1}{\|X_S^{k+1} X_{\sigma_i}^{k+1}\| + \|X_{L_i}^{k+1} X_{\sigma_i}^{k+1}\|} \cdot (u_{L_i}^{k+1} - u_S^{k+1}) = \tau m(S(t_{k+1})) g_S^{k+1}$$

**Theorem:** The above system has a unique solution

## Sketch of proof:

### Induction

- Assume  $g \equiv 0$
- Assume  $u^k \equiv 0$
- For " $k + 1$ ", multiply equations by corresponding  $u_S^{k+1}$ ,  
( $S \subset \Gamma_h(t_{k+1})$ )
- Sum the result over the  $Ss \subset \Gamma_h(t_{k+1})$

### Recall scheme:

Find  $\{u_S^{k+1}\}_{S, k}$  such that:

$$m(S(t_{k+1})) u_S^{k+1} - m(S(t_k)) u_S^k - \tau \sum_{\sigma_i \subset \partial S} m(\sigma_i) \frac{1}{\|X_S^{k+1} X_{\sigma_i}^{k+1}\| + \|X_{L_i}^{k+1} X_{\sigma_i}^{k+1}\|} \cdot (u_{L_i}^{k+1} - u_S^{k+1}) = \tau m(S(t_{k+1})) g_S^{k+1}$$

**Theorem:** The above system has a unique solution

## Sketch of proof:

### Induction

- Sum the result over the  $S_s \subset \Gamma_h(t_{k+1})$

- One obtains

$$\|u^{k+1}\|_{\mathbb{L}^2(\Gamma_h^{k+1})}^2 + \tau \|u^{k+1}\|_{1, \Gamma_h(t_{k+1})}^2 = 0 \implies u^{k+1} \equiv 0$$

where

$$\|u^k\|_{1, \Gamma_h(t_k)}^2 = \sum_{\sigma_i = S(t_k) \mid L(t_k)} m(\sigma_i) \frac{1}{\|\overrightarrow{X_S^k X_{\sigma_i}^k}\| + \|\overrightarrow{X_L^k X_{\sigma_i}^k}\|} \cdot (u_L^k - u_S^k)^2$$

### Recall scheme:

Find  $\{u_S^{k+1}\}_{S,k}$  such that:

$$m(S(t_{k+1})) u_S^{k+1} - m(S(t_k)) u_S^k - \tau \sum_{\sigma_i \subset \partial S} m(\sigma_i) \frac{1}{\|\overrightarrow{X_S^{k+1} X_{\sigma_i}^{k+1}}\| + \|\overrightarrow{X_{L_i}^{k+1} X_{\sigma_i}^{k+1}}\|} \cdot (u_{L_i}^{k+1} - u_S^{k+1}) = \tau m(S(t_{k+1})) g_S^{k+1}$$

**Proposition 1:** ( Stability,  $\mathbb{L}^\infty(\mathbb{L})$  and  $\mathbb{L}^2(\mathbb{H}_0^1)$  )

$\{u^k\}$ , solution of the above system with the dirichlet condition  $u = 0$  on  $\partial\Gamma(t)$ ,  $\exists C \in \mathbb{R}$  such that

$$\sup_k \|u^{k+1}\|_{\mathbb{L}^2(\Gamma_h^{k+1})}^2 + \sum_k \tau \left( \|u^{k+1}\|_{1, \Gamma_h^{k+1}} \right)^2 \leq C \left( \|u^0\|_{\mathbb{L}^2(\Gamma_h^0)}^2 + \tau \sum_k \|g^{k+1}\|_{\mathbb{L}^2(\Gamma_h^{k+1})}^2 \right)$$

**Sketch of proof:**

**Recall scheme:**

Find  $\{u_S^{k+1}\}_{S,k}$  such that:

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**Sketch of proof:**

- For " $k + 1$ ", multiply equations by corresponding  $u_S^{k+1}$ ,  
(  $S \subset \Gamma_h(t_{k+1})$  )
- Sum the result over the  $S^{k+1} \subset \Gamma_h(t_{k+1})$
- Use Cauchy-Schwarz inequality

**Recall scheme:**

Find  $\{u_S^{k+1}\}_{S,k}$  such that:

$$m(S(t_{k+1})) u_S^{k+1} - m(S(t_k)) u_S^k - \tau \sum_{\sigma_i \subset \partial S} m(\sigma_i) \frac{1}{\| \overrightarrow{X_S^{k+1} X_{\sigma_i}^{k+1}} \| + \| \overrightarrow{X_{L_i}^{k+1} X_{\sigma_i}^{k+1}} \|} \cdot (u_{L_i}^{k+1} - u_S^{k+1}) = \tau m(S(t_{k+1})) g_S^{k+1}$$

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## Sketch of proof:

One obtains

$$\begin{aligned} & \frac{1}{2} \|u^j\|_{\mathbb{L}^2(\Gamma_h^j)}^2 + \tau \sum_{k=1 \dots j} \|u^k\|_{1, \Gamma_h^k}^2 \\ & \leq \frac{1}{2} \left( \|u^0\|_{\mathbb{L}^2(\Gamma_h^0)}^2 + \tau \sum_{k=1 \dots k_{max}} \|g^k\|_{\mathbb{L}^2(\Gamma_h^k)}^2 \right) + \frac{1}{2} (\delta(h, \tau) + 1) \tau \sum_{k=1 \dots j} \|u^k\|_{\mathbb{L}^2(\Gamma_h^k)}^2 \end{aligned}$$

## Recall scheme:

Find  $\{u_S^{k+1}\}_{S,k}$  such that:

$$\begin{aligned} & m(S(t_{k+1})) u_S^{k+1} - m(S(t_k)) u_S^k \\ & - \tau \sum_{\sigma_i \subset \partial S} m(\sigma_i) \frac{1}{\|X_S^{k+1} X_{\sigma_i}^{k+1}\| + \|X_{L_i}^{k+1} X_{\sigma_i}^{k+1}\|} \cdot (u_{L_i}^{k+1} - u_S^{k+1}) = \tau m(S(t_{k+1})) g_S^{k+1} \end{aligned}$$

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■  $\delta(h, \tau) = \left( \frac{m(S(t_k))}{m(S(t_{k+1}))} - 1 \right) \frac{1}{\tau}$  is bounded

■ Discrete version of Gronwall leads to the result.

## Recall scheme:

Find  $\{u_S^{k+1}\}_{S,k}$  such that:

$$\begin{aligned} & m(S(t_{k+1})) u_S^{k+1} - m(S(t_k)) u_S^k \\ & - \tau \sum_{\sigma_i \subset \partial S} m(\sigma_i) \frac{1}{\|X_S^{k+1} X_{\sigma_i}^{k+1}\| + \|X_{L_i}^{k+1} X_{\sigma_i}^{k+1}\|} \cdot (u_{L_i}^{k+1} - u_S^{k+1}) = \tau m(S(t_{k+1})) g_S^{k+1} \end{aligned}$$

**Proposition 2:** ( Stability,  $\mathbb{L}^2(\mathbb{L}^2)$  for  $\partial_t u$ ,  $\mathbb{L}^\infty(\mathbb{H}_0^1)$  for  $u$  )

$\{u^k\}$ , solution of the above system with the dirichlet condition  $u = 0$  on  $\partial\Gamma(t)$ ,  $\exists C \in \mathbb{R}$  such that

$$\sum_k \tau \left\| \frac{u^{k+1} - u^k}{\tau} \right\|_{\mathbb{L}^2(\Gamma_h^{k+1})}^2 + \sup_k \left( \|u^{k+1}\|_{1, \Gamma_h^{k+1}} \right)^2 \leq C \left( \|u^0\|_{\mathbb{L}^2(\Gamma_h^0)}^2 + \|u^0\|_{1, \Gamma_h^0}^2 + \tau \sum_k \|g^{k+1}\|_{\mathbb{L}^2(\Gamma_h^{k+1})}^2 \right)$$

Assumption:  $\tau \leq \tau \quad \forall k$

**Sketch of proof:**

**Recall scheme:**

Find  $\{u_S^{k+1}\}_{S,k}$  such that:

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Assumption:  $\tau \leq \tau \quad \forall k$

## Sketch of proof:

- For " $k + 1$ ", multiply equations by corresponding  $\left( \frac{u^{k+1} - u^k}{\tau} \right) \Big|_{S^{k+1}}$ ,  $(S^{k+1} \subset \Gamma_h(t_{k+1}))$
- Sum the result over the  $S^{k+1} \subset \Gamma_h(t_{k+1})$

## Recall scheme:

Find  $\{u_S^{k+1}\}_{S, k}$  such that:

$$m(S(t_{k+1})) u_S^{k+1} - m(S(t_k)) u_S^k - \tau \sum_{\sigma_i \subset \partial S} m(\sigma_i) \frac{1}{\|X_S^{k+1} X_{\sigma_i}^{k+1}\| + \|X_{L_i}^{k+1} X_{\sigma_i}^{k+1}\|} \cdot (u_{L_i}^{k+1} - u_S^{k+1}) = \tau m(S(t_{k+1})) g_S^{k+1}$$

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Assumption:  $\tau \leq \tau \quad \forall k$

## Sketch of proof:

- Use Cauchy-Schwarz inequality
- Use the previous result to obtain the solution

## Recall scheme:

Find  $\{u_S^{k+1}\}_{S,k}$  such that:

$$m(S(t_{k+1})) u_S^{k+1} - m(S(t_k)) u_S^k - \tau \sum_{\sigma_i \subset \partial S} m(\sigma_i) \frac{1}{\|X_S^{k+1} X_{\sigma_i}^{k+1}\| + \|X_{L_i}^{k+1} X_{\sigma_i}^{k+1}\|} \cdot (u_{L_i}^{k+1} - u_S^{k+1}) = \tau m(S(t_{k+1})) g_S^{k+1}$$

## Theorem:

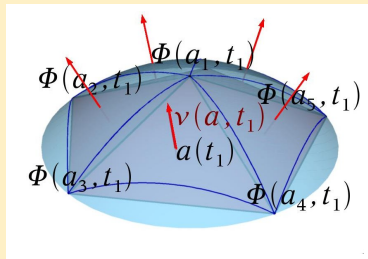
$u$ : Real solution on  $\Gamma(t)$ ,

$u^k$ : Discrete solution on  $\Gamma_h(t_k)$

$$E^k = \sum_S (u^{-l}(X_S^k, t_k) - u_S^k) \chi_S$$

$$\|E^k\|_{\mathbb{L}^2(\Gamma_h(t_k))} \leq C(h + \tau)$$

$$\tau = \tau$$



$$x(t) = a(t) - d(a(t))\nu(a(t))$$

**Theorem:**

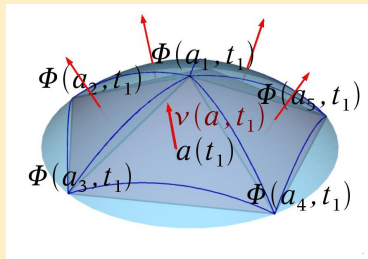
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$$x(t) = a(t) - d(a(t))\nu(a(t))$$

**Sketch of proof**

- Consistency of the geometry approximation.
- Consistency of the approximation of differential operators and integrals.
- Obtaining of discrete equations with  $E^{k+1}$  as unknown.
- multiplication of each equation by  $E_S^{k+1}$ , and partial summation in  $S^{k+1}$

## Theorem:

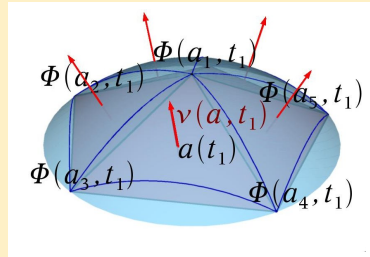
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$$\|E^k\|_{\mathbb{L}^2(\Gamma_h(t_k))} \leq C(h + \tau)$$

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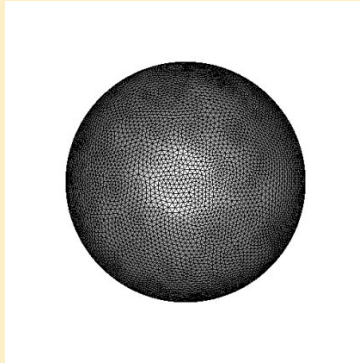
$$x(t) = a(t) - d(a(t))\nu(a(t))$$

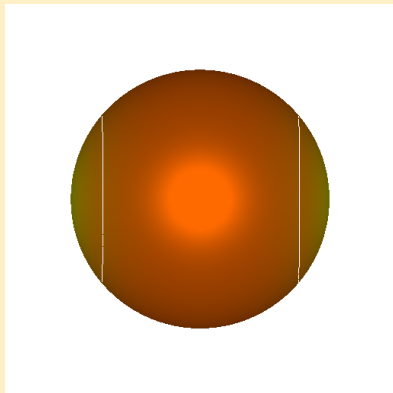
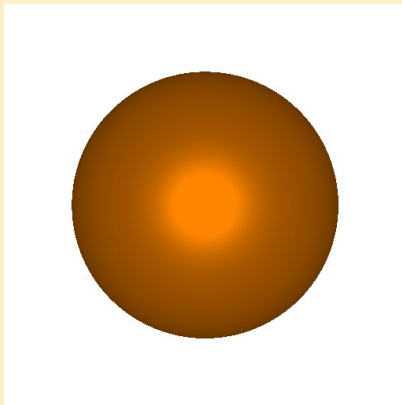
## Sketch of proof

- Cauchy-Schwarz inequality separates terms; One obtains

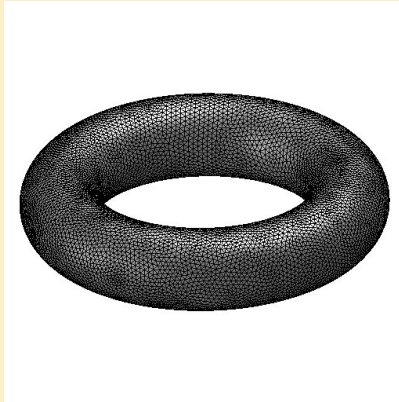
$$\begin{aligned} \frac{1}{2} \|E^{k+1}\|_{L^2(\Gamma_h^{k+1})}^2 + \tau \frac{1}{2} \|E^{k+1}\|_{1, \Gamma_h^{k+1}}^2 &\leq \frac{1}{2} \|E^k\|_{L^2(\Gamma_h^k)}^2 + \frac{1}{2} \delta(h, \tau) \tau \|E^{k+1}\|_{L^2(\Gamma_h^{k+1})}^2 \\ &\quad + \sqrt{m(\Gamma_h^{k+1})} C \tau (\tau + h) \|E^{k+1}\|_{L^2(\Gamma_h^{k+1})} + C \tau h^2 \end{aligned}$$

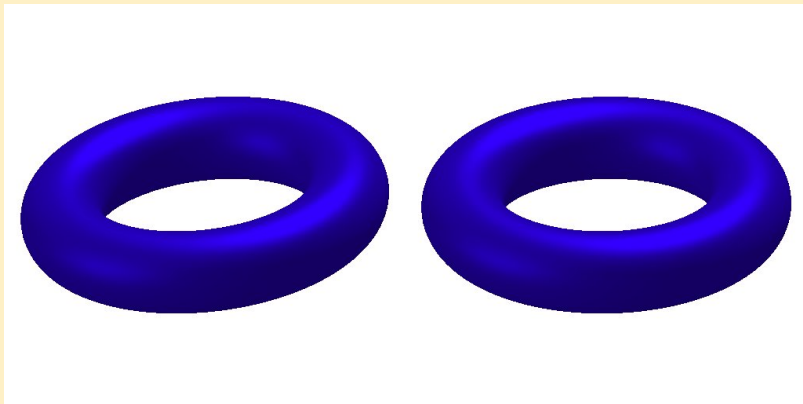
- Bound the sequence appearing on the right side to obtain the result.





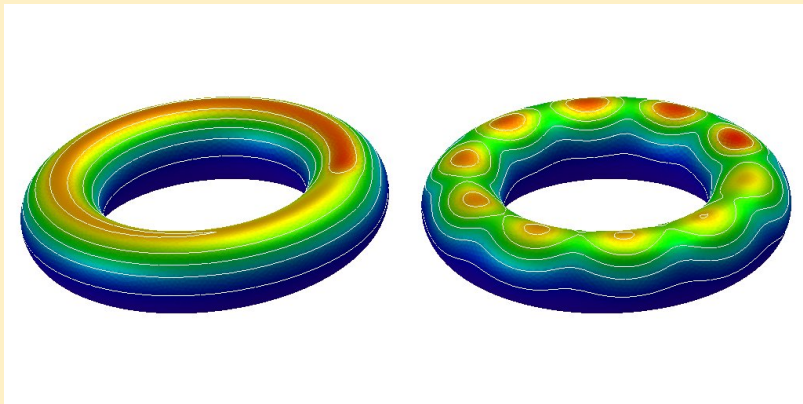
$$\mathcal{D}_0 = Id$$





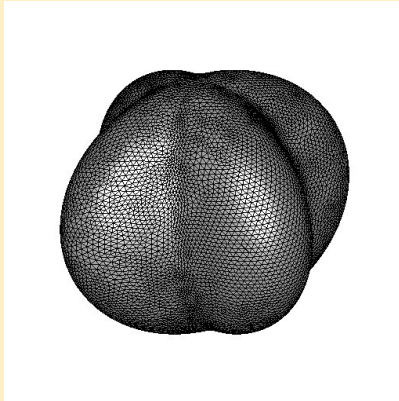
Time independent source term

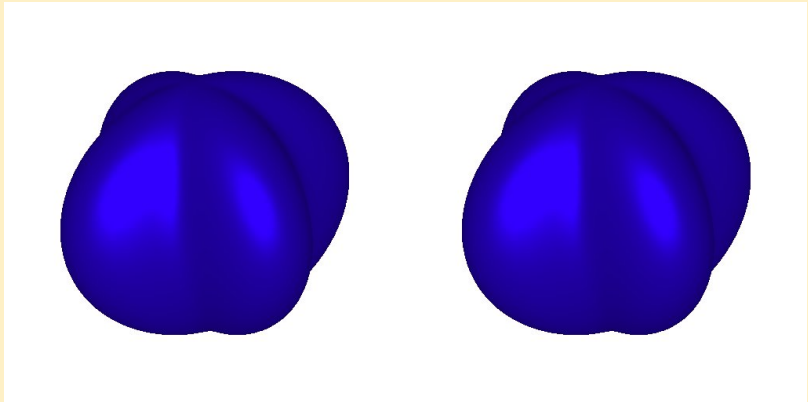
Periodic source term

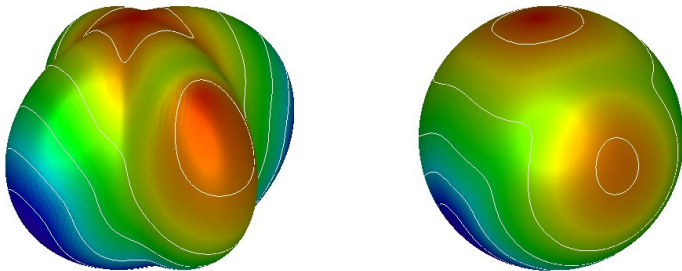


Time independent source term

Periodic source term







# THANK YOU FOR YOUR ATTENTION

Contact:

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`http://numod.ins.uni-bonn.de`

- Remark:**
- 1)  $dA_h$ : Discrete measure on  $\Gamma_h(t)$   
 $dA$ : Discrete measure on  $\Gamma(t)$   
 $h = \sup_S \text{diam}(S), \quad \delta_h, \quad \delta_h dA_h = dA \implies \sup_t \sup_{\Gamma(t)} |1 - \delta_h| \leq c h^2$
  - 2)  $u \in \chi(\Gamma_h(t))$ , and  $u^l$  its lift  

$$\|u\|_{L^2(\Gamma_h(t))}^2 \leq \frac{1}{\inf_t \inf_{\Gamma(t)} \delta_h} \|u^l\|_{L^2(\Gamma(t))}^2$$

$$\|u^l\|_{L^2(\Gamma(t))}^2 \leq \sup_t \sup_{\Gamma(t)} \delta_h \|u\|_{L^2(\Gamma_h(t))}^2$$