# Backward doubly stochastic differential equations and systems of quasilinear SPDEs 

Etienne Pardoux ${ }^{1, \star}$, Shige Peng ${ }^{2, \star \star}$<br>${ }^{1}$ Laboratoire APT, URA 225, Université de Provence, F-13331 Marseille Cedex 3, France<br>${ }^{2}$ Institute of Mathematics, Shandong University, Jinan, People's Republic of China

Received: 30 December 1992 / In revised form: 6 October 1993

Summary. We introduce a new class of backward stochastic differential equations, which allows us to produce a probabilistic representation of certain quasilinear stochastic partial differential equations, thus extending the Feynman-Kac formula for linear SPDE's.

Mathematics Subject Classification: $60 \mathrm{H} 10,60 \mathrm{H} 15,60 \mathrm{H} 30$

## Introduction

A new kind of backward stochastic differential equations (in short BSDE), where the solution is a pair of processes adapted to the past of the driving Brownian motion, has been introduced by the authors in [6]. It was then shown in a series of papers by the second and both authors (see [8, 7, 9, 10]), that this kind of backward SDEs gives a probabilistic representation for the solution of a large class of systems of quasi-linear parabolic PDEs, which generalizes the classical Feynman-Kac formula for linear parabolic PDEs.

On the other hand, the classical Feynman-Kac formula has been generalized by the first author in $[4,5]$ to provide a probabilistic representation for solutions of linear parabolic stochastic partial differential equations; see also Krylov and Rozovskii [1], Rozovskii [11] and Ocone and Pardoux [3] for further extensions. The aim of this paper is to combine the two above types of results, and relate a new class of backward stochastic differential equations, which we call "doubly stochastic" for reasons which will become clear below, to a class of systems of quasilinear parabolic SPDEs. Hence we shall give a probabilistic representation of solutions of such systems of quasilinear SPDEs, and use it to prove an existence and uniqueness result of such SPDEs.

[^0]Let us be more specific. Let $\left\{W_{t}, t \geqq 0\right\}$ and $\left\{B_{t}, t \geqq 0\right\}$ be two mutually independent standard Brownian motions, with values respectively in $\mathbb{R}^{d}$ and $\mathbb{R}^{l}$. For each $(t, x) \in \mathbb{R}_{+} \times \mathbb{R}^{d}$, let $\left\{X_{s}^{t, x} ; t \leqq s \leqq T\right\}$ be the solution of the SDE:

$$
X_{s}^{t, x}=x+\int_{t}^{s} b\left(X_{r}^{t, x}\right) d r+\int_{i}^{s} \sigma\left(X_{r}^{t, x}\right) d W_{r}, \quad t \leqq s \leqq T
$$

We next want to find a pair of processes $\left\{\left(Y_{s}^{t, x}, Z_{s}^{t, x}\right) ; t \leqq s \leqq T\right\}$ with values in $\mathbb{R}^{k} \times \mathbb{R}^{k \times l}$ such that for each $s \in[t, T]\left(Y_{s}^{t, x}, Z_{s}^{t, x}\right)$ is $\sigma\left(\bar{W}_{r} ; t \leqq r \leqq s\right) \vee \sigma\left(B_{r}\right.$ $-B_{s} ; s \leqq r \leqq T$ ) measurable and

$$
\begin{aligned}
Y_{s}^{t, x}= & h\left(X_{T}^{t, x}\right)+\int_{s}^{T} f\left(X_{r}^{t, x}, Y_{r}^{t, x}, Z_{r}^{t, x}\right) d r \\
& +\int_{s}^{T} g\left(X_{r}^{t, x}, Y_{r}^{t, x}, Z_{r}^{t, x}\right) d B_{r}-\int_{s}^{T} Z_{r}^{t, x} d W_{r}, \quad t \leqq s \leqq T
\end{aligned}
$$

where the $d W$ integral is a forward Itô integral and the $d B$ integral is a backward Itô integral. We shall show that, under appropriate conditions on $f$ and $g$, the above "backward doubly stochastic differential equation" has a unique solution.

We finally will show that under rather strong smoothness conditions on $b, \sigma, f$ and $g,\left\{Y_{t}^{t, x} ;(t, x) \in[0, T] \times \mathbb{R}^{d}\right\}$ is the unique solution of the following system of backward stochastic partial differential equations:

$$
\begin{aligned}
u(t, x)= & h(x)+\int_{s}^{T}\left[\mathscr{L}_{s} u(s, x)+f(x, u(s, x),(\nabla u \sigma)(s, x))\right] d s \\
& +\int_{t}^{T} g(x, u(s, x),(\nabla u \sigma)(s, x)) d B_{s}, \quad 0 \leqq t \leqq T
\end{aligned}
$$

where $u$ takes values in $\mathbb{R}^{k}$,

$$
(\mathscr{L} u)_{i}(t, x)=\left(L u_{i}\right)(t, x), \quad 1 \leqq i \leqq k
$$

and

$$
L=\frac{1}{2} \sum_{i, j=1}^{d}\left(\sigma \sigma^{*}\right)_{i j} \frac{\partial^{2}}{\partial x_{i} \partial x_{j}}+\sum_{i=1}^{d} b_{i} \frac{\partial}{\partial x_{i}}
$$

The paper is organised as follows. In Sect. 1, we study existence and uniqueness of the solution to a backward doubly stochastic differential equation, and estimate the moments of the solution. In Sect. 2, we consider both a forward and a backward SDE, as introduced above, and study the regularity of the solution of the latter with respect to $x$, the initial condition of the former. Finally in Sect. 3 we relate our BSDE to a system of quasilinear stochastic partial differential equations.
Notation. The Euclidean norm of a vector $x \in \mathbb{R}^{k}$ will be denoted by $|x|$, and for a $d \times d$ matrix $A$, we define $\|A\|=\sqrt{\operatorname{Tr} A A^{*}}$.

## 1 Backward doubly stochastic differential equations

Let $(\Omega, \mathscr{F}, P)$ be a probability space, and $T>0$ be fixed throughout this paper. Let $\left\{W_{t}, 0 \leqq t \leqq T\right\}$ and $\left\{B_{t}, 0 \leqq t \leqq T\right\}$ be two mutually independent standard Brownian motion processes, with values respectively in $\mathbb{R}^{d}$ and in $\mathbb{R}^{l}$, defined on $(\Omega, \mathscr{F}, P)$. Let $\mathscr{N}$ denote the class of $P$-null sets of $\mathscr{F}$. For each $t \in[0, T]$, we define

$$
\mathscr{F}_{t} \triangleq \mathscr{F}_{t}^{W} \vee \mathscr{F}_{t, T}^{B}
$$

where for any process $\left\{\eta_{t}\right\}, \mathscr{F}_{s, t}^{\eta}=\sigma\left\{\eta_{r}-\eta_{s} ; s \leqq r \leqq t\right\} \vee \mathscr{N}, \mathscr{F}_{t}^{\eta}=\mathscr{F}_{0, t}^{\eta}$.
Note that the collection $\left\{\mathscr{F}_{t}, t \in[0, T]\right\}$ is neither increasing nor decreasing, and it does not constitute a filtration.

For any $n \in \mathbb{N}$, let $M^{2}\left(0, T ; \mathbb{R}^{n}\right)$ denote the set of (classes of $d P \times d t$ a.e. equal) $n$ dimensional jointly measurable random processes $\left\{\varphi_{t} ; t \in[0, T]\right\}$ which satisfy:
(i) $E \int_{0}^{T}\left|\varphi_{t}\right|^{2} d t<\infty$
(ii) $\varphi_{t}$ is $\mathscr{F}_{t}$ measurable, for a.e. $t \in[0, T]$.

We denote similarly by $S^{2}\left([0, T] ; \mathbb{R}^{n}\right)$ the set of continuous $n$ dimensional random processes which satisfy:
(i) $E\left(\sup _{0 \leq t \leq T}\left|\varphi_{t}\right|^{2}\right)<\infty$
(ii) $\varphi_{t}$ is $\mathscr{F}_{t}$ measurable, for any $t \in[0, T]$.

Let

$$
\begin{aligned}
& f: \Omega \times[0, T] \times \mathbb{R}^{k} \times \mathbb{R}^{k \times d} \rightarrow \mathbb{R}^{k} \\
& \mathrm{~g}: \Omega \times[0, T] \times \mathbb{R}^{k} \times \mathbb{R}^{k \times d} \rightarrow \mathbb{R}^{k \times l}
\end{aligned}
$$

be jointly measurable and such that for any $(y, z) \in \mathbb{R}^{k} \times \mathbb{R}^{k \times d}$,

$$
\begin{aligned}
& f(\cdot, y, z) \in M^{2}\left(0, T ; \mathbb{R}^{k}\right) \\
& g(\cdot, y, z) \in M^{2}\left(0, T ; \mathbb{R}^{k \times l}\right) .
\end{aligned}
$$

We assume moreover that there exist constants $c>0$ and $0<\alpha<1$ such that for any $(\omega, t) \in \Omega \times[0, T],\left(y_{1}, z_{1}\right),\left(y_{2}, z_{2}\right) \in \mathbb{R}^{k} \times \mathbb{R}^{k \times l}$,

$$
\begin{align*}
& \left|f\left(t, y_{1}, z_{1}\right)-f\left(t, y_{2}, z_{2}\right)\right|^{2} \leqq c\left(\left|y_{1}-y_{2}\right|^{2}+\left\|z_{1}-z_{2}\right\|^{2}\right)  \tag{H.1}\\
& \left\|g\left(t, y_{1}, z_{1}\right)-g\left(t, y_{2}, z_{2}\right)\right\|^{2} \leqq c\left|y_{1}-y_{2}\right|^{2}+\alpha\left\|z_{1}-z_{2}\right\|^{2}
\end{align*}
$$

Given $\xi \in L^{2}\left(\Omega, \mathscr{F}_{T}, P ; \mathbb{R}^{k}\right)$, we consider the following backward doubly stochastic differential equation:

$$
\begin{equation*}
Y_{t}=\xi+\int_{i}^{T} f\left(s, Y_{s}, Z_{s}\right) d s+\int_{i}^{T} g\left(s, Y_{s}, Z_{s}\right) d B_{s}-\int_{t}^{T} Z_{s} d W_{s}, \quad 0 \leqq t \leqq T \tag{1.1}
\end{equation*}
$$

We note that the integral with respect to $\left\{B_{i}\right\}$ is a "backward Itô integral" and the integral with respect to $\left\{W_{t}\right\}$ is a standard forward Itô integral. These
two types of integrals are particular cases of the Itô-Skorohod integral, see Nualart and Pardoux [2].

The main objective of this section is to prove the:
Theorem 1.1 Under the above conditions, in particular (H.1), Eq. (1.1) has unique solution

$$
(Y, Z) \in S^{2}\left([0, T] ; \mathbb{R}^{k}\right) \times M^{2}\left(0, T ; \mathbb{R}^{k \times d}\right)
$$

Before we start proving the theorem, let us establish the same result in case $f$ and $g$ do not depend on $Y$ and $Z$. Given $f \in M^{2}\left(0, T, \mathbb{R}^{k}\right)$ and $g \in M^{2}\left(0, T ; \mathbb{R}^{k \times l}\right)$ and $\xi$ as above, consider the SDE:

$$
\begin{equation*}
Y_{t}=\xi+\int_{t}^{T} f(s) d s+\int_{i}^{T} g(s) d B_{s}-\int_{t}^{T} Z_{s} d W_{s}, \quad 0 \leqq t \leqq T \tag{1.2}
\end{equation*}
$$

Proposition 1.2 There exists a unique pair

$$
(Y, Z) \in S^{2}\left([0, T] ; \mathbb{R}^{k}\right) \times M^{2}\left(0, T ; \mathbb{R}^{k \times d}\right)
$$

which solves Eq. (1.2).
Proof. Uniqueness is immediate, since if $(\bar{Y}, \bar{Z})$ is the difference of two solutions,

$$
\bar{Y}_{t}+\int_{t}^{T} \bar{Z}_{\mathrm{s}} d W_{\mathrm{s}}=0, \quad 0 \leqq t \leqq T
$$

Hence by orthogonality

$$
E\left(\left|\bar{Y}_{t}\right|^{2}\right)+E \int_{t}^{T} T_{r}\left[\bar{Z}_{s} \bar{Z}_{s}^{*}\right] d s=0
$$

and $\bar{Y}_{t} \equiv 0 P$ a.s., $\bar{Z}_{t}=0 d t d P$ a.e.
We now prove existence. We define the filtration $\left(\mathscr{C}_{t}\right)_{0 \leqq t \leq T}$ by

$$
\mathscr{G}_{t}=\mathscr{F}_{t}^{W} \vee \mathscr{F}_{T}^{B}
$$

and the $\mathscr{G}_{t}$-square integrable martingale

$$
M_{t}=E^{\mathscr{G}_{t}}\left[\xi+\int_{0}^{T} f(s) d s+\int_{0}^{T} g(s) d B_{s}\right], \quad 0 \leqq t \leqq T
$$

An obvious extension of Itô's martingale representation theorem yields the existence of $\mathscr{G}_{t}$-progressively measurable process $\left\{Z_{t}\right\}$ with values in $\mathbb{R}^{k \times d}$ such that

$$
\begin{gathered}
E \int_{0}^{T}\left|Z_{t}\right|^{2} d t<\infty \\
M_{t}=M_{0}+\int_{0}^{t} Z_{s} d W_{s}, \quad 0 \leqq t \leqq T
\end{gathered}
$$

Hence

$$
M_{T}=M_{t}+\int_{0}^{T} Z_{s} d W_{s}
$$

Replacing $M_{T}$ and $M_{t}$ by their defining formulas and subtracting $\int_{0}^{t} f(s) d s$ $+\int_{0} g(s) d B_{s}$ from both sides of the equality yields

$$
Y_{t}=\xi+\int_{t}^{T} f(s) d s+\int_{t}^{T} g(s) d B_{s}-\int_{t}^{T} Z_{s} d W_{s}
$$

where

$$
Y_{t} \triangleq E^{\mathscr{G}_{t}}\left(\xi+\int_{t}^{T} f(s) d s+\int_{t}^{T} g(s) d B_{s}\right)
$$

It remains to show that $\left\{Y_{t}\right\}$ and $\left\{Z_{t}\right\}$ are in fact $\mathscr{F}_{t}$-adapted. For $Y_{t}$, this is obvious since for each $t$,

$$
Y_{t}=E\left(\Theta / \mathscr{F}_{t} \vee \mathscr{F}_{t}^{B}\right)
$$

where $\Theta$ is $\mathscr{F}_{T}^{W} \vee \mathscr{F}_{t, T}^{B}$ measurable. Hence $\mathscr{F}_{t}^{B}$ is independent of $\mathscr{F}_{t} \vee \sigma(\Theta)$, and

$$
Y_{t}=E\left(\Theta / \mathscr{F}_{t}\right) .
$$

Now

$$
\int_{t}^{T} Z_{s} d W_{s}=\xi+\int_{t}^{T} f(s) d s+\int_{t}^{T} g(s) d B_{s}-Y_{t}
$$

and the right side is $\mathscr{F}_{T}^{W} \vee \mathscr{F}_{t, T}^{B}$ measurable.
Hence, from Itô's martingale representation theorem, $\left\{Z_{s}, t<s<T\right\}$ is $\mathscr{F}_{s}^{W} \vee \mathscr{F}_{t, T}^{B}$ adapted. Consequently $Z_{s}$ is $\mathscr{F}_{s}^{W} \vee \mathscr{F}_{t, T}^{B}$ measurable, for any $t<s$, so it is $\mathscr{\mathscr { F }}_{s}^{W} \vee \mathscr{F}_{s, T}^{B}$ measurable.

We shall need the following extension of the well-known Itô formula.
Lemma 1.3 Let $\quad \alpha \in S^{2}\left([0, T] ; \mathbb{R}^{k}\right), \quad \beta \in M^{2}\left(0, T ; \mathbb{R}^{k}\right), \quad \gamma \in M^{2}\left(0, T ; \mathbb{R}^{k \times i}\right)$, $\delta \in M^{2}\left(0, T ; \mathbb{R}^{k \times d}\right)$ be such that:

$$
\alpha_{t}=\alpha_{0}+\int_{0}^{t} \beta_{s} d s+\int_{0}^{t} \gamma_{s} d B_{s}+\int_{0}^{t} \delta_{s} d W_{s}, \quad 0 \leqq t \leqq T .
$$

Then

$$
\begin{aligned}
\left|\alpha_{t}\right|^{2}= & \left|\alpha_{0}\right|^{2}+2 \int_{0}^{t}\left(\alpha_{s}, \beta_{s}\right) d s+2 \int_{0}^{t}\left(\alpha_{s}, \gamma_{s} d B_{s}\right) \\
& +2 \int_{0}^{t}\left(\alpha_{s}, \delta_{s} d W_{s}\right)-\int_{0}^{t}\left\|\gamma_{s}\right\|^{2} d s+\int_{0}^{t}\left\|\delta_{s}\right\|^{2} d s \\
E\left|\alpha_{t}\right|^{2}= & E\left|\alpha_{0}\right|^{2}+2 E \int_{0}^{t}\left(\alpha_{s}, \beta_{s}\right) d s-E \int_{0}^{t}\left\|\gamma_{s}\right\|^{2} d s+E \int_{0}^{t}\left\|\delta_{s}\right\|^{2} d s .
\end{aligned}
$$

More generally, if $\phi \in C^{2}\left(\mathbb{R}^{k}\right)$,

$$
\begin{aligned}
\phi\left(\alpha_{t}\right)= & \phi\left(\alpha_{0}\right)+\int_{0}^{t}\left(\phi^{\prime}\left(\alpha_{s}\right), \beta_{s}\right) d s+\int_{0}^{t}\left(\phi^{\prime}\left(\alpha_{s}\right), \gamma_{s} d B_{s}\right)+\int_{0}^{t}\left(\phi^{\prime}\left(\alpha_{s}\right), \delta_{s} d W_{s}\right) \\
& -\frac{1}{2} \int_{0}^{t} \operatorname{Tr}\left[\phi^{\prime \prime}\left(\alpha_{s}\right) \gamma_{s} \gamma_{s}^{*}\right] d s+\frac{1}{2} \int_{0}^{t} \operatorname{Tr}\left[\phi^{\prime \prime}\left(\alpha_{s}\right) \delta_{s} \delta_{s}^{*}\right] d s
\end{aligned}
$$

Proof. The first identity is a combination of Itô's forward and backward formulae, applied to the process $\left\{a_{t}\right\}$, and the function $x \rightarrow|x|^{2}$. We only sketch the proof.

$$
\text { Let } 0=t_{0}<t_{1}<\ldots<t_{n}=t
$$

$$
\begin{aligned}
\left|\alpha_{t_{i+1}}\right|^{2}-\left|\alpha_{t_{i}}\right|^{2}= & 2\left(\alpha_{t_{i+1}}-\alpha_{t_{i}}, \alpha_{t_{i}}\right)+\left|\alpha_{t_{i+1}}-\alpha_{t_{i}}\right|^{2} \\
= & 2\left(\int_{t_{i}}^{t_{i+1}} \beta_{s} d s, \alpha_{t_{i}}\right)+2\left(\int_{t_{i}}^{t_{i+1}} \gamma_{s} d B_{s}, \alpha_{t_{i+1}}\right)+2\left(\int_{t_{i}}^{t_{i+1}} \delta_{s} d W_{s}, \alpha_{t_{i}}\right) \\
& -2\left(\int_{t_{i}}^{t_{i+1}} \gamma_{s} d B_{s}, \alpha_{t_{i+1}}-\alpha_{t_{i}}\right)+\left|\alpha_{t_{i+1}}-\alpha_{t_{i}}\right|^{2} \\
= & 2 \int_{t_{i}}^{t_{i+1}}\left(\alpha_{t_{i}}, \beta_{s}\right) d s+2 \int_{t_{i}}^{t_{i+1}}\left(\alpha_{t_{i+1}}, \gamma_{s} d B_{s}\right)+2 \int_{t_{i}}^{t_{i+1}}\left(\alpha_{t_{i}}, \delta_{s} d W_{s}\right) \\
& -\left|\int_{t_{i}}^{t_{i+1}} \gamma_{s} d B_{s}\right|^{2}+\left|\int_{t_{i}}^{t_{i+1}} \delta_{s} d W_{s}\right|^{2}+\rho_{i},
\end{aligned}
$$

where $\sum_{i=0}^{n-1} \rho_{i} \rightarrow 0$ in probability, as $\sup _{i} t_{i+1}-t_{i} \rightarrow 0$. The rest of the proof is standard. $\sum_{i=0}$

The second identity follows from the first, provided the stochastic integrals have zero expectation. This will follow from

$$
E\left(\sup _{0 \leqq t \leqq T}\left|\int_{t}^{T}\left(\alpha_{s}, \gamma_{s} d B_{s}\right)\right|+\sup _{0 \leqq t \leqq T}\left|\int_{0}^{t}\left(\alpha_{s}, \delta_{s} d W_{s}\right)\right|\right)<\infty
$$

which is a consequence of Burkholder-Davis-Gundy's inequality and the assumptions made on $\alpha, \gamma$ and $\delta$. Indeed, considering e.g. the forward integral, we have:

$$
\begin{aligned}
E\left(\sup _{0 \leqq t \leqq T}\left|\int_{0}^{t}\left(\alpha_{s}, \delta_{s} d W_{s}\right)\right|\right) & \leqq c E \sqrt{\int_{0}^{T}\left|\alpha_{t}\right|^{2}\left\|\delta_{t}\right\|^{2} d t} \\
& \leqq \frac{c}{2}\left(E\left(\sup _{0 \leqq t \leqq T}\left|\alpha_{t}\right|^{2}\right)+E \int_{0}^{T}\left\|\delta_{t}\right\|^{2} d t\right)
\end{aligned}
$$

The last identity is proved in a way very similar to the first one.
We can now turn to the

Proof of Theorem 1.1 Uniqueness. Let $\left\{\left(Y_{t}^{1}, Z_{t}^{1}\right)\right\}$ and $\left\{\left(Y_{t}^{2}, Z_{t}^{2}\right)\right\}$ be two solutions. Define

$$
\bar{Y}_{t}=Y_{t}^{1}-Y_{t}^{2}, \quad \bar{Z}_{t}=Z_{t}^{1}-Z_{t}^{2}, \quad 0 \leqq t \leqq T
$$

Then

$$
\begin{aligned}
\bar{Y}_{t}= & \int_{t}^{T}\left[f\left(s, Y_{s}^{1}, Z_{s}^{1}\right)-f\left(s, Y_{s}^{2}, Z_{s}^{2}\right)\right] d s+\int_{t}^{T}\left[g\left(s, Y_{s}^{1}, Z_{s}^{1}\right)-g\left(s, Y_{s}^{2}, Z_{s}^{2}\right)\right] d B_{s} \\
& -\int_{t}^{T} \bar{Z}_{s} d W_{s}
\end{aligned}
$$

Applying Lemma 1.3 to $\bar{Y}$ yields:

$$
\begin{aligned}
E\left(\left|\bar{Y}_{t}\right|^{2}\right)+E \int_{t}^{T}\left\|\bar{Z}_{s}\right\|^{2} d s= & 2 E \int_{t}^{T}\left(f\left(s, Y_{s}^{1}, Z_{s}\right)-f\left(s, Y_{s}^{2}, Z_{s}^{2}\right), \bar{Y}_{s}\right) d s \\
& +E \int_{t}^{T}\left\|g\left(s, Y_{s}^{1}, Z_{s}^{1}\right)-g\left(s, Y_{s}^{2}, Z_{s}^{2}\right)\right\|^{2} d s
\end{aligned}
$$

Hence from (H.1) and the inequality $a b \leqq \frac{1}{2(1-\alpha)} a^{2}+\frac{1-\alpha}{2} b^{2}$,

$$
E\left(\left|\bar{Y}_{t}\right|^{2}\right)+E \int_{t}^{T}\left\|\bar{Z}_{s}\right\|^{2} d s \leqq c(\alpha) E \int_{t}^{T}\left|\bar{Y}_{t}\right|^{2} d s+\frac{1-\alpha}{2} E \int_{t}^{T}\left\|\bar{Z}_{s}\right\|^{2} d s+\alpha E \int_{t}^{T}\left\|\bar{Z}_{s}\right\|^{2} d s
$$

where $0<\alpha<1$ is the constant appearing in (H.1). Consequently

$$
E\left(\left|\bar{Y}_{t}\right|^{2}\right)+\frac{1-\alpha}{2} E \int_{t}^{T}\left\|\bar{Z}_{s}\right\|^{2} d s \leqq c(\alpha) E \int_{t}^{T}\left\|\bar{Y}_{s}\right\|^{2} d s
$$

From Gronwall's lemma, $E\left(\left|\bar{Y}_{t}\right|^{2}\right)=0,0 \leqq t \leqq T$, and hence $E \int_{0}^{T}\left\|\bar{Z}_{t}\right\|^{2} d s=0$.
Existence. We define recursively a sequence $\left\{\left(Y_{t}^{i}, Z_{t}^{i}\right)\right\}_{i=0,1, \ldots}$ as follows. Let $Y_{t}^{0}$ $\equiv 0, Z_{t}^{0} \equiv 0$. Given $\left\{\left(Y_{t}^{i}, Z_{t}^{i}\right)\right\},\left\{\left(Y_{t}^{i+1}, Z_{t}^{i+1}\right)\right\}$ is the unique solution, constructed as in Proposition 1.2, of the following equation:

$$
Y_{t}^{i+1}=\xi+\int_{t}^{T} f\left(s, Y_{s}^{i}, Z_{s}^{i}\right) d s+\int_{t}^{T} g\left(s, Y_{s}^{i}, Z_{s}^{i}\right) d B_{s}-\int_{t}^{T} Z_{s}^{i+1} d W_{s}
$$

Let $\bar{Y}_{t}^{i+1} \triangleq Y_{t}^{i+1}-Y_{t}^{i}, \bar{Z}_{t}^{i+1} \triangleq Z_{t}^{i+1}-Z_{t}^{i}, 0 \leqq t \leqq T$. The same computations as in the proof of uniqueness yield:

$$
\begin{aligned}
E\left(\left|\bar{Y}_{t}^{i+1}\right|^{2}\right)+E \int_{t}^{T}\left\|\bar{Z}_{t}^{i+1}\right\|^{2} d s= & 2 E \int_{t}^{T}\left(f\left(s, Y_{s}^{i}, Z_{s}^{i}\right)-f\left(s, Y_{s}^{i-1}, Z_{s}^{i-1}\right), \bar{Y}_{s}^{i+1}\right) d s \\
& +E \int_{t}^{T}\left\|g\left(s, Y_{s}^{i}, Z_{s}^{i}\right)-g\left(s, Y_{s}^{i-1}, Z_{s}^{i-1}\right)\right\|^{2} d s
\end{aligned}
$$

Let $\beta \in \mathbb{R}$. By integration by parts, we deduce

$$
\begin{gathered}
E\left(\left|\bar{Y}_{t}^{i+1}\right|^{2}\right) e^{\beta \tau}+\beta E \int_{t}^{T}\left|\bar{Y}_{s}^{i+1}\right|^{2} e^{\beta s} d s+E \int_{t}^{T}\left\|\bar{Z}_{s}^{i+1}\right\|^{2} e^{\beta s} d s \\
=2 E \int_{t}^{T}\left(f\left(s, Y_{s}^{i}, Z_{s}^{i}\right)-f\left(s, Y_{s}^{i-1}, Z_{s}^{i-1}\right), \bar{Y}_{s}^{i+1}\right) e^{\beta s} d s \\
\quad+E \int_{t}^{T}\left\|g\left(s, Y_{s}^{i}, Z_{s}^{i}\right)-g\left(s, Y_{s}^{i-1}, Z_{s}^{i-1}\right)\right\|^{2} e^{\beta s} d s
\end{gathered}
$$

There exists $c, \gamma>0$ such that

$$
\begin{aligned}
& E\left(\left|\bar{Y}_{t}^{i+1}\right|^{2}\right) e^{\beta s}+(\beta-\gamma) E \int_{t}^{T}\left|\bar{Y}_{s}^{i+1}\right|^{2} e^{\beta s} d s+E \int_{t}^{T}\left\|\bar{Z}_{s}^{i+1}\right\|^{2} e^{\beta s} d s \\
& \quad \leqq E \int_{t}^{T}\left(c\left|\bar{Y}_{s}^{i}\right|^{2}+\frac{1+\alpha}{2}\left\|\bar{Z}_{s}^{i}\right\|^{2}\right) e^{\beta s} d s
\end{aligned}
$$

Now choose $\beta=\gamma+\frac{2 c}{1+\alpha}$, and define $\bar{c}=\frac{2 c}{1+\alpha}$.

$$
\begin{aligned}
E\left(\left|\bar{Y}_{t}^{i+1}\right|^{2}\right) e^{\beta t} & +E \int_{t}^{T}\left(\bar{c}\left|\bar{Y}_{s}^{i+1}\right|^{2}+\left\|\bar{Z}_{s}^{i+1}\right\|^{2}\right) e^{\beta s} d s \leqq \frac{1+\alpha}{2} E \int_{t}^{T}\left(c\left|\bar{Y}_{s}^{i}\right|^{2}\right. \\
& \left.+\left\|\bar{Z}_{s}^{i}\right\|^{2}\right) e^{\beta s} d s .
\end{aligned}
$$

It follows immediately that

$$
E \int_{t}^{T}\left(\bar{c}\left|\bar{Y}_{s}^{i+1}\right|^{2}+\left\|\bar{Z}_{s}^{i+1}\right\|^{2}\right) e^{\beta s} d s \leqq\left(\frac{1+\alpha}{2}\right)^{i} E \int_{t}^{T}\left(\bar{c}\left|Y_{s}^{1}\right|^{2}+\left\|Z_{s}^{1}\right\|^{2}\right) e^{\beta s} d s
$$

and, since $\frac{1+\alpha}{2}<1,\left\{\left(Y_{t}^{i}, Z_{t}^{i}\right)\right\}_{i=0,1,2, \ldots}$ is a Cauchy sequence in $M^{2}\left(0, T ; \mathbb{R}^{k}\right)$ $\times M^{2}\left(0, T ; \mathbb{R}^{k \times d}\right)$. It is then easy to conclude that $\left\{Y_{t}^{i}\right\}_{i=0,1,2, \ldots}$ is also Cauchy in $S^{2}\left([0, T] ; \mathbb{R}^{k}\right)$, and that

$$
\left\{\left(Y_{t}, Z_{t}\right)\right\}=\lim _{i \rightarrow \infty}\left\{\left(Y_{t}^{i}, Z_{t}^{i}\right)\right\}
$$

solves Eq. (1.1).
We next establish higher order moment estimates for the solution of Eq. (1.1). For that sake, we need an additional assumption on $g$.
(H.2) $\left\{\begin{array}{l}\text { There exists } c \text { such that for all }(t, y, z) \in[0, T] \times \mathbb{R}^{k} \times \mathbb{R}^{k \times d}, g g^{*}(t, y, z) \\ \leqq z z^{*}+c\left(\|g(t, 0,0)\|^{2}+|y|^{2}\right) I .\end{array}\right.$

Theorem 1.4 Assume, in addition to the conditions of Theorem 1.1, that (H.2) holds and for some $p>2, \xi \in L^{p}\left(\Omega, \mathscr{F}_{T}, P ; \mathbb{R}^{k}\right)$ and

$$
E \int_{0}^{T}\left(|f(t, 0,0)|^{p}+\|g(t, 0,0)\|^{p}\right) d t<\infty .
$$

Then

$$
E\left(\sup _{0 \leqq t \leqq T}\left|Y_{t}\right|^{p}+\left(\int_{0}^{T}\left\|Z_{t}\right\|^{2} d t\right)^{p / 2}\right)<\infty
$$

Proof. We apply Lemma 1.3 with $\varphi(x)=|x|^{p}$, yielding

$$
\begin{aligned}
&\left|Y_{t}\right|^{p}+\frac{p}{2} \int_{t}^{T}\left|Y_{s}\right|^{p-2}\left\|Z_{s}\right\|^{2} d s+\frac{p}{2}(p-2) \int_{t}^{T}\left|Y_{s}\right|^{p-4}\left(Z_{s} Z_{s}^{*} Y_{s}, Y_{s}\right) d s \\
&=|\xi|^{p}+\left.p \int_{t}^{T}\left|Y_{s}\right|\right|^{p-2}\left(f\left(s, Y_{s}, Z_{s}\right), Y_{s}\right) d s+p \int_{i}^{T}\left|Y_{s}\right|^{p-2}\left(Y_{s}, g\left(s, Y_{s}, Z_{s}\right) d B_{s}\right) \\
&+\frac{p}{2} \int_{t}^{T}\left|Y_{s}\right|^{p-2}\left\|g\left(s, Y_{s}, Z_{s}\right)\right\|^{2} d s \\
& \quad+\frac{p}{2}(p-2) \int_{t}^{T}\left|Y_{s}\right|^{p-4}\left(g g^{*}\left(s, Y_{s}, Z_{s}\right) Y_{s}, Y_{s}\right) d s-p \int_{t}^{T}\left|Y_{s}\right|^{p-2}\left(Y_{s}, Z_{s} d W_{s}\right) .
\end{aligned}
$$

Also we do not know a priori that the above stochastic integrals have zero expectation, arguing as in the proof of Lemma 2.1 in Pardoux and Peng [7], we obtain that

$$
\begin{aligned}
& E\left(\left|Y_{t}\right|^{p}\right)+\frac{p}{2} E \int_{t}^{T}\left|Y_{s}\right|^{p-2}\left\|Z_{s}\right\|^{2} d s+\frac{p}{2}(p-2) E \int_{t}^{T}\left|Y_{s}\right|^{p-4}\left(Z_{s} Z_{s}^{*} Y_{s}, Y_{s}\right) d s \\
& \quad \leqq E\left(|\xi|^{p}\right)+p E \int_{t}^{T}\left|Y_{s}\right|^{p-2}\left(f\left(s, Y_{s}, Z_{s}\right), Y_{s}\right) d s+\frac{p}{2} E \int_{t}^{T}\left|Y_{s}\right|^{p-2}\left\|g\left(s, Y_{s}, Z_{s}\right)\right\|^{2} d s \\
& \quad+\frac{p}{2}(p-2) E \int_{t}^{T}\left|Y_{s}\right|^{p-4}\left(g g^{*}\left(s, Y_{s}, Z_{s}\right) Y_{s}, Y_{s}\right) d s
\end{aligned}
$$

Note that we can conclude from (H.1) that for any $\alpha<\alpha^{\prime}<1$, there exists $c\left(\alpha^{\prime}\right)$ such that

$$
\|g(t, y, z)\|^{2} \leqq c\left(\alpha^{\prime}\right)\left(|y|^{2}+\|g(t, 0,0)\|^{2}\right)+\alpha^{\prime}\|z\|^{2}
$$

From the last two inequalities, (H.1) and (H.2), and using Hölder's and Young's inequalities, we deduce that there exists $\theta>0$ and $c$ such that for $0 \leqq t \leqq T$,

$$
\begin{aligned}
& E\left(\left|Y_{t}\right|^{p}\right)+\theta E \int_{t}^{T}\left|Y_{s}\right|^{p-2}\left\|Z_{s}\right\|^{2} d s \\
& \left.\quad \leqq E\left(|\xi|^{p}\right)+c E \int_{t}^{T}\left(\left|Y_{t}\right|^{p}\right)+|f(s, 0,0)|^{p}+\|g(s, 0,0)\|^{p}\right) d s .
\end{aligned}
$$

It then follows, using Gronwall's lemma, that

$$
\sup _{0 \leqq t \leqq T} E\left(\left|Y_{t}\right|^{p}\right)+E \int_{0}^{T}\left|Y_{t}\right|^{p-2}\left\|Z_{t}\right\|^{2} d t<\infty .
$$

Applying the same inequalities we have already used to the first identity of this proof, we deduce that

$$
\begin{aligned}
\left|Y_{t}\right|^{p} \leqq & \left.|\xi|^{p}+c \int_{t}^{T}\left(\left|Y_{s}\right|^{p}\right)+|f(s, 0,0)|^{p}+\|g(s, 0,0)\|^{p}\right) d s \\
& +p \int_{t}^{T}\left|Y_{s}\right|^{p-2}\left(Y_{s}, g\left(s, Y_{s}, Z_{s}\right) d B_{s}\right)-p \int_{t}^{T}\left|Y_{s}\right|^{p-2}\left(Y_{s}, Z_{s} d W_{s}\right) .
\end{aligned}
$$

Hence, from Burkholder-Davis-Gundy's inequality,

$$
\begin{aligned}
E\left(\sup _{0 \leqq t \leqq T}\left|Y_{t}\right|^{p}\right) \leqq & E\left(|\xi|^{p}\right)+c E \int_{0}^{T}\left(\left|Y_{t}\right|^{p}+|f(t, 0,0)|^{p}+\|g(t, 0,0)\|^{p}\right) d t \\
& +c E \sqrt{\int_{0}^{T}\left|Y_{t}\right|^{2 p-4}\left(g g^{*}\left(t, Y_{t}, Z_{t}\right) Y_{t}, Y_{t}\right) d t} \\
& +c E \sqrt{\int_{0}^{T}\left|Y_{t}\right|^{2 p-4}\left(Z_{t} Z_{t}^{*} Y_{t}, Y_{t}\right) d t}
\end{aligned}
$$

We estimate the last term as follows:

$$
\begin{aligned}
E \sqrt{\int_{0}^{T}\left|Y_{t}\right|^{2 p-4}\left(Z_{t} Z_{t}^{*} Y_{t}, Y_{t}\right) d t} & \leqq E\left(Y_{t}^{p / 2} \sqrt{\int_{0}^{T}\left|Y_{t}\right|^{p-2}\left\|Z_{t}\right\|^{2} d t}\right) \\
& \leqq \frac{1}{3} E\left(\sup _{0 \leqq t \leqq T}\left|Y_{t}\right|^{p}\right)+\frac{1}{4} E \int_{0}^{T}\left|Y_{t}\right|^{p-2}\left\|Z_{t}\right\|^{2} d t
\end{aligned}
$$

The next to last term of the above inequality can be treated analogously, and we deduce that

$$
E\left(\sup _{0 \leqq t \leqq T}\left|Y_{t}\right|^{p}\right)<\infty .
$$

Now we have

$$
\begin{aligned}
\int_{0}^{T}\left\|Z_{t}\right\|^{2} d t= & |\xi|^{2}-\left|Y_{0}\right|^{2}+2 \int_{0}^{T}\left(f\left(t, Y_{t}, Z_{t}\right), Y_{t}\right) d t+2 \int_{0}^{T}\left(Y_{t}, g\left(t, Y_{t}, Z_{t}\right) d B_{t}\right) \\
& +\int_{0}^{T}\left\|g\left(t, Y_{t}, Z_{t}\right)\right\|^{2} d t-2 \int_{0}^{T}\left(Y_{t}, Z_{t} d W_{t}\right)
\end{aligned}
$$

Hence for any $\delta>0$,

$$
\begin{aligned}
& \left(\int_{0}^{T}\left\|Z_{t}\right\|^{2} d t\right)^{p / 2} \leqq(1+\delta)\left(\int_{0}^{T}\left\|g\left(t, Y_{t}, Z_{t}\right)\right\|^{2} d t\right)^{p / 2} \\
& +c(\delta, p)\left[|\xi|^{p}+\left|Y_{0}\right|^{p}+\left|\int_{0}^{T}\left(f\left(t, Y_{t}, Z_{t}\right), Y_{t}\right) d t\right|^{p / 2}\right. \\
& \left.+\left|\int_{0}^{T}\left(Y_{t}, g\left(t, Y_{t}, Z_{t}\right) d B_{t}\right)\right|^{p / 2}+\left|\int_{0}^{T}\left(Y_{t}, Z_{t} d W_{t}\right)\right|^{p / 2}\right] \\
& E\left[\left(\int_{0}^{T}\left\|Z_{t}\right\|^{2} d t\right)^{p / 2}\right] \\
& \leqq(1+\delta)^{2} \alpha E\left[\left(\int_{0}^{T}\left\|Z_{t}\right\|^{2} d t\right)^{p / 2}\right]+c^{\prime}(\delta, p) \\
& +c(\delta, p) E\left[\left(\int_{0}^{T}\left|Y_{t}\right|\left\|Z_{t}\right\| d t\right)^{p / 2}\right]+c(\delta, p) E\left[\left(\int_{0}^{T}\left|Y_{t}\right|^{2}\left\|Z_{t}\right\|^{2} d t\right)^{p / 4}\right] \\
& \leqq(1+\delta)^{2} \alpha E\left[\left(\int_{0}^{T}\left\|Z_{t}\right\|^{2} d t\right)^{p / 2}\right]+c^{\prime}(\delta, p) \\
& +c(\delta, p) E\left\{\left(\sup _{0 \leqq t \leqq T}\left|Y_{t}\right|^{p / 2}\right)\left[\left(\int_{0}^{T}\left\|Z_{t}\right\| d t\right)^{p / 2}+\left(\int_{0}^{T}\left\|Z_{t}\right\|^{2} d t\right)^{p / 4}\right]\right\} \\
& \leqq\left[(1+\delta)^{2} \alpha+(1+\delta)\right] E\left[\left(\int_{0}^{T}\left\|Z_{t}\right\|^{2} d t\right)^{p / 2}\right]+c^{\prime \prime}(\delta, p) \text {. }
\end{aligned}
$$

The second part of the result now follows, if we choose $\delta>0$ small enough such that

$$
(1+\delta)^{2} \alpha+(1+\delta)<1
$$

(recall that $\alpha<1$ ).

## 2 Regularity of the solution of the BDSDE

Let us first repeat some notations from Pardoux and Peng [7].
$C^{k}\left(\mathbb{R}^{p} ; \mathbb{R}^{q}\right), C_{l, b}^{k}\left(\mathbb{R}^{p} ; \mathbb{R}^{q}\right), C_{p}^{k}\left(\mathbb{R}^{p} ; \mathbb{R}^{q}\right)$ will denote respectively the set of functions of class $C^{k}$ from $\mathbb{R}^{p}$ into $\mathbb{R}^{q}$, the set of those functions of class $C^{k}$ whose partial derivatives of order less than or equal to $k$ are bounded (and hence the function itself grows at most linearly at infinity), and the set of those functions of class $C^{k}$ which, together with all their partial derivatives of order less than or equal to $k$, grow at most like a polynomial function of the variable $x$ at infinity.

We are given $b \in C_{l, b}^{3}\left(\mathbb{R}^{d}, \mathbb{R}^{d}\right)$ and $\sigma \in C_{l, b}^{3}\left(\mathbb{R}^{d}, \mathbb{R}^{d \times d}\right)$, and for each $t \in[0, T)$, $x \in \mathbb{R}^{d}$, we denote by $\left\{X_{s}^{t, x}, t \leqq s \leqq T\right\}$ the unique strong solution of the following SDE:

$$
\begin{align*}
d X_{s}^{t, x} & =b\left(X_{s}^{t, x}\right) d s+\sigma\left(X_{s}^{t, x}\right) d W_{s}, \quad t \leqq s \leqq T  \tag{2.1}\\
X_{s}^{t, x} & =x
\end{align*}
$$

It is well known that the random field $\left\{X_{s}^{t, x} ; 0 \leqq t \leqq s \leqq T, x \in \mathbb{R}^{d}\right\}$ has a version which is a.s. of class $C^{2}$ in $x$, the function and its derivatives being a.s. continuous with respect to $(t, s, x)$.

Moreover, for each ( $t, x$ ),

$$
\sup _{t \leqq s \leqq T}\left(\left|X_{s}^{t, x}\right|+\left|\nabla X_{s}^{t, x}\right|+\left|D^{2} X_{s}^{t, x}\right|\right) \in \bigcap_{p \geqq 1} L^{p}(\Omega)
$$

where $\nabla X_{s}^{t, x}$ denotes the matrix of first order derivatives of $X_{s}^{t, x}$ with respect to $x$ and $D^{2} X_{s}^{t, x}$ the tensor of second order derivatives.

Now the coefficients of the BDSDE will be of the form (with an obvious abuse of notations):

$$
\begin{aligned}
& f(s, y, z)=f\left(s, X_{s}^{t, x}, y, z\right) \\
& g(s, y, z)=g\left(s, X_{s}^{t, x}, y, z\right)
\end{aligned}
$$

where

$$
\begin{aligned}
& f:[0, T] \times \mathbb{R}^{d} \times \mathbb{R}^{k} \times \mathbb{R}^{k \times d} \rightarrow \mathbb{R}^{k} \\
& g:[0, T] \times \mathbb{R}^{d} \times \mathbb{R}^{k} \times \mathbb{R}^{k \times d} \rightarrow \mathbb{R}^{k \times i}
\end{aligned}
$$

We assume that for any $s \in[0, T],(x, y, z) \rightarrow(f(s, x, y, z), g(s, x, y, z))$ is of class $C^{3}$, and all derivatives are bounded on $[0, T] \times \mathbb{R}^{d} \times \mathbb{R}^{k} \times \mathbb{R}^{k \times d}$.

We assume again that (H.1) and (H.2) hold, together with
(H.3)

$$
\begin{equation*}
g_{z}^{\prime}(t, x, y, z) \theta \theta^{*} g_{z}^{\prime}(t, x, y, z)^{*} \leqq \theta \theta^{*}, \quad \forall t \in[0, T], x \in \mathbb{R}^{d}, y \in \mathbb{R}^{k}, z, \theta \in \mathbb{R}^{k \times d} \tag{H.3}
\end{equation*}
$$

Let $h \in C_{p}^{\ni}\left(\mathbb{R}^{d} ; \mathbb{R}^{h}\right)$. For any $t \in[0, T], x \in \mathbb{R}^{d}$, let $\left\{\left(Y_{s}^{t, x}, Z_{s}^{t, x}\right) ; t \leqq s \leqq T\right\}$ denote the unique solution of the BDSDE:

$$
\begin{align*}
Y_{s}^{t, x}= & h\left(X_{T}^{t, x}\right)+\int_{s}^{T} f\left(r, X_{r}^{t, x}, Y_{r}^{t, x}, Z_{r}^{t, x}\right) d r  \tag{2.2}\\
& +\int_{s}^{T} g\left(r, X_{r}^{t, x}, Y_{r}^{t, x}, Z_{r}^{t, x}\right) d B_{r}-\int_{s}^{T} Z_{r}^{t, x} d W_{r}, \quad t \leqq s \leqq T
\end{align*}
$$

We shall define $X_{s}^{t, x}, Y_{s}^{t, x}$ and $Z_{s}^{t, x}$ for all $(s, t) \in[0, T]^{2}$ by letting $X_{s}^{t, x}=X_{s \vee t}^{t, x}$, $Y_{s}^{t, x}=Y_{s \vee t}^{t, x}$, and $Z_{s}^{t, x}=0$ for $s<t$.
Theorem $2.1\left\{Y_{s}^{t, x} ;(s, t) \in[0, T]^{2}, x \in \mathbb{R}^{d}\right\}$ has a version whose trajectories belong to $C^{0,0,2}\left([0, T]^{2} \times \mathbb{R}^{d}\right)$.
Before proceeding to the proof of this theorem, let us state an immediate corollary:

Corollary 2.2 There exists a continuous version of the random field $\left\{Y_{t}^{t, x} ; t \in[0, T], x \in \mathbb{R}^{d}\right\}$ such that for any $t \in[0, T], x \rightarrow Y_{t}^{t, x}$, is of class $C^{2}$ a.s., the derivatives being a.s. continuous in $(t, x)$.
Proof of Theorem 2.1 We first note that we can deduce from Theorem 1.4 applied to the present situation that, for each $p \geqq 2$, there exist $c_{p}$ and $q$ such that

$$
E\left(\sup _{t \leqq s \leqq T}\left|Y_{s}^{t, x}\right|^{p}+\left(\int_{t}^{T}\left\|Z_{s}^{t, x}\right\|^{2} d s\right)^{p / 2}\right) \leqq c_{p}\left(1+|x|^{q}\right) .
$$

Next for $t \vee t^{\prime} \leqq s \leqq T$,

$$
\begin{aligned}
Y_{s}^{t, x}-Y_{s}^{t^{\prime}, x^{\prime}}= & {\left[\int_{0}^{1} h^{\prime}\left(X_{T}^{t^{\prime}, x^{\prime}}+\lambda\left(X_{T}^{t, x}-X_{T}^{t^{\prime}, x^{\prime}}\right)\right) d \lambda\right]\left(X_{T}^{t, x}-X_{T}^{t^{\prime}, x^{\prime}}\right) } \\
& +\int_{s}^{T}\left(\varphi_{r}\left(t, x ; t^{\prime}, x^{\prime}\right)\left[X_{r}^{t, x}-X_{r}^{t^{\prime}, x^{\prime}}\right]+\psi_{r}\left(t, x ; t^{\prime}, x^{\prime}\right)\left[Y_{r}^{t, x}-Y_{r}^{t^{\prime}, x^{\prime}}\right]\right. \\
& +\chi_{r}\left(t, x ; t^{\left.\left.t^{\prime}, x^{\prime}\right)\left[Z_{r}^{t, x}-Z_{r}^{t^{\prime}, x^{\prime}}\right]\right) d r+\int_{s}^{T}\left(\bar{\varphi}_{r}\left(t, x ; t^{\prime}, x^{\prime}\right)\left[X_{r}^{t, x}-X_{r}^{t^{\prime}, x^{\prime}}\right]\right.}\right. \\
& \left.+\bar{\psi}_{r}\left(t, x ; t^{\prime}, x^{\prime}\right)\left[Y_{r}^{t, x}-Y_{r}^{t^{\prime}, x^{\prime}}\right]+\bar{\chi}_{r}\left(t, x ; t^{\prime}, x^{\prime}\right)\left[Z_{r}^{t, x}-Z_{r}^{t^{\prime}, x^{\prime}}\right]\right) d B_{r} \\
& -\int_{s}^{T}\left(Z_{r}^{t, x}-Z_{r}^{t^{\prime}, x^{\prime}}\right) d W_{r}
\end{aligned}
$$

where

$$
\begin{aligned}
& \varphi_{r}\left(t, x ; t^{\prime}, x^{\prime}\right)=\int_{0}^{1} f_{x}^{\prime}\left(\sum_{r, \lambda}^{t, x ; t^{\prime}, x^{\prime}}\right) d \lambda \\
& \psi_{r}\left(t, x ; t^{\prime}, x^{\prime}\right)=\int_{0}^{1} f_{y}^{\prime}\left(\sum_{r, \lambda}^{t, x ; t^{\prime}, x^{\prime}}\right) d \lambda \\
& \chi_{r}\left(t, x ; t^{\prime}, x^{\prime}\right)=\int_{0}^{1} f_{z}^{\prime}\left(\sum_{r, \lambda^{t}, x, x^{\prime}}\right) d \lambda
\end{aligned}
$$

$\bar{\varphi}_{r}, \bar{\psi}_{r}$ and $\bar{\chi}_{r}$ are defined analogously, with $f$ replaced by $g$, and

$$
\Sigma_{r, \lambda}^{t, x ; t^{\prime}, x^{\prime}}=\left(r, X_{r}^{t^{\prime}, x^{\prime}}+\lambda\left(X_{r}^{t, x}-X_{r}^{t^{\prime}, x^{\prime}}\right), Y_{r}^{t^{\prime}, x^{\prime}}+\lambda\left(Y_{r}^{t, x}-Y_{r}^{t^{\prime}, x^{\prime}}\right), Z_{r}^{t^{\prime}, x^{\prime}}+\lambda\left(Z_{r}^{t, x}-Z_{r}^{t^{\prime}, x^{\prime}}\right)\right) .
$$

Combining the argument of Theorem 1.4 with the estimate:

$$
E\left(\sup _{0 \leqq s \leqq T}\left|X_{s}^{t, x}-X_{s}^{t^{\prime}, x^{\prime}}\right|^{p}\right) \leqq c_{p}\left(1+|x|^{p}+\left|x^{\prime}\right|^{p}\right)\left(\left|x-x^{\prime}\right|^{p}+\left|t-t^{\prime}\right|^{p / 2}\right),
$$

we deduce that for all $p \geqq 2$, there exists $c_{p}$ and $q$ such that

$$
\begin{gathered}
E\left(\sup _{0 \leqq s \leqq T}\left|Y_{s}^{t, x}-Y_{s}^{t^{\prime}, x^{\prime}}\right|^{p}+\left(\int_{t}^{T}\left\|Z_{s}^{t, x}-Z_{s}^{t^{\prime}, x^{\prime}}\right\|^{2} d s\right)^{p / 2}\right) \\
\leqq c_{p}\left(1+|x|^{q}+\left|x^{\prime}\right|^{q}\right)\left(\left|x-x^{\prime}\right|^{p}+\left|t-t^{\prime}\right|^{p / 2}\right)
\end{gathered}
$$

Note that (H.3) is used in the proof; it plays the same role as (H.2) in the proof of Theorem 1.4. Note also that (H.1) implies that $\left\|\bar{\chi}_{r}\right\| \leqq \alpha<1$. We conclude from the last estimate, using Kolmogorov's lemma, that $\left\{Y_{s}^{t, x} ; s, t \in[0, T], x \in \mathbb{R}^{d}\right\}$ has an a.s. continuous version.

Next we define

$$
\Delta_{h}^{i} X_{s}^{t, x} \triangleq\left(X_{s}^{t, x+k_{o_{i}}}-X_{s}^{t, x}\right) / h,
$$

where $h \in \mathbb{R} \backslash\{0\},\left\{e_{1}, \ldots, e_{d}\right\}$ is an orthonormal basis of $\mathbb{R}^{d}$. $\Delta_{h}^{i} Y_{s}^{t, x}$ and $\Delta_{h}^{i} Z_{s}^{t, x}$ are defined analogously. We have

$$
\begin{aligned}
\Delta_{h}^{i} Y_{s}^{t, x}= & \int_{0}^{t} h^{\prime}\left(X_{T}^{t, x}+\lambda h \Delta_{h}^{i} X_{T}^{t, x}\right) \Delta_{h}^{i} X_{r}^{t, x} d \lambda \\
& +\int_{s}^{T} \int_{0}^{1}\left[f_{x}^{\prime}\left(\Xi_{r, \lambda}^{t, x, h}\right) \Delta_{h}^{i} X_{r}^{t, x}+f_{y}^{\prime}\left(\Xi_{r, 2}^{t, x, h}\right) \Delta_{h}^{i} Y_{r}^{t, x}+f_{z}^{\prime}\left(\Xi_{r, \lambda}^{t, x, h}\right) \Delta_{h}^{i} Z_{r}^{t, x}\right] d \lambda d r \\
& +\int_{s}^{T} \int_{0}^{1}\left[g_{x}^{\prime}\left(\Xi_{r, \lambda}^{t, x, h}\right) A_{h}^{i} X_{r}^{t, x} g_{y}^{\prime}\left(\Xi_{r, \lambda}^{t, x, h}\right) \Delta_{h}^{i} Y_{r}^{t, x}+g_{z}^{\prime}\left(\Xi_{r, \lambda}^{t, x, h}\right) \Delta_{h}^{i} Z_{r}^{t, x}\right] d \lambda d B_{r} \\
& -\int_{s}^{T} \Delta_{h}^{i} Z_{r}^{t, x} d W_{r},
\end{aligned}
$$

where $\Xi_{r, \lambda}^{t, x, h}=\left(r, X_{r}^{t, x}+\lambda h \Delta_{h}^{i} X_{r}^{t, x}, Y_{r}^{t, x}+\lambda h \Delta_{h}^{i} Y_{r}^{t, x}, Z_{r}^{t, x}+\lambda h \Delta_{h}^{i} Z_{r}^{t, x}\right)$.
We note that for each $p \geqq 2$, there exists $c_{p}$ such that

$$
E\left(\sup _{0 \leqq s \leqq T}\left|\Delta_{h}^{i} X_{s}^{t, x}\right|^{p}\right) \leqq c_{p} .
$$

The same estimates as above yields

$$
E\left(\sup _{t \leqq s \leqq T}\left|A_{h}^{i} Y_{s}^{t, x}\right|^{p}+\left(\int_{t}^{T}\left\|\Delta_{h}^{i} Z_{s}^{t, x}\right\|^{2} d s\right)^{p / 2}\right) \leqq c_{p}\left(1+|x|^{q}+|h|^{q}\right) .
$$

Finally, we consider

$$
\begin{aligned}
\Delta_{h}^{i} Y_{s}^{t, x}-\Delta_{h^{\prime}}^{i} Y_{s}^{t^{\prime}, x^{\prime}}= & \int_{0}^{1} h^{\prime}\left(X_{T}^{t, x}+\lambda h \Delta_{h}^{i} X_{T}^{t, x}\right) \Delta_{h}^{i} X_{T}^{t, x} d \lambda \\
& -\int_{0}^{1} h^{\prime}\left(X_{T}^{t^{\prime}, x^{\prime}}+\lambda h^{\prime} \Delta_{h}^{i} X_{T}^{t^{\prime}, x^{\prime}}\right) \Delta_{h^{\prime}}^{i} X_{T}^{t^{\prime}, x^{\prime}} d \lambda \\
& +\int_{s}^{T} \int_{0}^{1}\left[f_{x}^{\prime}\left(\Xi_{r, \lambda}^{t, x, h}\right) \Delta_{h}^{i} X_{r}^{t, x}-f_{x}^{\prime}\left(\Xi_{r, \lambda}^{t^{\prime}, x^{\prime}, h^{\prime}}\right) \Delta_{h^{\prime}}^{i}, X_{r}^{t^{\prime}, x^{\prime}}\right] d \lambda d r \\
& +\int_{s}^{T} \int_{0}^{1}\left[f_{y}^{\prime}\left(\Xi_{r, \lambda}^{t, x, h}\right) \Delta_{h}^{i} Y_{r}^{t, x}-f_{y}^{\prime}\left(\Xi_{r, \lambda}^{t^{\prime}, x^{\prime}, h^{\prime}}\right) \Delta_{h^{\prime}}^{i} Y_{r}^{t^{\prime}, x^{\prime}}\right] d \lambda d r \\
& +\int_{s}^{T} \int_{0}^{1}\left[f_{z}^{\prime}\left(\Xi_{r, \lambda}^{t, x, h}\right) \Delta_{h}^{i} Z_{r}^{t, x}-f_{z}^{\prime}\left(\Xi_{r, \lambda}^{t^{\prime}, x^{\prime}, h^{\prime}}\right) \Delta_{h^{\prime}}^{i}, Z_{r}^{t^{\prime}, x^{\prime}}\right] d \lambda d r \\
& \left.\int_{s}^{T} \int_{0}^{1}\left[g_{x}^{\prime}(t, x, \lambda), h_{h}\right) \Delta_{h}^{i} X_{r}^{t, x}-g_{x}^{\prime}\left(\Xi_{r, \lambda}^{t^{\prime},,^{\prime}, h^{\prime}}\right) \Delta_{h^{\prime}}^{i} X_{r}^{t^{\prime}, x^{\prime}}\right] d \lambda d B_{r} \\
& +\int_{s}^{T} \int_{0}^{1}\left[g_{y}^{\prime}\left(\Xi_{r, \lambda}^{t, x, h}\right) \Delta_{h}^{i} Y_{r}^{t, x}-g_{y}^{\prime}\left(\Xi_{r, \lambda}^{t^{\prime}, x^{\prime}, h^{\prime}}\right) \Delta_{h^{\prime}}^{i}, Y_{r}^{t^{\prime}, x^{\prime}}\right] d \lambda d B_{r} \\
& +\int_{s}^{T} \int_{0}^{1}\left[g_{x}^{\prime}\left(\Xi_{r, \lambda}^{t, x, h}\right) \Delta_{h}^{i} Z_{r}^{t, x}-g_{z}^{\prime}\left(\Xi_{r, \lambda}^{t_{r}^{\prime}, x^{\prime}, h^{\prime}}\right) \Delta_{h^{\prime}}^{i}, Z_{r}^{t^{\prime}, x^{\prime}}\right] d \lambda d B_{r} \\
& -\int_{s}^{T}\left[\Delta_{h}^{i} Z_{r}^{t, x}-\Delta_{h^{\prime}}^{i} Z_{r}^{t_{r}^{\prime}, x^{\prime}}\right] d W_{r} .
\end{aligned}
$$

We note that

$$
E\left(\sup _{0 \leqq s \leqq T}\left|\Delta_{h}^{i} X_{s}^{t, x}-\Delta_{h^{\prime}}^{i} X_{s}^{t^{\prime}, x^{\prime}}\right|^{p}\right) \leqq c_{p}\left(1+|x|^{p}\right)\left(\left|x-x^{\prime}\right|^{p}+\left|h-h^{\prime}\right|^{p}+\left|t-t^{\prime}\right|^{p / 2}\right)
$$

and

$$
\begin{aligned}
\left|\Xi_{r, 2}^{t, x, h}-\Xi_{r, \lambda}^{t^{\prime}, x^{\prime}, h^{\prime}}\right| \leqq & \left(\left|X_{r}^{t, x}-X_{r}^{t^{\prime}, x^{\prime}}\right|+\left|X_{r}^{t, x+h_{e_{i}}}-X_{r}^{t^{\prime}, x^{\prime}+h_{e_{i}}^{\prime}}\right|\right. \\
& +\left|Y_{r}^{t, x}-Y_{r}^{t^{\prime}, x^{\prime}}\right|+\left|Y_{r}^{t, x+h_{e_{i}}}-Y_{r}^{t^{\prime}, x^{\prime}+h_{e_{i}}^{\prime}}\right| \\
& \left.+\left\|Z_{r}^{t, x}-Z_{r}^{t^{\prime}, x^{\prime}}\right\|+\left\|Z_{r}^{t, x+h_{e_{i}}}-Z_{r}^{t^{\prime}, x^{\prime}+h_{e_{i}}^{\prime}}\right\|\right) .
\end{aligned}
$$

Using similar arguments as those in Theorem 1.4, combined with those of Theorem 2.9 in Pardoux and Peng [7], we show that

$$
\begin{aligned}
& E\left(\sup _{0 \leqq s \leqq T}\left|\Delta_{h}^{i} Y_{s}^{t, x}-\Delta_{h^{\prime}}^{i} Y_{s}^{t^{\prime}, x^{\prime}}\right|^{p}+\left(\int_{A_{\wedge} t^{\prime}}^{T}\left\|\Delta_{h}^{i} Z_{s}^{t, x}-\Delta_{h^{\prime}}^{i}, Z_{s}^{t^{\prime}, x^{\prime}}\right\|^{2} d s\right)^{p / 2}\right) \\
& \quad \leqq c_{p}\left(1+|x|^{q}+\left|x^{\prime}\right|^{q}+|h|^{q}+\left|h^{\prime}\right|^{q}\right) \times\left(\left|x-x^{\prime}\right|^{p}+\left|h-h^{\prime}\right|^{p}+\left|t-t^{\prime}\right|^{p / 2}\right)
\end{aligned}
$$

The existence of a continuous derivative of $Y_{s}^{t, x}$ with respect to $x$ follows easily from the above estimate, as well as the existence of a mean-square derivative of $Z_{s}^{t, x}$ with respect to $x$, which is mean square continuous in ( $s, t, x$ ). The existence of a continuous second derivative of $Y_{s}^{t, x}$ with respect to $x$ is proved in a similar fashion.

It is easy to deduce, as in Pardoux and Peng [7], that $\left\{\left(\nabla Y_{s}^{t, x}\right.\right.$ $\left.\left.=\frac{\partial Y_{s}^{t, x}}{\partial x}, \nabla Z_{s}^{t, x}=\frac{\partial Z_{s}^{t, x}}{\partial x}\right)\right\}$ is the unique solution of the BDSDE:

$$
\begin{aligned}
\nabla Y_{s}^{t, x}= & h^{\prime}\left(X_{T}^{t, x}\right) \nabla X_{T}^{t, x}+\int_{s}^{T}\left[f_{x}^{\prime}\left(r, X_{r}^{t, x}, Y_{r}^{t, x}, Z_{r}^{t, x}\right) \nabla X_{r}^{t, x}\right. \\
& \left.+f_{y}^{\prime}\left(r, X_{r}^{t, x}, Y_{r}^{t, x}, Z_{r}^{t, x}\right) \nabla Y_{r}^{t, x}+f_{z}^{\prime}\left(r, X_{r}^{t, x}, Y_{r}^{t, x}, Z_{r}^{t, x}\right) \nabla Z_{r}^{t, x}\right] d r \\
& +\int_{s}^{T}\left[g_{x}^{\prime}\left(r, X_{r}^{t, x}, Y_{r}^{t, x}, Z_{r}^{t, x}\right) \nabla X_{r}^{t, x}+g_{y}^{\prime}\left(r, X_{r}^{t, x}, Y_{r}^{t, x}, Z_{r}^{t, x}\right) \nabla Y_{r}^{t, x}\right. \\
& \left.+g_{z}^{\prime}\left(r, X_{r}^{t, x}, Y_{r}^{t, x}, Z_{r}^{t, x}\right) \nabla Z_{r}^{t, x}\right] d B_{r}-\int_{s}^{T} \nabla Z_{r}^{t, x} d W_{r}
\end{aligned}
$$

We shall need below a formula relating $Z$ with the gradients of $Y$ and $X$ :
Proposition 2.3 The random field $\left\{Z_{s}^{t, x} ; 0 \leqq t \leqq s \leqq T, x \in \mathbb{R}^{d}\right\}$ has an a.s. continuous version which is given by:

$$
Z_{s}^{t, x}=\nabla Y_{s}^{t, x}\left(\nabla X_{s}^{t, x}\right)^{-1} \sigma\left(X_{s}^{t, x}\right)
$$

and in particular

$$
Z_{t}^{t, x}=\nabla Y_{t}^{t, x} \sigma(x) .
$$

Proof. We only indicate the main ideas, the details being obvious adaptations of those leading to Lemma 2.5 in Pardoux and Peng [7].

For any random variable $F$ of the form $F=f\left(W\left(h_{1}\right), \ldots, W\left(h_{n}\right) ; B\left(k_{1}\right), \ldots, B\left(k_{p}\right)\right)$ with $f \in C_{b}^{\infty}\left(\mathbb{R}^{n+p}\right), h_{1}, \ldots, h_{n} \in L^{2}\left([0, T], \mathbb{R}^{d}\right), k_{1}, \ldots, k_{p} \in L^{2}\left([0, T], \mathbb{R}^{l}\right)$, where

$$
W\left(h_{i}\right) \triangleq \int_{0}^{T}\left(h_{i}(t), d W_{i}\right), \quad B\left(k_{j}\right) \triangleq \int_{0}^{T}\left(k_{j}(t), d B_{t}\right)
$$

we let

$$
D_{t} F \triangleq \sum_{i=1}^{n} f_{i}^{\prime}\left(W\left(h_{1}\right), \ldots, W\left(h_{n}\right) ; B\left(k_{1}\right), \ldots, B\left(k_{p}\right)\right) h_{i}(t), \quad 0 \leqq t \leqq T
$$

For such an $F$, we define its 1, 2-norm as:

$$
\|F\|_{1,2}=\left(E\left[F^{2}+\int_{0}^{T}\left|D_{t} F\right|^{2} d t\right]\right)^{1 / 2}
$$

S denoting the set of random variables of the above form, we define the Sobolev space:

$$
\mathbb{D}^{1,2} \triangleq \overline{\mathbf{S}}^{\|\cdot\|_{1,2}}
$$

The "derivation operator" $D$. extends as an operator from $\mathbb{D}^{1,2}$ into $L^{2}\left(\Omega ; L^{2}\left([0, T], \mathbb{R}^{d}\right)\right)$. It turns out that under the assumptions of Theorem 2.1, the components of $X_{s}^{t, x}, Y_{s}^{t, x}$ and $Z_{s}^{t, x}$ take values in $\mathbb{D}^{1,2}$, and the pair $\left\{\left(D_{\theta} Y_{s}^{t, x}\right.\right.$, $\left.D_{\theta} Z_{s}^{t, x} ; t \leqq \theta \leqq s \leqq T\right\}$ satisfies for each fixed $\theta$ the same equation as $\left\{\left(\nabla Y_{s}^{t, x}, \nabla Z_{s}^{t, x}\right)\right\}$, but where $\nabla X_{s}^{t, x}$ has been replaced by $D_{\theta} X_{s}^{t, x}$. Now since for $t \leqq \theta<s$,

$$
D_{\theta} X_{s}^{t, x}=\nabla X_{s}^{t, x}\left(\nabla X_{\theta}^{t, x}\right)^{-1} \sigma\left(X_{\theta}^{t, x}\right)
$$

and moreover the mapping

$$
D_{\theta} X^{t, x} \rightarrow\left(D_{\theta} Y^{t, x}, D_{\theta} Z^{t, x}\right)
$$

is the same linear mapping as

$$
\nabla X^{t, x} \rightarrow\left(\nabla Y_{\cdot}^{t, x}, \nabla Z^{t \cdot x}\right)
$$

it follows that

$$
D_{\theta} Y_{s}^{t, x}=\nabla Y_{s}^{t, x}\left(\nabla X_{\theta}^{t, x}\right)^{-1} \sigma\left(X_{\theta}^{t, x}\right)
$$

Now $D_{\theta} Y_{s}^{t, x}=0$ for $\theta>s$, and

$$
\begin{aligned}
D_{\theta} Y_{\theta}^{t, x} & \triangleq \lim _{s \downarrow \mid \theta} D_{\theta} Y_{s}^{t, x} \\
& =Z_{\theta}^{t, x}, \theta \text { a.e. }
\end{aligned}
$$

This gives the first part of the proposition. The second part follows.

## 3 BDSDEs and systems of quasilinear SPDEs

We now relate our BDSDE to the following system of quasilinear backward stochastic partial differential equations:

$$
\begin{align*}
u(t, x)= & h(x)+\int_{t}^{T}[\mathscr{L} u(s, x)+f(s, x, u(s, x),(\nabla u \sigma)(s, x))] d s  \tag{3.1}\\
& +\int_{t}^{T} g(s, x, u(s, x),(\nabla u \sigma)(s, x)) d B_{s}, \quad 0 \leqq t \leqq T
\end{align*}
$$

where $u: \mathbb{R}_{+} \times \mathbb{R}^{d} \rightarrow \mathbb{R}^{k}$,

$$
\mathscr{L} u=\left(\begin{array}{c}
L u_{1} \\
\vdots \\
L u_{k}
\end{array}\right)
$$

with $L=\frac{1}{2} \sum_{i, j=1}^{d}\left(\sigma \sigma^{*}\right)_{i j}(t, x) \frac{\partial^{2}}{\partial x_{i} \partial x_{j}}+\sum_{i=1}^{d} b_{i}(t, x) \frac{\partial}{\partial x_{i}}$.
Theorem 3.1 Let $f$ and $g$ satisfy the assumptions of Sect. 1 and $h$ be of class $C^{2}$. Let $\left\{u(t, x) ; 0 \leqq t \leqq T, x \in \mathbb{R}^{d}\right\}$ be a random field such that $u(t, x)$ is $\mathscr{F}_{t, T^{-}}^{B}$-measurable for each $(t, x), u \in C^{0,2}\left([0, T] \times \mathbb{R}^{d} ; \mathbb{R}^{k}\right)$ a.s., and $u$ satisfies Eq. (3.1).

Then $u(t, x)=Y_{t}^{t, x}$, where $\left\{\left(Y_{s}^{t, x}, Z_{s}^{t, x}\right) ; t \leqq s \leqq T\right\}_{t \geqq 0, x \in \mathbb{R}^{d}}$ is the unique solution of the BDSDE (2.2).
Proof. It suffices to show that $\left\{\left(u\left(t, X_{s}^{t, x}\right),(\nabla u \sigma)\left(s, X_{s}^{t, x}\right) ; 0 \leqq s \leqq t\right\}\right.$ solves the BDSDE (2.2).

Let $t=t_{0}<t_{1}<t_{2}<\ldots<t_{n}=T$

$$
\begin{aligned}
\sum_{i=0}^{n-1} & {\left[u\left(t_{i}, X_{t_{i}}^{t, x}\right)-u\left(t_{i+1}, X_{t_{i+1}}^{t, x}\right)\right] } \\
= & \sum_{i}\left[u\left(t_{i}, X_{t_{i}}^{t, x}\right)-u\left(t_{i}, X_{t_{i+1}}^{t, x}\right)\right]+\sum_{i}\left[u\left(t_{i}, X_{t_{i+1}}^{t, x}\right)-u\left(t_{i+1}, X_{t_{i+1}}^{t, x}\right)\right] \\
= & -\int_{t_{i}}^{t_{i+1}} \mathscr{L} u\left(t_{i}, X_{s}^{t, x}\right) d s-\int_{t_{i}}^{t_{i+1}}(\nabla u \sigma)\left(t_{i}, X_{\mathrm{s}}^{t, x}\right) d W_{\mathrm{s}} \\
& +\int_{t_{i}}^{t_{i+1}}\left[\mathscr{L}\left(u\left(s, X_{t_{i+1}}^{t, x}\right)\right)+f\left(s, X_{t_{i+1}}^{t, x}, u\left(s, X_{t_{i+1}}^{t, x}\right),(\nabla u \sigma)\left(s, X_{t_{i+1}}^{t, x}\right)\right)\right] d s \\
& +\int_{t_{i}}^{t_{i+1}} g\left(s, X_{i_{i+1}}^{i, x}, u\left(s, X_{t_{i+1}}^{t, x}\right),(\nabla u \sigma)\left(s, X_{t_{i+1}}^{t, x}\right)\right) d B_{s},
\end{aligned}
$$

where we have used the Itô formula and the equation satisfied by $u$. It finally suffices to let the mesh size go to zero in order to conclude.
We have also a converse to Theorem 3.1:

Theorem 3.2 Let $f, g$ and $h$ satisfy the assumptions of Sects. 1 and 2. Then $\left\{u(t, x) \triangleq Y_{t}^{t, x} ; 0 \leqq t \leqq T, x \in \mathbb{R}^{d}\right\}$ is the unique classical solution of the system of backward SPDEs (3.1).

Proof. We prove that $\left\{Y_{t}^{t, x}\right\}$ is a solution. Uniqueness will then follow from Theorem 3.2. We first note that $Y_{t+h}^{t, x}=Y_{t+h}^{t+h, X_{t}^{t} x_{h}}$. Hence

$$
\begin{aligned}
u(t+h, x)-u(t, x)= & u(t+h, x)-u\left(t+h, X_{t+h}^{t, x}\right)+u\left(t+h, X_{t+h}^{t, x}\right)-u(t, x) \\
= & -\int_{t}^{t+h} \mathscr{L} u\left(t+h, X_{s}^{t, x}\right) d s-\int_{t}^{t+h}(\nabla u \sigma)\left(t+h, X_{s}^{t, x}\right) d W_{s} \\
& -\int_{t}^{t+h} f\left(s, X_{s}^{t, x}, Y_{s}^{t, x}, Z_{s}^{t, x}\right) d s-\int_{t}^{t+h} g\left(s, X_{s}^{t, x}, Y_{s}^{t, x}, Z_{s}^{t, x}\right) d B_{s} \\
& +\int_{t}^{t+h} Z_{s}^{t, x} d W_{s}
\end{aligned}
$$

We can then finish the proof exactly as in Theorem 3.2 of Pardoux and Peng [7].
Remark 3.3 Condition (H.1), with $\alpha<1$, is a very natural condition for (3.1) to be well posed. Indeed, in the case where $g$ is linear with respect to its last argument, and does not depend on $y, g$ is of the form:

$$
g(s, x, z)=c(s, x) z
$$

i.e. the stochastic integral term in (3.1) reads:

$$
\int_{t}^{T} c(s, x)(\nabla u \sigma)(s, x) d B_{s} .
$$

Condition (H.1) for $g$, in this case, reduces to $|c(s, x)| \leqq \alpha<1$. This is a well known condition (see e.g. Pardoux [5]) for the SPDE (3.1) to be a well-posed stochastic parabolic equation.
Remark 3.4 Our result generalizes the stochastic Feynman-Kac formula of Pardoux [4] for linear SPDEs. Indeed, if $k=1, f$ and $g$ are linear in $y$ and do not depend on $z$, the BDSDE becomes

$$
Y_{s}^{t, x}=h\left(X_{T}^{t, x}\right)+\int_{s}^{T} a\left(r, X_{r}^{t, x}\right) Y_{r}^{t, x} d r+\int_{s}^{T} b\left(r, X_{r}^{t, x}\right) Y_{r}^{t, x} d B_{r}-\int_{s}^{T} Z_{r}^{t, x} d W_{r}
$$

and it has an explicit solution given by:

$$
\begin{aligned}
Y_{s}^{t, x}= & \exp \left(\int_{s}^{T} a\left(r, X_{r}^{t, x}\right) d r+\int_{s}^{T} b\left(r, X_{r}^{t, x}\right) d B_{r}-\frac{1}{2} \int_{s}^{T}\left|b\left(r, X_{r}^{t, x}\right)\right|^{2} d r\right) h\left(X_{T}^{t, x}\right) \\
& -\int_{s}^{T} \exp \left(\int_{s}^{r} a\left(\theta, X_{\theta}^{t, x}\right) d \theta+\int_{s}^{r} b\left(\theta, X_{\theta}^{t, x}\right) d B_{\theta}-\frac{1}{2} \int_{s}^{r}\left|b^{2}\left(\theta, X_{\theta}^{t, x}\right)\right|^{2} d \theta\right) Z_{r}^{t, x} d W_{r}
\end{aligned}
$$

and because $Y_{t}^{t, x}$ is $\mathscr{F}_{t, T}^{B}$ measurable,

$$
\begin{aligned}
Y_{t}^{t, x}= & E\left[h ( X _ { T } ^ { t , x } ) \operatorname { e x p } \left(\int_{t}^{T} a\left(r, X_{r}^{t, x}\right) d r+\int_{i}^{T} b\left(r, X_{r}^{t, x}\right) d B_{r}\right.\right. \\
& \left.\left.-\frac{1}{2} \int_{t}^{T}\left|b\left(r, X_{r}^{t, x}\right)\right|^{2} d r\right) / \mathscr{F}_{t, T}^{B}\right]
\end{aligned}
$$

which is the formula in Pardoux [4] (where only the case $a \equiv 0$ is considered). Note however that in [4] $B$ and $W$ are allowed to be correlated. This does not seem possible here, unless we allow the stochastic integrals in the BDSDE to be of a non adapted nature.

## References

1. Krylov, N.V., Rozovskii, B.L.: Stochastic evolution equations. J. Sov. Math. 16, 1233-1277 (1981)
2. Nualart, D., Pardoux, E.: Stochastic calculus with anticipating integrands. Probab. Theory Relat. Fields 78, 535-581 (1988)
3. Ocone, D., Pardoux, E.: A stochastic Feynman-Kac formula for anticipating SPDEs, and application to nonlinear smoothing. Stochastics 45, 79-126 (1993)
4. Pardoux, E.: Un résultat sur les équations aux dérivés partielles stochastiques et filtrage des processus de diffusion. Note C.R. Acad. Sci., Paris Sér. A 287, 1065-1068 (1978)
5. Pardoux, E.: Stochastic PDEs, and filtering of diffusion processes. Stochastics 3, 127-167 (1979)
6. Pardoux, E., Peng, S.: Adapted solution of a backward stochastic differential equation. Syst. Control Lett. 14, 55-61 (1990)
7. Pardoux, E., Peng, S.: Backward stochastic differential equations and quasilinear parabolic partial differential equations. In: Rozuvskii, B.L., Sowers, R.B. (eds.) Stochastic partial differential equations and their applications. (Lect. Notes Control Inf. Sci., vol. 176, pp. 200-217) Berlin Heidelberg New York: Springer 1992
8. Peng, S.: Probabilistic interpretation for systems of quasilinear parabolic partial differential equations. Stochastics 37, 61-74 (1991)
9. Peng, S.: A generalized dynamic programming principle and Hamilton-Jacobi-Bellmann equation. Stochastics 38, 119-134 (1992)
10. Peng, S.: A non linear Feynman-Kac formula and applications. In: Chen, S.P., Yong, J.M. (eds.) Proc. of Symposium on system science and control theory, pp. 173-184. Singapore: World Scientific 1992
11. Rozovskii, B.: Stochastic evolution systems. Dordrecht: Reidel 1.991

[^0]:    * The research of this author was partially supported by DRET under contract 901636/A000/ DRET/DS/SR
    ** The research of this author was supported by a grant from the French "Ministère de la Recherche et de la Technologie", which is gratefully acknowledged

