Scaling limits in adaptive dynamics

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PROBABILISTIC STRUCTURES IN EVOLUTION



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Plan

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NOVALENC SPUCTURES



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Plan

- Modelling adaptive dynamics
- Scaling limits and time scales
- On three limits in one step





Adaptive dynamics is a biological theory that describes the evolution of biological populations:

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Markov processes on space of positive measures.

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- Generator acting on a suitable core of functions $f:\mathcal{M}_p(\mathcal{X})\to\mathbb{R}$ by

$$Lf(\nu) = \int_{\mathcal{X}} [f(\nu + \delta_{x}) - f(\nu)] b(x)(1 - m(x))\nu(dx)$$

+
$$\int_{\mathcal{X}} [f(\nu - \delta_{x}) - f(\nu)] \left[d(x) + \int_{\mathcal{X}} c(x, y)\nu(dy) \right] \nu(dx)$$

+
$$\int_{\mathcal{X}} \int_{\mathcal{X}} [f(\nu + \delta_{x+y}) - f(\nu)] m(x) M(x, dy)\nu(dx).$$

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- *m*(*x*): rate of mutation of an individual *x* when giving birth;
- *M*(*x*, *dy*): probability distribution of the type of a mutant child of an individual of type *x*.



NEW PROMALESC SPUCTURES

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Case 2: $K \uparrow \infty$, $\sigma > 0$, fixed, $u \downarrow 0$, $T \sim \ln(1/u)$: (B, Wang, 2012) \Rightarrow deterministic jump process (trait substitution sequence)





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Case 3: $K \uparrow \infty$, $u = u_K \ll \frac{1}{K \ln K}$, $\sigma > 0$, fixed; $T \sim (Ku)^{-1}$ (Champagnat-Méléard 09,10):

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- Convergence to (random) jump process (Trait substitution sequence (TSS));
- Evolutionary branching at critical points of invasion fitness (Polymorphic evolution sequence (PES))



Case 4: $K \uparrow \infty$, $u \ll \frac{1}{K \ln K}$, $\sigma > 0$, $T \sim (Ku)^{-1}$; then $\sigma \downarrow 0$, time rescaled by σ^{-2} :

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$$\frac{dx_t}{dt} = \int h \left[h m(x_t) \overline{z}(x_t) \partial_1 f(x_t, x_t)\right]_+ M(x_t, dh),$$

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 $\bar{z}(x) = \frac{b(x)-d(x)}{c(x,x)}$: equilibrium of a monomorphic population of trait x $f(x,y) = b(y) - d(y) - \bar{z}(x)c(x,y)$: invasion fitness of trait y from x.

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All limits in one step.....

Theorem ((Baar, B, Champagnat, '15))

Assume that all functions are smooth that for some $\alpha > 0$,

$$\mathcal{K}^{-rac{1}{2}+lpha} \ll \sigma_{\mathcal{K}} \ll 1$$
 and
 $\exp(-\mathcal{K}^{lpha}) \ll u_{\mathcal{K}} \ll rac{\sigma_{\mathcal{K}}^{1+lpha}}{\mathcal{K} \ln \mathcal{K}},$

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Let $\nu_0^K \sim \overline{z}(x) \delta_x$, $x \in \mathcal{X}$. Then, for all T > 0,

$$\left(\nu_{t/(\kappa u_{\kappa}\sigma_{\kappa}^{2})}^{\kappa}\right)_{0\leq t\leq T}\rightarrow \left(\overline{z}(x_{t})\delta_{x_{t}}\right)_{0\leq t\leq T}$$

in probability, as $K \to \infty$, where $(x_t)_{0 \le t \le T}$ solves the CEAD.

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Scaling limits in adaptive dynamics

Basic strategy similar to the one in Champagnat et al: First show that a momomorphic initial population with trait x is replaced by a monomorphic population with trait x + h, if f(x, x + h) > 0 and h is in the support of $M(x, \cdot)$. Happens in three phases:







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- The resident population dies out.





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Almost all of this brakes down, if $\sigma = \sigma_K \downarrow 0$

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- In phases 1 and 3, much sharper control of resident (mutant) population needed to ensure approximation by super-(sub) critical branching processes
- Phase 2 takes time of order $\sigma_{K}^{-1} \ln K$: cannot use LLN!

HIVELING

In pictures



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In pictures



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Scaling limits in adaptive dynamics

σ_K ≫ K^{-1/2+α} ensures that evolutionary advantage of mutant is not compensated by fluctuations in the size of the resident population, which are of order K^{-1/2}.





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- $u_K \ll \frac{\sigma_k^{1+\alpha}}{K \ln K}$ ensures that no successful mutants arrive during an invasion period.
- $1/(Ku_K \sigma_K^2)$ is the number of mutations (σ_K^{-2}) necessary to move the population by order 1 times the mean time $(1/Ku_K)$ between two mutations.

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Main techniques

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- Extended process: We enrich the process by tagging each particle the the number of the mutation it is the offspring of. This allows to deal with simultaneous mutant.
- A rigorous stochastic Euler scheme to replace the LLN in Phase 2.







The deterministic system

For $\sigma = 0$, the deterministic Lotka-Volterra system with traits x and x + h has an invariant manifold of fixed points connecting the monomorphic resident and monomorphic mutant populations.



When $\sigma_K > 0$, this turns into an integral curve along which drift is $O(\sigma_K)$. Show that the stochastic system moves along this curve with speed $O(\sigma_K)$.

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Stochastic Euler scheme

Control the motion in small increments, similar to Euler schemes. Use that total mass changes only with speed $\sigma_{\mathcal{K}}^2$!



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Scaling limits in adaptive dynamics

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Thus, speed of change of x_t is

 $u_{\mathcal{K}}\mathcal{K}\bar{z}(x_t)m(x_t) \sigma_{\mathcal{K}}h \sigma_{\mathcal{K}}h[\partial_1 f(x_t, x_t)]_+$

where h is random with law $M(x_t, dh)$.

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where *h* is random with law $M(x_t, dh)$. Finally, LLN leads to CEAD.

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Thank you for your attention!

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