

# Lecture 3

## Hierarchical and latent class models

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Dakar – Fevrier 2010

## Outline

- ▶ Hierarchical models
- ▶ Mixture and latent class models
- ▶ Gibbs sampler algorithm for latent class models

## Hierarchical models

- ▶ Bayesian models can be defined hierarchically.
- ▶ Hyperprior distribution  $p(\psi)$
- ▶ Prior distribution  $p(\theta|\psi)$
- ▶ likelihood  $p(y|\theta)$
- ▶ In this case, the posterior distribution is

$$p(\theta, \psi|y) \propto p(y|\theta)p(\theta|\psi)p(\psi).$$

## Mixture model

- ▶ Case 1.  $y \in \mathbb{R}$
- ▶ Convex combination of densities. Let  $(p_k)_{k=1,\dots,K}$ ,  $\theta = (\theta_k)_{k=1,\dots,K}$  and  $\sum_{k=1}^K p_k = 1$

$$p(y|\theta) = \sum_{k=1}^K p_k p(y|\theta_k)$$

- ▶ Gaussian mixture. For  $\theta_k = (m_k, \sigma_k^2)$ , we have

$$p(y|\theta_k) = N(m_k, \sigma_k^2)(y)$$

## Mixture model

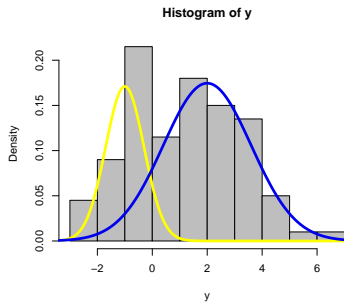
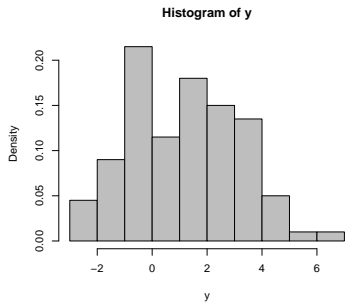
- ▶ Case 2.  $y = (y_1, \dots, y_n)$
- ▶ Sampling distribution.

$$p(y|\theta) = \prod_{i=1}^n \left( \sum_{k=1}^K p_k p(y_i|\theta_k) \right)$$

- ▶ Gaussian mixture. For  $i = 1, \dots, n$ ,

$$p(y_i|\theta_k) = N(m_k, \sigma_k^2)(y_i).$$

## Mixture model ( $K = 2$ )



$$p_1 = 30\% \quad p_2 = 70\%$$

## Clustering problems

- ▶ How many groups in the data?
- ▶ What are the within-group means and variances?
- ▶ For a given individual, what is the assignment probability?

## Mixtures as hierarchical models

- ▶ Introduce a **hidden (unobserved) class label**  $z_i \in \{1, \dots, K\}$  for each  $y_i$
- ▶ For  $i = 1, \dots, n$  consider

$$p(y_i | \theta, z_i) = p(y_i | \theta_{z_i}) = N(m_{z_i}, \sigma_{z_i}^2)(y_i)$$

- ▶ With this representation, we obtain

$$p(y_i | \theta) = \sum_{k=1}^K p(y_i | \theta_k) p(z_i = k)$$



## Bayesian model for Gaussian mixtures

- ▶ Hyperprior distribution on class labels:  $p(z) \propto 1$   
( $p(z_i = k) = \frac{1}{K}$ )
- ▶ Prior distribution on parameters

$$p(\theta) = \frac{1}{\sigma_1^2} \frac{1}{\sigma_2^2} \cdots \frac{1}{\sigma_K^2}$$

- ▶ Sampling distribution

$$p(y_i | \theta, z_i) = N(m_{z_i}, \sigma_{z_i}^2)(y_i), \quad i = 1, \dots, n$$

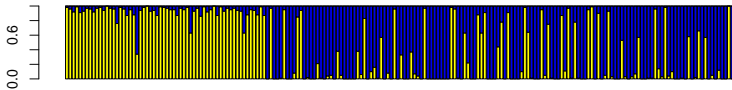
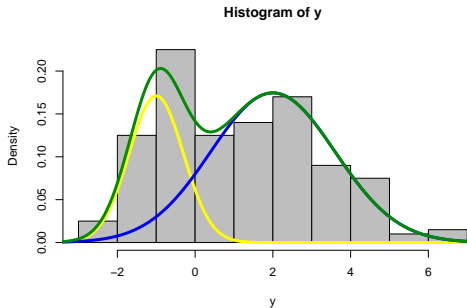
- ▶  $z$  is a hidden variable.

## Creating an artificial data set ( $n = 200$ )

- ▶  $y_1, \dots, y_{60}$  are sampled from **class 1**.

```
z.truth = c(rep(1,60), rep(2, 140))
m.truth = c(-1, 2)
s.truth = c(.7, 1.6)
for (i in 1:200){
  y[i]=rnorm(1,m.truth[z.truth[i]],sd=s.truth[z.truth[i]])
}
```

## Barplots: Marginal posterior distributions on class labels $p(z_i|y)$



## Clustering as an inference problem

- ▶ **Clustering** consists of estimating the unobserved class label  $z_i$  for each  $i$ .
- ▶ This can be achieved by computing the marginal posterior distributions,  $p(z_i|y)$ ,
- ▶ from the joint posterior distribution

$$p(\theta, z|y) \propto p(y|\theta, z)p(\theta)p(z)$$

## Gibbs sampler for the mixture model

- ▶ Consider the **multidimensional** parameter ( $n + 2K$  dimensions)

$$(z, \theta) = (z_1, \dots, z_n, m_1, \dots, m_K, \sigma_1^2, \dots, \sigma_K^2)$$

- ▶ The **Gibbs sampler cycle** (sweep) is

GS1. For  $i = 1, \dots, n$ , update  $z_i \sim p(z_i | \theta, y_i)$  (conditional independence)

GS2. For  $k = 1, \dots, K$ , update  $m_k \sim p(m_k | z, m_{-k}, \sigma^2)$  where

$$m_{-k} = (\dots, m_{k-1}, m_{k+1}, \dots)$$

GS3. For  $k = 1, \dots, K$ , update  $\sigma_k^2 \sim p(\sigma_k^2 | z, m, \sigma_{-k}^2)$

## Joint posterior distribution

- ▶ The joint posterior distribution is

$$\begin{aligned} p(\theta, z|y) &\propto \left( \prod_{i=1}^n p(y_i|\theta, z_i)p(z_i) \right) p(\theta) \\ &\propto \prod_{i=1}^n p(y_i|\theta, z_i) \prod_{k=1}^K \frac{1}{\sigma_k^2} \\ &\propto \prod_{i=1}^n \frac{1}{\sqrt{\sigma_{z_i}^2}} \exp\left(-\frac{1}{2\sigma_{z_i}^2}(y_i - m_{z_i})^2\right) \prod_{k=1}^K \frac{1}{\sigma_k^2} \end{aligned}$$

## Gibbs sampler GS1

- Conditional distribution on class labels (Bayes formula)

$$\begin{aligned} p(z_i|\theta, y_i) &= \frac{p(y_i|\theta, z_i)}{\sum_k p(y_i|\theta, k)} \\ &\propto \frac{\frac{1}{\sqrt{\sigma_{z_i}^2}} \exp(-\frac{1}{2\sigma_{z_i}^2}(y_i - m_{z_i})^2)}{\sum_{k=1}^K \frac{1}{\sqrt{\sigma_k^2}} \exp(-\frac{1}{2\sigma_k^2}(y_i - m_k)^2)} \end{aligned}$$

## R script

- ▶ Use the R function `sample`

```
for (i in 1:n) {  
  p = exp(-(y[i] - m)^ 2/2/sigma2 )/sqrt(sigma2)  
  z[i] = sample(1:K, 1, prob = p ) }  
}
```



## Gibbs sampler GS2

- ▶ Conditional distribution on **within-group means**
- ▶ Let  $n_k$  be the current size of class  $k$ ,  $n_k = \#\{i : z_i = k\}$ , we have (exercise)

$$p(m_k | m_{-k}, \sigma^2, z, y) = N(\bar{y}_k, \frac{\sigma_k^2}{n_k})$$

with

$$\bar{y}_k = \frac{1}{n_k} \sum_{i: z_i=k} y_i.$$

## R script

- ▶ Use the R function `rnorm`

```
nk[k]=sum(z==k)
```

```
m[k]=rnorm(1,mean(y[z==k]),sd=sqrt(sigma2[k]/nk[k]))
```

## Gibbs sampler GS3

- ▶ Conditional distribution on **within-group variances**
- ▶ Let  $n_k$  be the current size of class  $k$ ,  $n_k = \#\{i : z_i = k\}$ , we have (exercise)

$$p(\sigma_k^2 | m, \sigma_{-k}^2, z, y) = \text{Inv}\chi^2(n_k, s_k^2)$$

with

$$s_k^2 = \frac{1}{n_k} \sum_{i: z_i=k} (y_i - m_k)^2.$$

## R script

- ▶ Use the R function `rchisq`

```
sigma2[k] = sum((y[z==k]-m[k])^ 2)/rchisq(1,  
nk[k])
```

## Gibbs sampler for mixture model (1)

```
mcmc.mix=function(y,niter=1000,m.o=
c(0,1),sigma2.o=c(1,1)) {
n=length(y);K=length(m.o);m=m.o;s2=sigma2.o
z=NULL;p=NULL;nk = NULL
p.mcmc=NULL;m.mcmc=NULL;sigma2.mcmc=NULL;z.mcmc=NULL
for(nit in 1:niter) {
for(i in 1:n) {
p=exp(-(y[i]-m)^ 2/2/s2)/sqrt(s2)
z[i]=sample(1:K,1,prob = p) }
z.mcmc=rbind(z.mcmc,z)
```

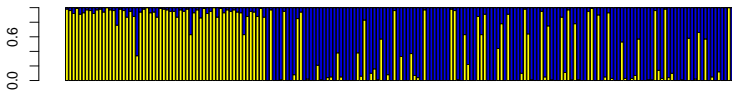
## Gibbs sampler for mixture model (2)

```
for(k in 1:K) {  
  nk[k]=sum(z==k)  
  m[k]=rnorm(1,mean(y[z==k]),sd=sqrt(s2[k]/nk[k]))  
  s2[k]=sum((y[z==k]-m[k])^2)/rchisq(1,nk[k]) }  
m.mcmc=rbind(m.mcmc,m)  
sigma2.mcmc=rbind(sigma2.mcmc,s2)  
}  
return(list(z=z.mcmc,m=m.mcmc,sigma2=sigma2.mcmc))  
}
```

## Results for the simulated data ( $K = 2$ classes)

- ▶ Run the program for  $y$  (30% of the total data set are from class 1)

```
obj=mcmc.mix(y,niter=300,m.o=c(2,4),sigma2.o=c(1,1))
mat = rbind(apply(obj$z[-(1:100)],MARGIN=2,
FUN=function(a)mean(a==1)),
apply(obj$z[-(1:100)],MARGIN=2,FUN=function(a)
mean(a==2)),
apply(obj$z[-(1:100)],MARGIN=2,FUN=function(a)
mean(a==3)))
barplot(mat,col=c("yellow","blue2","red"))
```



## Exercises

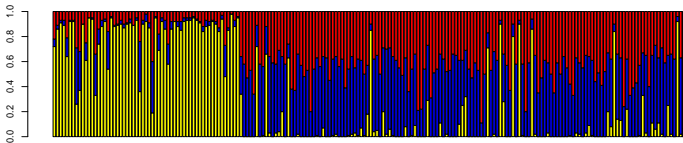
- ▶ Display posterior distributions for the within-group means and variances.
- ▶ Estimate the number of mis-assigned data ( $\approx 15\%$ ).



## Results for the simulated data ( $K = 3$ classes)

- ▶ Run the program for  $y$  (30% data from class 1)

```
obj=mcmc.mix.k(y,niter=200,m.o=c(-2,1,2),sigma2.o
=c(1,1,1))
mat = rbind(apply(obj$z[-(1:100)],MARGIN=2,
FUN=function(a)mean(a==1)),
apply(obj$z[-(1:100)],MARGIN=2,FUN=function(a)
mean(a==2)),
apply(obj$z[-(1:100)],MARGIN=2,FUN=function(a)
mean(a==3)))
barplot(mat,col=c("yellow","blue2","red"))
```



## Exercises

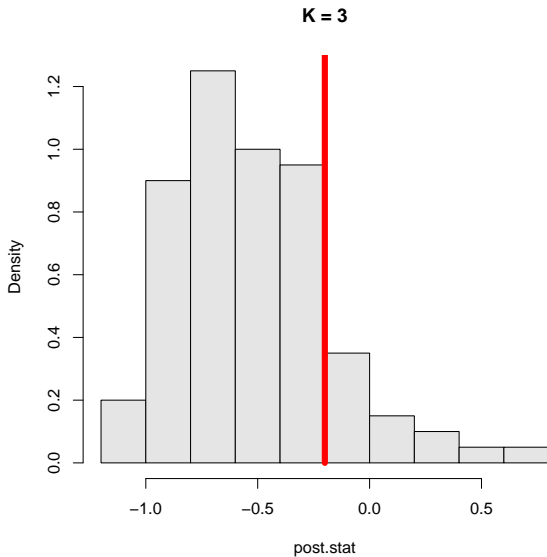
- ▶ Display posterior distributions for the within-group means and variances.
- ▶ Estimate the number of mis-assigned data ( $\approx 8\%$ ).
- ▶ which  $K$  is correct? Show the components in the  $K = 3$  model.
- ▶ Posterior predictive checks

## Posterior predictive checks

- ▶ Check the 3 component model with the kurtosis (skewness) statistics

```
post.stat = NULL
for (i in 1:100){
  zz = obj$z[i+100,];mm = obj$m[i+100,];ss2 =
  obj$sigma2[i+100,]
  yy = c(rnorm(sum(zz==1),mm[1],sqrt(ss2[1])),
  rnorm(sum(zz==2),mm[2],sqrt(ss2[2])),
  rnorm(sum(zz==3),mm[3],sqrt(ss2[3])))
  post.stat=c(post.stat,kurtosis(yy))}
```

## Posterior predictive checks



## Exercises

- Ex1. Implement the MCMC algorithm for mixtures of one-dimensional Gaussian distribution.
- Ex2. Analyze the `iris sepal length` data set (`data(iris); y = iris[,1]`)
- Ex3. Run the algorithm with  $K = 2$  and  $K = 3$ .
- Ex4. Which  $K$  is the best model?

## Bibliography and resources

- ▶ Gelman A, Carlin JB, Stern HS, Rubin DB (2004) Bayesian Data Analysis 2nd ed. Chapman & Hall, New-York.
- ▶ E. Paradis (2005) R pour les débutants. Univ. Montpellier II.
- ▶ R website: <http://cran.r-project.org/>