

Bistable pulsating fronts for reaction-diffusion equations in a periodic habitat

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Abstract

This paper is concerned with the existence and qualitative properties of pulsating fronts for spatially periodic reaction-diffusion equations with bistable nonlinearities. We focus especially on the influence of the spatial period and, under various assumptions on the reaction terms and by using different types of arguments, we show several existence results when the spatial period is small or large. We also establish some properties of the set of periods for which there exist non-stationary fronts. Furthermore, we prove the existence of stationary fronts or non-stationary partial fronts at any period which is on the boundary of this set. Lastly, we characterize the sign of the front speeds and we show the global exponential stability of the non-stationary fronts for various classes of initial conditions. Our arguments are based on the maximum principle, spectral analysis and dynamical systems approach.

1 Introduction and main results

In this paper, we study the existence and qualitative properties of periodically propagating solutions of periodic reaction-diffusion equations of the type

$$u_t = (a_L(x)u_x)_x + f_L(x, u), \quad t \in \mathbb{R}, \quad x \in \mathbb{R} \quad (1.1)$$

with $L > 0$, where u_t stands for $u_t(t, x) = \partial_t u(t, x) = \partial u / \partial t(t, x)$, u_x stands for $u_x(t, x) = \partial_x u(t, x) = \partial u / \partial x(t, x)$ and $(a_L(x)u_x)_x$ stands for $(a_L(x)u_x)_x(t, x) = \partial_x(a_L u_x)(t, x) = \partial(a_L u_x) / \partial x(t, x)$. The diffusion and reaction coefficients a_L and f_L are given by

$$a_L(x) = a(x/L) \quad \text{and} \quad f_L(x, u) = f(x/L, u),$$

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where the function $a : \mathbb{R} \rightarrow \mathbb{R}$ is positive, of class $C^{1,\alpha}(\mathbb{R})$ (with $0 < \alpha < 1$) and 1-periodic, that is $a(x+1) = a(x)$ for all $x \in \mathbb{R}$. Throughout the paper, the function $f : \mathbb{R} \times [0, 1] \rightarrow \mathbb{R}$, $(x, u) \mapsto f(x, u)$ is continuous, 1-periodic in x , of class $C^{0,\alpha}$ in x uniformly in $u \in [0, 1]$, and of class $C^{1,1}$ in u uniformly in $x \in \mathbb{R}$ with $\partial_u f(\cdot, 0)$ and $\partial_u f(\cdot, 1)$ being continuous in \mathbb{R} . One assumes that, for every $x \in \mathbb{R}$, the profile $f(x, \cdot)$ is bistable in $[0, 1]$, that is, there is $\theta_x \in (0, 1)$ such that

$$f(x, 0) = f(x, 1) = f(x, \theta_x) = 0, \quad f(x, \cdot) < 0 \text{ on } (0, \theta_x), \quad f(x, \cdot) > 0 \text{ on } (\theta_x, 1). \quad (1.2)$$

One also assumes that 0 and 1 are uniformly (in x) stable zeroes of $f(x, \cdot)$, in the sense that there exist $\gamma > 0$ and $\delta \in (0, 1/2)$ such that

$$\begin{cases} f(x, u) \leq -\gamma u & \text{for all } (x, u) \in \mathbb{R} \times [0, \delta], \\ f(x, u) \geq \gamma(1 - u) & \text{for all } (x, u) \in \mathbb{R} \times [1 - \delta, 1]. \end{cases} \quad (1.3)$$

Notice that this implies in particular that $\delta < \theta_x < 1 - \delta$ and $\max(\partial_u f(x, 0), \partial_u f(x, 1)) \leq -\gamma$ for all $x \in \mathbb{R}$. Furthermore, from the periodicity and regularity of f , (1.3) is equivalent to $\max(\partial_u f(x, 0), \partial_u f(x, 1)) < 0$ for all $x \in \mathbb{R}$.

A particular case of such a function f satisfying (1.2) and (1.3) is the cubic nonlinearity

$$f(x, u) = u(1 - u)(u - \theta_x), \quad (1.4)$$

where $x \mapsto \theta_x$ is a 1-periodic $C^{0,\alpha}(\mathbb{R})$ function ranging in $(0, 1)$. Notice that in (1.4) or more generally in (1.2), the intermediate zero θ_x of $f(x, \cdot)$ is not assumed to be constant in general.

For mathematical purposes, the function f is extended in $\mathbb{R} \times (\mathbb{R} \setminus [0, 1])$ as follows: $f(x, u) = \partial_u f(x, 0)u$ for $(x, u) \in \mathbb{R} \times (-\infty, 0)$ and $f(x, u) = \partial_u f(x, 1)(u - 1)$ for $(x, u) \in \mathbb{R} \times (1, +\infty)$. Thus, f is continuous in $\mathbb{R} \times \mathbb{R}$, 1-periodic in x , $\min_{x \in \mathbb{R}} f(x, u) > 0$ for all $u < 0$ and $\max_{x \in \mathbb{R}} f(x, u) < 0$ for all $u > 1$, and $f(x, u)$, $\partial_u f(x, u)$ are globally Lipschitz-continuous in u uniformly in $x \in \mathbb{R}$.

Pulsating fronts

For each $L > 0$, the functions a_L and $f_L(\cdot, u)$ (for all $u \in [0, 1]$) are L -periodic (in x). One is especially interested in the paper in understanding the role of the spatial period L on the existence of solutions connecting the two stable steady states 0 and 1 and propagating with a constant average speed, the so-called pulsating, or periodic, fronts. Namely, a pulsating front connecting 0 and 1 for (1.1) is a solution $u : \mathbb{R} \times \mathbb{R} \rightarrow [0, 1]$ such that there exist a real number c_L (the average speed) and a function $\phi : \mathbb{R} \times \mathbb{R} \rightarrow [0, 1]$ such that

$$\begin{cases} u(t, x) = \phi(x - c_L t, x/L) \text{ for all } (t, x) \in \mathbb{R} \times \mathbb{R}, \\ \phi(\xi, y) \text{ is 1-periodic in } y, \\ \phi(-\infty, y) = 1, \quad \phi(+\infty, y) = 0 \text{ uniformly in } y \in \mathbb{R}. \end{cases} \quad (1.5)$$

If $c_L \neq 0$, then the map $(t, x) \mapsto (x - c_L t, x/L)$ is a bijection from $\mathbb{R} \times \mathbb{R}$ to $\mathbb{R} \times \mathbb{R}$ and ϕ is uniquely determined by u . Furthermore, in this case, for every $x \in \mathbb{R}$, the function $t \mapsto u(t, x + c_L t)$ is L/c_L -periodic (in time). The notion of pulsating front with nonzero speed was first given in [46]. On the other hand, a pulsating front with a speed $c_L = 0$ simply means a stationary solution $u(t, x) = \phi_0(x)$ of (1.1) such that $\phi_0 : \mathbb{R} \rightarrow [0, 1]$, $\phi_0(-\infty) = 1$ and $\phi_0(+\infty) = 0$. In this case, the function u can be written as in (1.5) where the function ϕ , which is then not uniquely determined, can be defined as $\phi(\xi, y) = \phi_0(\xi)$ for all $(\xi, y) \in \mathbb{R} \times \mathbb{R}$.

In this paper, we will show the uniqueness of the speed c_L of pulsating fronts for any $L > 0$, and we will then give some conditions which guarantee the existence of pulsating fronts with nonzero or

zero speed. In particular, we will focus on the dependence with respect to the spatial period L of the underlying medium and we will consider the limits as $L \rightarrow 0^+$ (the homogenization limit) and $L \rightarrow +\infty$ (slowly varying media). We will finally discuss the global and exponential stability of pulsating fronts with nonzero speed.

Some known existence results

Before going further on, let us mention a very important case where the existence of fronts is known, that is the case of a homogeneous medium in the sense that the function a is equal to a positive constant d and the function f does not depend on x . In this case, the function $f : [0, 1] \rightarrow \mathbb{R}$ is such that $f(0) = f(\theta) = f(1) = 0$ for some $\theta \in (0, 1)$, $f < 0$ on $(0, \theta)$, $f > 0$ on $(\theta, 1)$ and $f'(0) < 0$, $f'(1) < 0$. It is well known [4, 23] that for this homogeneous equation

$$u_t = d u_{xx} + f(u), \quad (1.6)$$

there exists a unique speed $c \in \mathbb{R}$ and a unique (up to shifts in x) front

$$u(t, x) = \phi(x - ct) \quad \text{such that } 0 < \phi < 1 \text{ in } \mathbb{R}, \quad \phi(-\infty) = 1 \text{ and } \phi(+\infty) = 0. \quad (1.7)$$

Such a front is decreasing in x and, for the equation (1.1) with an arbitrary $L > 0$, with $a_L = d$ and with $f_L(x, \cdot) = f$, it can also be viewed as a pulsating front with speed $c_L = c$. Furthermore, the speed c has the same sign as the integral $\int_0^1 f$ and the front is globally and exponentially stable [23] (we will come back later to the precise notions of stability, directly in the framework of the periodic equation (1.1)). In particular, if we fix $y \in \mathbb{R}$ and if in (1.1) we freeze the coefficients a_L and f_L around the position Ly , that is if we set $a^y(x) = a_L(Ly) = a(y)$ for all $x \in \mathbb{R}$ and $f^y(u) = f_L(Ly, u) = f(y, u)$ for all $u \in [0, 1]$, then the homogeneous equation $(u^y)_t = a^y(u^y)_{xx} + f^y(u^y)$ (with $(t, x) \in \mathbb{R} \times \mathbb{R}$) admits a unique front $u^y(t, x) = \phi^y(x - c^y t)$ and a unique speed $c^y \in \mathbb{R}$, with $0 < \phi^y < 1$ in \mathbb{R} , $\phi^y(-\infty) = 1$ and $\phi^y(+\infty) = 0$. Furthermore, the speed c^y has the sign of $\int_0^1 f^y(u) du = \int_0^1 f(y, u) du$.

When the coefficients a_L and f_L of (1.1) truly depend on x , the question of the existence of pulsating fronts is a long-time standing open and difficult problem and only few partial results are known in the literature. Actually, no explicit condition guaranteeing the existence or the non-existence has been known so far in general. Nevertheless, some particular cases have been dealt with and some more abstract conditions have been given. Firstly, for a given $L > 0$, the pulsating fronts are known to exist for (1.1) if $f = f(u)$ does not depend on x and if the coefficient a_L is close to a constant in some norms, see [22, 47, 50, 52, 53]. Secondly, when $f(x, u) = b(x)g(u)$ with $0 < b_1 \leq b \leq b_2 < +\infty$ in \mathbb{R} and $\int_0^1 \min_{[0,1]} f(\cdot, u) du > 0$, the existence of pulsating fronts with nonzero speed was established in [43]. Further results were obtained in [59] on the existence of pulsating fronts under the condition $\int_0^1 \min_{[0,1]} f(\cdot, u) du > 0$ (notice that both references [43, 59] were also concerned with generalized transition fronts in non-periodic media). Thirdly, if the equation (1.1) has no stable L -periodic steady state $0 < u(x) < 1$ (see Definition 3.5 below for the precise meaning), then it admits pulsating fronts [22]. Moreover, (1.1) admits pulsating fronts with a positive speed under the additional assumption that at least some compactly supported initial conditions give rise to solutions converging to 1 at $t \rightarrow +\infty$ locally uniformly in $x \in \mathbb{R}$, see [19]. However, pulsating fronts with nonzero speed c_L do not exist in general for some diffusions a_L (not too close to their average) and some x -independent reactions $f = f(u) = u(1-u)(u-\theta)$ with $\theta \simeq 1/2$, see [52, 54] and the comments following equation (1.8) below.

The bistability assumption (1.2), that is, the change of sign of $f(x, \cdot)$ in $(0, 1)$ and the fact that θ_x depends on x in general, makes the questions of the existence of possible intermediate L -periodic steady states of (1.1) and of the existence of pulsating fronts connecting 0 and 1 quite subtle. Many more existence results have actually been established for other types of nonlinearities f such as combustion,

monostable or specific Fisher-KPP nonlinearities: for instance, for 1-periodic (in x) combustion nonlinearities f for which $f \geq 0$ in $\mathbb{R} \times [0, 1]$, $f = 0$ in $\mathbb{R} \times ([0, \theta] \cup \{1\})$ for some $\theta \in (0, 1)$ and $f(x, \cdot)$ is nonincreasing in $[1 - \delta, 1]$ for some $\delta > 0$ independent of x , it is known that for every $L > 0$, there is a unique (up to shifts in t) pulsating front $u(t, x) = \phi(x - c_L t, x/L)$ connecting 0 and 1, with $c_L > 0$, see [8, 51]. This existence result holds whatever the size of a and f may be. On the other hand, when f is positive on $\mathbb{R} \times (0, 1)$, then for each $L > 0$, pulsating fronts $u(t, x) = \phi(x - ct, x/L)$ exist if and only if $c \geq c_L^*$, for some positive minimal speed c_L^* , see [8, 35, 38, 39, 48]. Furthermore, some variational formulas for c_L^* in the positive case and in the more specific KPP case have been derived in [10, 12, 20] and some further qualitative and uniqueness properties for each speed $c \in [c_L^*, +\infty)$ have been given in [25, 28, 29].

Uniqueness of the speed and further qualitative properties of pulsating fronts

In this paper, we first discuss the question of the uniqueness of the speed of pulsating fronts for the bistable equation (1.1), under assumptions (1.2) and (1.3), as well as the monotonicity and the uniqueness of pulsating fronts with nonzero speed. In [9], qualitative properties of transition fronts, which are more general than pulsating fronts, were investigated in unstructured heterogeneous media. Some results of [9] can be applied to the pulsating fronts of the periodic equation (1.1), provided that the propagation speeds are not zero. More precisely, [9, Theorems 1.11 and 1.14] (see also [49] for x -independent reactions $f = f(u)$) lead to the uniqueness of the speed and of the fronts (up to shifts in time) in the class of pulsating fronts with *nonzero speed*, as well as the negativity of $\partial_\xi \phi$ for a pulsating front $\phi(x - ct, x/L)$ with $c \neq 0$ and $\xi = x - ct$. In the present paper, we prove the uniqueness of the speed in a *more general class of pulsating fronts with zero or nonzero speed*. Furthermore, we show that if the speed is not equal to 0, then it has a well determined sign, as in the homogeneous case. To our knowledge, these fundamental properties are new for the x -dependent equation (1.1). Throughout the paper, we denote \bar{f} the arithmetic mean of the function f with respect to the variable x , that is,

$$\bar{f}(u) = \int_0^1 f(x, u) dx \quad \text{for } u \in [0, 1].$$

Theorem 1.1. *For any fixed $L > 0$, the speed of pulsating fronts for (1.1) is unique in the sense that if $u_L(t, x) = \phi_L(x - c_L t, x/L)$ and $\tilde{u}_L(t, x) = \tilde{\phi}_L(x - \tilde{c}_L t, x/L)$ are two pulsating fronts, then $\tilde{c}_L = c_L$. Furthermore, if $c_L \neq 0$, then it has the sign of $\int_0^1 \bar{f}(u) du$, the functions u_L and \tilde{u}_L are increasing in t if $c_L > 0$, resp. decreasing in t if $c_L < 0$, and the front is unique up to shifts in t , that is, there is $\tau \in \mathbb{R}$ such that $\tilde{u}_L(t, x) = u_L(t + \tau, x)$ for all $(t, x) \in \mathbb{R}^2$.*

When $c_L \neq 0$, given the uniqueness of the speed stated in the first part of Theorem 1.1, the monotonicity and uniqueness of u_L up to shifts in t can then be viewed as a consequence of [9]. Here, we will see that the uniqueness results (the uniqueness of the fronts as well as that of the speed) follow from the global stability of the pulsating fronts with nonzero speed (see Theorem 1.9 below and the last part of the proof of Theorem 1.1 in Section 2.2).

Theorem 1.1 also shows that the sign of the front speed, if not zero, is that of $\int_0^1 \bar{f}(u) du$ and therefore, it does not depend on L . But we point out that this property is only valid under the condition $c_L \neq 0$. In other words, one can not say that if $\int_0^1 \bar{f}(u) du \neq 0$ then $c_L \neq 0$. Consider for instance the equation

$$u_t = (d(x)u_x)_x + \mu^2 g(u), \quad t \in \mathbb{R}, \quad x \in \mathbb{R}, \quad (1.8)$$

where $d(x) = 1 + \delta \lambda \sin(2\pi x)$, $\mu \in \mathbb{R}$, $\delta \in \mathbb{R}$, $\lambda \in \mathbb{R}$, and $g(u) = u(1 - u)(u - 1/2 + \delta)$. Xin [52] proved that there are $\mu > 0$, $\delta \in (0, 1/2)$ and $\lambda \neq 0$ such that equation (1.8) admits a stationary front, that is, a pulsating front with speed $c = 0$, whereas $\int_0^1 g(u) du \neq 0$.

Existence of pulsating fronts for small $L > 0$

In this section and the following two ones, we present new results on the existence of pulsating fronts for the bistable equation (1.1). We first begin with the case of rapidly oscillating environments. For combustion-type and x -independent nonlinearities $f = f(u)$, Heinze proved in [30] that pulsating fronts for equation (1.1), which exist in this case for every $L > 0$, can be homogenized as $L \rightarrow 0^+$. He also showed in [31] that the homogenization process still holds for semilinear higher-dimensional reaction-diffusion equations of the type $u_t = \Delta u + f(u)$ with x -independent bistable nonlinearities $f = f(u)$ in periodically perforated domains (see the beginning of Section 3.1). By using variational principles for the speeds, the asymptotic expansions of the speeds for both models were established in [32]. In the case of periodic Fisher-KPP type of nonlinearity, the convergence of the minimal speeds c_L^* to the homogenization limit was proved in [21].

Inspired by the aforementioned homogenization results and the methods which were used, mostly in [31], we will show here that, under some assumptions guaranteeing their existence, pulsating fronts $u_L(t, x) = \phi_L(x - c_L t, x/L)$ of (1.1) converge as $L \rightarrow 0^+$, in a sense which will be made clear in Lemma 3.2, to the following limit:

$$a_H \phi_0'' + c_0 \phi_0' + \bar{f}(\phi_0) = 0 \text{ in } \mathbb{R}, \quad \phi_0(-\infty) = 1, \quad \phi_0(+\infty) = 0, \quad (1.9)$$

where $a_H > 0$ denotes the harmonic mean of the function a , defined by

$$a_H = \left(\int_0^1 a(x)^{-1} dx \right)^{-1}. \quad (1.10)$$

Theorem 1.2. *Assume that there is a unique (up to shifts) front ϕ_0 , with speed $c_0 \neq 0$, for the homogenized equation (1.9). Then there is $L_* > 0$ such that for any $0 < L < L_*$, equation (1.1) admits a unique (up to shifts in time) pulsating front $u_L(t, x) = \phi_L(x - c_L t, x/L)$, with speed $c_L \neq 0$, and $c_L \rightarrow c_0$ as $L \rightarrow 0^+$. Lastly, up to translation of ϕ_0 , there holds $\phi_L(\xi, y) - \phi_0(\xi) \rightarrow 0$ in $H^1(\mathbb{R} \times (0, 1))$ as $L \rightarrow 0^+$.*

This theorem does not only give the existence and uniqueness of pulsating fronts at small $L > 0$, but it also provides the convergence of the speeds c_L to c_0 as $L \rightarrow 0^+$. In particular, for small $L > 0$, the speeds c_L have the same sign as the speed c_0 of the homogenized equation (1.9), that is, the same sign as the integral $\int_0^1 \bar{f}(u) du$ (notice that this sign property could also be viewed as a consequence of Theorem 1.1).

Remark 1.3. By the assumptions (1.2) and (1.3), the function \bar{f} is a $C^1([0, 1])$ function such that $\bar{f}(0) = \bar{f}(1) = 0$, $\bar{f}'(0) < 0$ and $\bar{f}'(1) < 0$. In addition, if one assumes that there is a *unique* real number $\bar{\theta} \in (0, 1)$ such that $\bar{f}(\bar{\theta}) = 0$, then, as already mentioned, equation (1.9) admits a unique solution (ϕ_0, c_0) with $0 < \phi_0 < 1$ in \mathbb{R} , and c_0 has the sign of $\int_0^1 \bar{f}(u) du$. However, it is easy to see that there are examples of nonlinearities $f(x, u)$ which satisfy (1.2) and (1.3), but for which \bar{f} has more than one zero in $(0, 1)$. The possible multiple oscillations of \bar{f} on $(0, 1)$ do not exclude the existence of fronts for the homogenized equation (1.9), although the existence does not hold in general, see [23].

Recently, Fang and Zhao [22] considered the propagation property for the equation

$$u_t = (d(x) u_x)_x + f(u), \quad t \in \mathbb{R}, \quad x \in \mathbb{R}, \quad (1.11)$$

where $d(x)$ is a positive C^1 -continuous periodic function and $f(u) = u(1 - u)(u - \theta)$ with $\theta \in (0, 1)$. Under an abstract setting, they first established the existence of bistable traveling waves for monotone spatially periodic semiflows, and then applied the abstract results to the semiflow generated by the

solution operator associated with equation (1.11). By studying the stability of the intermediate (i.e., ranging in $(0, 1)$) periodic steady states, they proved the existence of pulsating fronts provided that $d(x)$ is sufficiently close to a positive constant in C^0 -norm. Actually, we will show in the present paper that some results of [22] can be used to prove the existence of pulsating fronts for (1.1) when L is small enough, under some assumptions on \bar{f} but for general diffusion coefficients a (we will consider later the case of large periods L). More precisely, we have the following result:

Theorem 1.4. *Assume that there is $\bar{\theta} \in (0, 1)$ such that*

$$\bar{f} < 0 \text{ on } (0, \bar{\theta}), \bar{f} > 0 \text{ on } (\bar{\theta}, 1), \text{ and } \bar{f}'(\bar{\theta}) > 0. \quad (1.12)$$

Then there is $\tilde{L}_ > 0$ such that for all $0 < L < \tilde{L}_*$, equation (1.1) admits a pulsating front $u_L(t, x) = \phi_L(x - c_L t, x/L)$ with speed c_L , and $c_L \rightarrow c_0$ as $L \rightarrow 0^+$, where c_0 is the unique speed for the homogenized equation (1.9). Furthermore, $c_L = c_0 = 0$ for all $0 < L < \tilde{L}_*$ if $c_0 = 0$.*

The results stated in Theorems 1.2 and 1.4 and the methods used to prove them are different. On the one hand, the proof of Theorem 1.2 relies on a perturbation argument and on the application of the implicit function theorem in some suitable Banach spaces. It provides the uniqueness (up to shifts in time) of the pulsating fronts $u_L(t, x) = \phi_L(x - c_L t, x/L)$ when L is small, as well as the uniqueness and the nonzero sign of the speeds c_L . The proof uses as an essential ingredient the fact that the front speed of the homogenized equation (1.9) is not zero. On the other hand, the main tool in the proof of Theorem 1.4 is to show that equation (1.1) does not admit any semistable L -periodic steady state ranging in $(0, 1)$, and this strategy may well give rise to pulsating fronts $u_L(t, x) = \phi_L(x - c_L t, x/L)$ with speed $c_L = 0$. Consider for instance the equation (1.8) again, which admits some stationary fronts for some parameters $d(x)$, $\mu > 0$, $g(u) = u(1 - u)(u - 1/2 + \delta)$ and $\delta \in (0, 1/2)$. For the equation (1.1) with $a_L(x) = d(x/L)$ and $f_L(x, u) = f(u) = \mu^2 g(u)$, Theorem 1.2 can be applied since $\bar{f}(u) = \mu^2 u(1 - u)(u - 1/2 + \delta)$ and the speed c_0 associated with (1.9) is positive (it has the sign of $\int_0^1 \bar{f}$). As a consequence, the period L_* given in Theorem 1.2 satisfies $L_* \leq 1$, since the interval $(0, L_*)$ is an interval of existence (and uniqueness) of pulsating fronts with *nonzero* speeds. Theorem 1.4 can also be applied in this case since \bar{f} satisfies (1.12) with $\bar{\theta} = 1/2 - \delta$. We believe that in this case, for every $L > 0$, equation (1.1) has no semistable L -periodic steady state ranging in $(0, 1)$. If that were true, then the method used in the proof of Theorem 1.4 would imply that the threshold \tilde{L}_* would actually be infinite (while $L_* \leq 1$). Generally speaking, though completely different, the methods used in Theorems 1.2 and 1.4 are both based on some compactness arguments, which make difficult to get some explicit a priori bounds on L_* and \tilde{L}_* and to compare them in general.

Finally, we point out that even if Theorem 1.2 can cover the case of functions \bar{f} with multiple oscillations on the interval $[0, 1]$, it does not hold if $\int_0^1 \bar{f}(u) du = 0$, while Theorem 1.4 does, under the additional assumption (1.12) (Theorem 1.2 provides an interval of existence and uniqueness of pulsating fronts with nonzero speeds, while the fronts given in Theorem 1.4 may be stationary in general). As an example, fix an x -independent function $f = f(u)$ satisfying (1.2) and (1.3) and fix a positive constant $d > 0$. It follows from [22] that there is $\eta > 0$ such that for every $L > 0$ and for every a satisfying the general assumptions of the present paper together with $\|a - d\|_{L^\infty(\mathbb{R})} \leq \eta$, equation (1.1) admits a pulsating front. From Theorem 1.1, this pulsating front has to be stationary since $\int_0^1 \bar{f}(u) du = \int_0^1 f(u) du = 0$. The existence of these stationary fronts cannot be covered by Theorem 1.2, but it can by Theorem 1.4, for small $L > 0$ (and actually, for all $L > 0$ since all L -periodic stationary states $0 < \bar{u}(x) < 1$ are unstable if $\|a - d\|_{L^\infty(\mathbb{R})} \leq \eta$, and the proof of Theorem 1.4 is based on this property).

Existence of pulsating fronts for large $L > 0$

The method used in the proof of Theorem 1.4 can also be applied to prove the existence of pulsating fronts of equation (1.1) with large $L > 0$.

Theorem 1.5. *Assume that*

$$\int_0^1 f(x, u) du > 0 \quad \text{and} \quad \frac{\partial f}{\partial u}(x, \theta_x) > 0 \quad \text{for all } x \in \mathbb{R}. \quad (1.13)$$

Then there is $L^ > 0$ such that for all $L > L^*$, equation (1.1) admits a pulsating front $u_L(t, x) = \phi_L(x - c_L t, x/L)$ with speed $c_L > 0$.*

Notice that, similarly, equation (1.1) admits a pulsating front with negative speed $c_L < 0$ for large L large if (1.13) is replaced by $\int_0^1 f(x, u) du < 0$ for all $x \in \mathbb{R}$. On the other hand, if $\min_{x \in \mathbb{R}} \int_0^1 f(x, u) du < 0 < \max_{x \in \mathbb{R}} \int_0^1 f(x, u) du$, then there is in general no pulsating front with nonzero speed for large L , but there are stationary fronts (see our paper [17]).

Theorem 1.5 shows the existence of pulsating fronts with speed $c_L > 0$ for large L . Actually, in the proof of Theorem 1.5, from some compactness arguments, we first prove the instability of all intermediate L -periodic steady states to get the existence of pulsating fronts with $c_L \geq 0$ for L large under the assumption (1.13) and we exclude the case $c_L = 0$ for large L by using again (1.13). We also point out that, as in Theorems 1.2 and 1.4, the existence of pulsating fronts stated in Theorem 1.5 does not require that the coefficients of (1.1) be close to their spatial average. Thus, one can say that Theorems 1.2, 1.4 and 1.5 are of a different spirit from the aforementioned existence results of [22, 50, 52].

Remark 1.6. From the proofs of Theorems 1.4 and 1.5 in Sections 3.2 and 3.3, one will see that the conditions (1.12) and (1.13) are only used to show the instability of the L -periodic steady states of equation (1.1), and this stability property is invariant by changing x into $-x$. Thus, these conditions do not only imply the existence of fronts $u(t, x) = \phi(x - c_L t, x/L)$ satisfying (1.5), but they also provide the existence of pulsating fronts of the type $\tilde{u}(t, x) = \tilde{\phi}(x + \tilde{c}_L t, x/L)$ for the same range of periods L , where $\tilde{\phi}$ is 1-periodic in its second variable and satisfies reversed limiting conditions:

$$\tilde{\phi}(-\infty, y) = 0 \quad \text{and} \quad \tilde{\phi}(+\infty, y) = 1, \quad \text{uniformly for } y \in \mathbb{R}.$$

Moreover, if both speeds c_L and \tilde{c}_L are nonzero, then they must have the same sign, which is that of $\int_0^1 \bar{f}(u) du$, as a consequence of Theorem 1.1. Furthermore, by uniqueness, $\tilde{c}_L = c_L$ if a and f are even in x . But whether $\tilde{c}_L = c_L$ for general coefficients a and f is not clear in general.¹

Remark 1.7. Let a and f satisfy the general assumptions of the paper, in particular, (1.2), (1.3) as well as the 1-periodicity in x , and consider now the equation

$$u_t = (a(x)u_x)_x + M f(x, u), \quad t \in \mathbb{R}, \quad x \in \mathbb{R}, \quad (1.14)$$

where the positive parameter M measures the amplitude of the reaction. A solution u of this 1-periodic equation is a pulsating front with speed σ if and only if the function $v(t, x) = u(t/M, x/\sqrt{M})$ is a pulsating front for the equation (1.1) with $L = \sqrt{M}$ and speed σ/\sqrt{M} . Therefore, under the assumption of Theorem 1.2, there is $M_* > 0$ such that for all $0 < M < M_*$, equation (1.14) admits a unique (up to shifts in time) pulsating front, with speed $\sigma_M \neq 0$, and $\sigma_M \sim \sqrt{M} c_0$ as $M \rightarrow 0^+$. Similarly, under the assumption (1.12) of Theorem 1.4, there is $\tilde{M}_* > 0$ such that for all $0 < M < \tilde{M}_*$, equation (1.14) admits a pulsating front with speed σ_M , and $\sigma_M \sim \sqrt{M} c_0$ as $M \rightarrow 0^+$ if the unique speed c_0 of the

¹We thank Dr. X. Liang for mentioning this question.

homogenized equation (1.9) is not zero, while $\sigma_M = 0$ for all $0 < M < \widetilde{M}_*$ if $c_0 = 0$. Lastly, under the assumption (1.13) of Theorem 1.5, there is $M^* > 0$ such that for all $M > M^*$, equation (1.14) admits a pulsating front with speed $\sigma_M > 0$. However, the study of the behavior of σ_M as $M \rightarrow +\infty$ is still open, as that of c_L as $L \rightarrow +\infty$ in Theorem 1.5 (see also the discussion after Theorem 1.8).

Set of periods L for which pulsating fronts with nonzero speed exist

After establishing some conditions for the existence of pulsating fronts for small or large periods, we derive some properties of the set of periods L for which (1.1) admits pulsating fronts with nonzero speeds. We had already emphasized the particular role played by the stationary fronts and we focus in this section on the fronts with nonzero speeds. We define

$$E = \left\{ L > 0 : (1.1) \text{ admits a pulsating front with speed } c_L \neq 0 \right\} \quad (1.15)$$

and we investigate the properties of E under the assumption $\int_0^1 \bar{f}(u) du \neq 0$. Indeed, if $\int_0^1 \bar{f}(u) du = 0$, then the sign property of the speed in Theorem 1.1 excludes the existence of pulsating fronts with nonzero speeds for any period L : in other words, E is empty in this case. It also follows from [17] that there is a constant C which only depends on a and f such that

$$|c_L| \leq C, \quad \forall L \in E, \quad (1.16)$$

that is, the front speeds are globally bounded independently of the period L . As we see in [17], the same property actually holds for the broader notion of global mean speeds of generalized transition fronts. In the present paper, we do not prove this global property (1.16) and we deal with local properties of the set E . In particular, it will follow from Theorem 1.8 below that the speeds c_L with $L \in E$ are locally bounded around any point $L_0 \in E$ and we will also prove in Lemma 4.6 below that the speeds c_L with $L \in E$ are locally bounded around any boundary point $L_0 \in \partial E \cap (0, +\infty)$. Motivated by the implicit function theorem used in the homogenization process in Theorem 1.2, we will first prove the following result.

Theorem 1.8. *The set E is open and for any $L_0 \in E$, one has $c_L \rightarrow c_{L_0}$ as $L \rightarrow L_0$ and $L \in E$.*

Under the assumptions of Theorems 1.4 and 1.5, that is, under conditions (1.12) and (1.13), it is natural to wonder whether $E = (0, +\infty)$, namely, whether there exist pulsating fronts with nonzero speed for all $L > 0$. As a matter of fact, the answer is *negative* in general, since quenching may occur even for some x -independent nonlinearities $f = f(u)$ (see again the example given with (1.8)), that is, stationary fronts connecting 0 and 1 may exist. Under the conditions of Theorems 1.2 and 1.5, the set E contains some neighborhoods of 0 and $+\infty$. When $E \neq (0, +\infty)$, is E of the type $E = (0, \underline{L}) \cup (\bar{L}, +\infty)$ for some $0 < \underline{L} \leq \bar{L} < +\infty$? We leave this question for further investigation.

In view of Theorem 1.1, the periods L for which (1.1) admits stationary fronts cannot belong to E , but they may appear at the boundary of E . Hence, it is of interest to investigate the question of the solutions of equation (1.1) when $L \in (0, +\infty)$ is a boundary point of E . In Section 4, we prove further results on the existence of partial fronts and semistable periodic states (in a sense to be defined) at points of $\partial E \cap (0, +\infty)$. The statements are a bit long and require additional stability notions, so we postpone them in Section 4.

As already emphasized, $E = (0, +\infty)$ for equation (1.1) under some additional assumptions on the coefficients a and f , see [22, 23, 50, 52, 53] and the comments after equation (1.11). When $E = (0, +\infty)$, it is interesting to investigate the effect of environmental fragmentation on the speed of pulsating fronts: from Theorem 1.8, the map $L \mapsto c_L$ is continuous, but can one say that it is monotone? As known in [41] for equations with periodic Fisher-KPP type nonlinearities f , the minimal wave speed c_L^* of

pulsating fronts, which is well defined for all $L > 0$, is nondecreasing with respect to the period $L > 0$. The limits of c_L^* as $L \rightarrow 0^+$ and $L \rightarrow +\infty$ have been determined in [21, 26, 27], and the proofs use as an essential tool a variational formula for c_L^* , which only involves the derivative $\partial_u f(\cdot, 0)$ of f at $u = 0$. For the bistable equation (1.1) under assumptions (1.2) and (1.3), Theorems 1.2 and 1.4 give the limit of c_L as $L \rightarrow 0^+$, but the determination of the limit, if any, of c_L as $L \rightarrow +\infty$ under the assumptions of Theorem 1.5 is still open, as is the question of the monotonicity of c_L with respect to L on the connected components of the set E .

More generally speaking, for general diffusion and reaction coefficients $a(x)$ and $f(x, u)$ satisfying (1.2) and (1.3), the question of the existence of pulsating fronts with zero or nonzero speed c_L for the L -periodic equation (1.1) is very challenging. The possible presence of multiple ordered steady states can prevent the existence of fronts with zero or nonzero speed in general, as in the homogeneous case $f = f(u)$ (see [23] and Remark 4.4 below) or as for problems in straight infinite cylinders with non-convex sections, see [7]. After completion of the present paper, we learned that the answer to the question of existence of stationary or non-stationary fronts is negative in general, see [59]. Apart from the results in [59], the only related “non-existence” results had been concerned with the non-existence of pulsating fronts with nonzero speed, for some specific equations such as (1.8) (see [52, 54]) or in the case of large periods (see [17]). We mention that the existence of stationary solutions (preventing the existence of truly propagating solutions) has also been investigated for spatially discrete models [1, 5, 13, 15, 36, 40], for some non-periodic equations [3, 37, 42, 44] or in some higher-dimensional situations [6, 14].

Exponential stability of pulsating fronts

The last main result of the paper is concerned with the global and exponential stability of the pulsating fronts with nonzero speed. In this section, we fix $L \in (0, \infty)$ and we assume that equation (1.1) admits a pulsating front $\phi_L(x - c_L t, x/L)$ with nonzero speed $c_L \neq 0$. We study the asymptotic behavior as $t \rightarrow +\infty$ of the solutions of

$$\begin{cases} u_t = (a_L(x)u_x)_x + f_L(x, u), & t > 0, \quad x \in \mathbb{R}, \\ u(0, x) = g(x), & x \in \mathbb{R}, \end{cases} \quad (1.17)$$

for the class of “front-like” initial conditions $g \in L^\infty(\mathbb{R}, [0, 1])$ (the initial condition $u(0, x) = g(x)$ is understood for a.e. $x \in \mathbb{R}$). From [23], it is well known that for the homogeneous equation (1.6), if the initial value g is above $1 - \delta$ at $-\infty$ and below δ at $+\infty$, where $\delta > 0$ is as in (1.3), then the solution of associated initial value problem converges at large time to a translate of the traveling wave solution (1.7), and this convergence is exponential in time. For scalar reaction-diffusion equations with bistable time-periodic nonlinearities, such exponential stability of time-periodic traveling waves was first proved in [2], and then a dynamical systems approach to these results was presented in [57, Section 10]. For a special class of equations in periodic habitat with x -independent bistable reaction $f = f(u)$, only the local stability of pulsating fronts had been shown, see [50] (see also [45] for some results on the local stability of fronts for time almost-periodic bistable equations). In the current paper, we show the global and exponential stability of pulsating fronts for the more general equation (1.1).

Theorem 1.9. *Assume that equation (1.1) admits a pulsating front $u_L(t, x) = \phi_L(x - c_L t, x/L)$ with speed $c_L \neq 0$. Then there exists a positive constant $\mu > 0$ such that for every $g \in L^\infty(\mathbb{R}, [0, 1])$ satisfying*

$$\liminf_{x \rightarrow -\infty} g(x) > 1 - \delta \quad \text{and} \quad \limsup_{x \rightarrow +\infty} g(x) < \delta, \quad (1.18)$$

where δ is the constant given in (1.3), the solution $u(t, x)$ of (1.17) satisfies

$$|u(t, x) - u_L(t + \tau_g, x)| = |u(t, x) - \phi_L(x - c_L t - c_L \tau_g, x/L)| \leq C_g e^{-\mu t} \quad \text{for all } t \geq 0, \quad x \in \mathbb{R}, \quad (1.19)$$

for some constants $\tau_g \in \mathbb{R}$ and $C_g > 0$.

This theorem implies in particular that for the large class of initial values satisfying (1.18), the solutions of (1.17) have the same profile and the same wave speed at large time. Furthermore, Theorem 1.9 also immediately provides the uniqueness of the speed of pulsating fronts as well as the uniqueness of the pulsating fronts up to shifts in time in the case where the speed is not zero (these uniqueness properties stated in Theorem 1.1 are proved at the end of Section 2.2). More generally speaking, the global stability of pulsating fronts will be used in [17] to prove a uniqueness result in the larger class of generalized transition fronts.

In Theorem 1.9, the assumption $c_L \neq 0$ is essential. Namely, there are equations of the type (1.1) which admit stationary fronts (with speed $c_L = 0$) that are not stable: in [17] we construct generalized transition fronts which connect unstable stationary fronts to stable ones.

In Theorem 1.9, the initial conditions are assumed to be close enough to 0 and 1 at $\pm\infty$. Actually, the convergence holds under other types of assumptions for the initial conditions, as the following result shows.

Theorem 1.10. *Assume that equation (1.1) admits a pulsating front $u_L(t, x) = \phi_L(x - c_L t, x/L)$ with speed $c_L \neq 0$ and assume that the L -periodic stationary states $0 < \bar{u}(x) < 1$ of (1.1) are all unstable. Then for any L -periodic stationary states $0 < \bar{u}_\pm(x) < 1$ of (1.1) and for any $g \in L^\infty(\mathbb{R}, [0, 1])$ with*

$$\liminf_{x \rightarrow -\infty} (g(x) - \bar{u}_-(x)) > 0 \quad \text{and} \quad \limsup_{x \rightarrow +\infty} (g(x) - \bar{u}_+(x)) < 0, \quad (1.20)$$

the solution $u(t, x)$ of (1.17) satisfies (1.19).

Under the assumptions of Theorem 1.10 (we thank Dr. J. Fang for mentioning initial conditions of the type (1.20)), it follows that any two L -periodic stationary states $0 < \bar{u}_1(x) < 1$ and $0 < \bar{u}_2(x) < 1$ of (1.1) are either identically equal, or unordered in the sense that $\min_{\mathbb{R}}(\bar{u}_1 - \bar{u}_2) < 0 < \max_{\mathbb{R}}(\bar{u}_1 - \bar{u}_2)$. Given this fact, the proof of Theorem 1.10 is then based on the following argument. Firstly, if a function v solves the Cauchy problem (1.17) with an L -periodic initial condition $g \in L^\infty(\mathbb{R}, [0, 1])$ such that $g > \bar{u}_1$ in \mathbb{R} (resp. $g < \bar{u}_2$ in \mathbb{R}), then $v(t, x) \rightarrow 1$ (resp. $v(t, x) \rightarrow 0$) as $t \rightarrow +\infty$ uniformly in $x \in \mathbb{R}$. Secondly, the main step consists in showing that the solution u of (1.17) with an initial condition g satisfying (1.20) can be controlled from below or above as $x \rightarrow \pm\infty$ by solutions v of the above type. Therefore, $u(T, \cdot)$ satisfies the limiting conditions (1.18) for some time $T > 0$ large enough and Theorem 1.9 can be applied to $u(T + t, x)$ and leads to the conclusion.

However, we point out that even if Theorem 1.9 is used in the proof of Theorem 1.10, the assumption (1.20) does not imply (1.18) in general, so Theorem 1.10 cannot be viewed as a direct corollary of Theorem 1.9. To see it, let us consider the homogeneous equation (1.6) with an x -independent function $f = f(u)$ satisfying (1.2), with $\theta_x = \theta$, together with (1.3) and $\int_0^1 f(u) du > 0$. The assumptions of Theorems 1.9 and 1.10 are fulfilled, and any initial condition $g \in L^\infty(\mathbb{R}, [0, 1])$ such that $\liminf_{x \rightarrow -\infty} g(x) > \theta$ and $\limsup_{x \rightarrow +\infty} g(x) < \theta$ satisfies (1.20) but not (1.18) in general.

In Theorems 1.9 and 1.10, the initial conditions g are front-like in the sense that g is not too small at $-\infty$ and not too large at $+\infty$. We mention that the Cauchy problem with initial conditions which are compactly supported or at least not too large at $\pm\infty$ has been extensively studied in the homogeneous and periodic cases, see, e.g., [4, 18, 23, 24, 52, 58].

Remark 1.11. Some of the results proved in the paper could be extended to higher dimensions, such as those on the homogenization regime when $L > 0$ is small. Some others require specific features of some limiting one-dimensional equations, such as the study of the case of large periods, and their extension to higher dimensions is not clear. Lastly, the stability results can not be extended as such in higher dimensions, because of possible non-converging oscillations in the directions orthogonal to the

propagation. We also preferred to focus in this paper on the one-dimensional equation (1.1) for the sake of simplicity of the presentation and since this situation already contains difficult issues and reveals some of the most interesting aspects of the role of the spatial periodicity.

Outline of the paper. In Section 2, we give the proof for the qualitative properties of pulsating fronts stated in Theorem 1.1. Section 3 is devoted to the proof of the existence results for small and large periods L , that is, Theorems 1.2, 1.4 and 1.5. In Section 4, we prove Theorem 1.8 and further results on the properties of the set of periods of non-stationary fronts. Lastly, Section 5 is devoted to the proof of the stability results, Theorems 1.9 and 1.10, while the Appendix (Section 6) is concerned with the proof of some auxiliary lemmas used in the proofs of Theorems 1.2 and 1.8.

2 Qualitative properties of pulsating fronts: proof of Theorem 1.1

This section is devoted to the proof of Theorem 1.1. In Section 2.1, we prove the part of Theorem 1.1 which is concerned with the sign of the speed of non-stationary fronts. In Section 2.2, we carry out the proof for the other part of Theorem 1.1, that is, the monotonicity and uniqueness of non-stationary fronts as well as the uniqueness of the speed for pulsating fronts with zero or nonzero speed.

2.1 The sign of the speeds of non-stationary pulsating fronts

In this section, we show that the sign of non-stationary pulsating fronts is that of the integral $\int_0^1 \bar{f}(u) du$. We state this result (see Lemma 2.2 below) in a separated section, since it will be used several times later and is also of interest in its own. Before doing so, we first establish some exponential bounds for the pulsating fronts when they approach their limiting states, whether they be stationary or non-stationary. The proof is similar to that of the exponential decay of pulsating fronts for combustion nonlinearities in [51]. We include it here because its strategy is useful.

Lemma 2.1. *For a fixed $L > 0$, if $u(t, x) = \phi_L(x - c_L t, x/L)$ is a pulsating front of equation (1.1) with speed $c_L \in \mathbb{R}$, then there exist $A_1, A_2 \in \mathbb{R}$, $\mu_1 > 0$, $\mu_2 > 0$, $C_1 > 0$, $C_2 > 0$ such that*

$$0 < u(t, x) = \phi_L(x - c_L t, x/L) \leq C_1 e^{-\mu_1(x - c_L t)} \quad \text{if } x - c_L t \geq A_1, \quad (2.1)$$

$$0 < 1 - u(t, x) = 1 - \phi_L(x - c_L t, x/L) \leq C_2 e^{\mu_2(x - c_L t)} \quad \text{if } x - c_L t \leq A_2. \quad (2.2)$$

Proof. From the strong parabolic maximum principle, we know that $0 < u(t, x) < 1$ for all $(t, x) \in \mathbb{R}^2$. According to the sign of c_L , two cases may occur.

Case 1: $c_L = 0$. In this case, $u(t, x) = u(x)$ is a stationary solution of equation (1.1) with limiting conditions $\lim_{x \rightarrow -\infty} u(x) = 1$ and $\lim_{x \rightarrow +\infty} u(x) = 0$. Then there exists $A_1 \in \mathbb{R}$ such that $u(x) \leq \delta$ for all $x \geq A_1$, where $\delta > 0$ is as in (1.3). It follows from (1.3) that $(a_L u')'(x) - \gamma u(x) \geq 0$ for all $x \geq A_1$. Choose $\mu_1 > 0$ small enough so that $a_L(x)\mu_1^2 - a'_L(x)\mu_1 - \gamma \leq 0$ for all $x \in \mathbb{R}$, and define $\omega(x) = C_1 e^{-\mu_1 x}$, where C_1 is a positive constant such that $C_1 e^{-\mu_1 A_1} \geq u(A_1)$. But $(a_L \omega')'(x) - \gamma \omega(x) = C_1 (a_L(x)\mu_1^2 - a'_L(x)\mu_1 - \gamma) e^{-\mu_1 x} \leq 0$ for all $x \in \mathbb{R}$. Then the inequality (2.1) follows from the elliptic weak maximum principle, and (2.2) can be obtained in the same way, using this time the second line of (1.3).

Case 2: $c_L \neq 0$. In this case, consider the variables

$$\xi = x - c_L t \quad \text{and} \quad y = \frac{x}{L}. \quad (2.3)$$

Upon substitution, $\phi_L(\xi, y)$ satisfies the following problem:

$$\begin{cases} \tilde{\partial}_L(a(y)\tilde{\partial}_L\phi_L) + c_L\partial_\xi\phi_L + f(y, \phi_L) = 0 \text{ for all } (\xi, y) \in \mathbb{R} \times \mathbb{R}, \\ \phi_L(\xi, y) \text{ is 1-periodic in } y, \\ \phi_L(-\infty, y) = 1, \phi_L(+\infty, y) = 0 \text{ uniformly in } y \in \mathbb{R}, \end{cases} \quad (2.4)$$

where

$$\tilde{\partial}_L = \partial_\xi + \frac{1}{L}\partial_y.$$

By the periodicity condition, equation (2.4) can be restricted in $y \in \mathbb{T} := \mathbb{R}/\mathbb{Z}$.

For any $\mu \in \mathbb{R}$, let \mathcal{T}_μ be the linear operator defined by

$$\mathcal{T}_\mu(\psi) = L^{-2}(a\psi')' - 2L^{-1}\mu a\psi' + (-L^{-1}\mu a' - c_L\mu + a\mu^2 - \gamma)\psi$$

for all $\psi \in C^2(\mathbb{T})$. The Krein-Rutman theory provides the existence and uniqueness, for any $\mu \in \mathbb{R}$, of the principal eigenvalue $\lambda_1(\mu)$ of \mathcal{T}_μ , associated with a (unique up to multiplication) positive eigenfunction ψ_μ . By uniqueness, $\lambda_1(0) = -\gamma < 0$. Moreover, there are $\alpha > 0$ (depending on a) and $\beta > 0$ (depending on a, L, c_L and γ) such that $-\mu a'(y)/L - c_L\mu + a(y)\mu^2 - \gamma \geq \alpha\mu^2 - \beta$ for all $\mu \in \mathbb{R}$ and $y \in \mathbb{R}$, whence $\lambda_1(\mu) \geq \alpha\mu^2 - \beta$ and $\lambda_1(\mu) > 0$ for $|\mu|$ large enough. Since $\mu \mapsto \lambda_1(\mu)$ is a convex function (see, e.g., the proof of [8, Proposition 5.7]), $\lambda_1(\mu)$ is continuous in μ , and hence there is $\mu_1 > 0$ such that $\lambda_1(\mu_1) = 0$. A direct computation shows that

$$\tilde{\partial}_L(a(y)\tilde{\partial}_L(e^{-\mu_1\xi}\psi_{\mu_1}(y))) + c_L\partial_\xi(e^{-\mu_1\xi}\psi_{\mu_1}(y)) - \gamma e^{-\mu_1\xi}\psi_{\mu_1}(y) = 0 \text{ for all } (\xi, y) \in \mathbb{R} \times \mathbb{T}, \quad (2.5)$$

that is, $\bar{u}_t - (a_L(x)\bar{u}_x)_x + \gamma\bar{u} = 0$ with $\bar{u}(t, x) = e^{-\mu_1(x-c_Lt)}\psi_{\mu_1}(x/L)$. On the other hand, since $\lim_{\xi \rightarrow +\infty} \phi_L(\xi, y) = 0$ uniformly for $y \in \mathbb{T}$, there is $A_1 \in \mathbb{R}$ such that $0 < \phi_L(\xi, y) \leq \delta$ for all $\xi \geq A_1$ and $y \in \mathbb{T}$. It then follows from (1.3) that

$$\tilde{\partial}_L(a(y)\tilde{\partial}_L\phi_L) + c_L\partial_\xi\phi_L - \gamma\phi_L \geq 0 \text{ for all } \xi \geq A_1 \text{ and } y \in \mathbb{T}. \quad (2.6)$$

One can normalize ψ_{μ_1} in such a way that $e^{-\mu_1 A_1}\psi_{\mu_1}(y) > \phi_L(A_1, y)$ for all $y \in \mathbb{T}$. Define $\varepsilon^* = \inf \{ \varepsilon \geq 0 \mid u(t, x) - \varepsilon \leq \bar{u}(t, x) \text{ for all } x - c_L t \geq A_1 \}$. The real number ε^* is well defined and $u(t, x) - \varepsilon^* \leq \bar{u}(t, x)$ for all $x - c_L t \geq A_1$. Assume by contradiction that $\varepsilon^* > 0$. Since $u(t + L/c_L, x + L) = u(t, x)$ in \mathbb{R}^2 and $u(t, x) \rightarrow 0$ as $x - c_L t \rightarrow +\infty$, there is then $(t^*, x^*) \in \mathbb{R}^2$ such that $x^* - c_L t^* \geq A_1$ and $u(t^*, x^*) - \varepsilon^* = \bar{u}(t^*, x^*)$, whence $x^* - c_L t^* > A_1$ from the normalization of ψ_{μ_1} . Define $z = \bar{u} - u$. From (2.5) and (2.6), one has $0 \leq z_t - (a_L(x)z_x)_x + \gamma z$ for all $x - c_L t \geq A_1$. But z has a minimum at the point (t^*, x^*) with $x^* - c_L t^* > A_1$ and $z(t^*, x^*) = -\varepsilon^* < 0$. Hence $0 \leq -\gamma\varepsilon^*$, which is a contradiction. Thus, $\varepsilon^* = 0$, that is, (2.1) holds $C_1 = \max_{\mathbb{T}} \psi_{\mu_1} > 0$.

Similarly, there is $A_2 \in \mathbb{R}$ such that $0 < 1 - \phi_L(\xi, y) \leq \delta$ for all $\xi \leq A_2$ and $y \in \mathbb{T}$. As above, by working this time with the function $1 - \phi_L(\xi, y)$ on the set $(-\infty, A_2) \times \mathbb{T}$, (2.2) follows. \square

Lemma 2.2. *If equation (1.1) admits a pulsating front $u(t, x) = \phi_L(x - c_L t, x/L)$ with $c_L \neq 0$, then c_L has the sign of $\int_0^1 \bar{f}(s) ds$.*

Proof. Use the variables (ξ, y) as in (2.3) and notice that, since $c_L \neq 0$, parabolic estimates applied to u and u_t imply that the function $\phi_L(\xi, y)$ is a classical solution of (2.4) and, by Lemma 2.1, all functions $\partial_\xi\phi_L, \partial_y\phi_L, \partial_{\xi\xi}\phi_L, \partial_{\xi y}\phi_L$ and $\partial_{yy}\phi_L$ converge to 0 exponentially as $\xi \rightarrow \pm\infty$. Integrating by parts the first equation of (2.4) against $\partial_\xi\phi_L$ yields $\int_{\mathbb{R} \times \mathbb{T}} (a(y)\tilde{\partial}_L\phi_L\tilde{\partial}_L(\partial_\xi\phi_L) - c_L(\partial_\xi\phi_L)^2 - f(y, \phi_L)\partial_\xi\phi_L) = 0$. Since $\int_{\mathbb{R} \times \mathbb{T}} a(y)\tilde{\partial}_L\phi_L\tilde{\partial}_L(\partial_\xi\phi_L) = (1/2) \int_{\mathbb{R} \times \mathbb{T}} a(y)\partial_\xi(\tilde{\partial}_L\phi_L)^2 = 0$, one infers that

$$c_L \int_{\mathbb{R} \times \mathbb{T}} (\partial_\xi\phi_L)^2 = - \int_{\mathbb{R} \times \mathbb{T}} f(y, \phi_L)\partial_\xi\phi_L = - \int_{\mathbb{R} \times \mathbb{T}} \partial_\xi \left(\int_0^{\phi_L(\xi, y)} f(y, s) ds \right) = \int_0^1 \bar{f}(s) ds.$$

Hence, c_L has the sign of $\int_0^1 \bar{f}(s) ds$. \square

2.2 Monotonicity and uniqueness properties

To complete the proof of Theorem 1.1, we now only need to show that non-stationary pulsating fronts are strictly monotone in time and unique up to shift in time, and that the speeds of pulsating fronts, whether they be stationary or non-stationary, are unique as well. The general strategy can be described as follows. The first step is to derive the time-monotonicity result by quoting the monotonicity property established in [9] for transition fronts (which are more general than pulsating fronts). We should point out that the time-monotonicity property can also be proved directly by applying the sliding method (see, [8, 9, 49]). Then, the time-monotonicity property is used as a key point to establish the global stability of non-stationary fronts stated in Theorem 1.9. Lastly, as already mentioned in Section 1, the uniqueness properties stated in Theorem 1.1 are consequences of such a global stability. Since the proof for Theorem 1.9 is quite lengthy, for the sake of clarity, we just quote the conclusions here and postpone the proof in Section 5 (which is a separated section consisting of the proof for two types of global stability of non-stationary fronts).

Proof of Theorem 1.1. Since the sign property of the speed has been proved in Lemma 2.2, we only do the proof for the monotonicity and uniqueness results here. We first show the time-monotonicity property of pulsating fronts with nonzero speed. According to the definition of transition fronts in [9, Definition 1.1], it is easy to see that, as for equation (1.1), any pulsating front $u_L(t, x) = \phi_L(x - c_L t, x/L)$ connecting 0 and 1 is a transition front connecting two stationary solutions 0 and 1 with $(\Gamma_t)_{t \in \mathbb{R}} := (c_L t)_{t \in \mathbb{R}}$, $(\Omega_t^+)_{t \in \mathbb{R}} := (\{x \mid x < c_L t\})_{t \in \mathbb{R}}$ and $(\Omega_t^-)_{t \in \mathbb{R}} := (\{x \mid x > c_L t\})_{t \in \mathbb{R}}$. Furthermore, due to the assumptions (1.2), (1.3) and the regularity of f , there is a positive constant $\tilde{\delta} \leq \delta$ such that the function $s \mapsto f(x, s)$ is nonincreasing in $[0, \tilde{\delta}]$ and in $[1 - \tilde{\delta}, 1]$. Therefore, if $c_L > 0$, then $u_L(t, x)$ is an invasion of 0 by 1 (see, [9, Definition 1.4]), whence [9, Theorem 1.11] together with its followed discussion implies that $u_L(t, x)$ is increasing in t . Similarly, if $c_L < 0$, then $u_L(t, x)$ is an invasion of 1 by 0, and hence $u_L(t, x)$ is decreasing in t .

As far as the uniqueness properties are concerned, one has to show that if $U(t, x) = \phi_L(x - c_L t, x/L)$ and $\tilde{U}(t, x) = \tilde{\phi}_L(x - \tilde{c}_L t, x/L)$ are two pulsating fronts of equation (1.1) with $c_L \neq 0$, then $\tilde{c}_L = c_L$, and U and \tilde{U} are equal up to shift in time. Since $\tilde{U}(0, \cdot) \in C(\mathbb{R}, [0, 1])$ and $\tilde{U}(0, -\infty) = 1$, $\tilde{U}(0, +\infty) = 0$, Theorem 1.9 (whose proof will be given in Section 5, and is independent of the present one) yields the existence of $\tau \in \mathbb{R}$ such that $\sup_{x \in \mathbb{R}} |\tilde{U}(t, x) - \phi_L(x - c_L t - c_L \tau, x/L)| \rightarrow 0$ as $t \rightarrow +\infty$, whence

$$\sup_{\xi \in \mathbb{R}} \left| \phi_L\left(\xi - c_L \tau, \frac{\xi + c_L t}{L}\right) - \tilde{\phi}_L\left(\xi + (c_L - \tilde{c}_L)t, \frac{\xi + c_L t}{L}\right) \right| \rightarrow 0 \text{ as } t \rightarrow +\infty. \quad (2.7)$$

Remember that $\tilde{\phi}_L(+\infty, x/L) = \phi_L(+\infty, x/L) = 0$, $\tilde{\phi}_L(-\infty, x/L) = \phi_L(-\infty, x/L) = 1$ uniformly in $x \in \mathbb{R}$, that $\phi_L(\xi, x/L)$ is continuous in \mathbb{R}^2 , L -periodic in x and decreasing in ξ , whence $0 < \min_{x \in \mathbb{R}} \phi_L(\xi, x/L) \leq \max_{x \in \mathbb{R}} \phi_L(\xi, x/L) < 1$ for all $\xi \in \mathbb{R}$. Therefore, if $c_L \neq \tilde{c}_L$, by fixing $\xi \in \mathbb{R}$ and letting $t \rightarrow +\infty$ in (2.7), one derives a contradiction. Thus, $c_L = \tilde{c}_L$ and one infers from (2.7) that, for every $(\xi, x) \in \mathbb{R}^2$ and $k \in \mathbb{N}$,

$$\phi_L\left(\xi - c_L \tau, \frac{x}{L}\right) - \tilde{\phi}_L\left(\xi, \frac{x}{L}\right) = \phi_L\left(\xi - c_L \tau, \frac{\xi}{L} + c_L\left(\frac{x - \xi}{c_L L} + \frac{k}{|c_L|}\right)\right) - \tilde{\phi}_L\left(\xi, \frac{\xi}{L} + c_L\left(\frac{x - \xi}{c_L L} + \frac{k}{|c_L|}\right)\right) \xrightarrow{k \rightarrow +\infty} 0.$$

Thus, $\phi_L(\xi - c_L \tau, x/L) = \tilde{\phi}_L(\xi, x/L)$ for all $(\xi, x) \in \mathbb{R}^2$, that is, $\tilde{U}(t, x) = U(t + \tau, x)$ for all $(t, x) \in \mathbb{R}^2$. Hence, the proof of Theorem 1.1 is complete. \square

3 Existence of pulsating fronts

As already emphasized, the proofs of Theorems 1.2 and 1.4 on the existence of pulsating fronts for small periods L use different methods. They are carried out in Sections 3.1 and 3.2, whereas Section 3.3 is

devoted to the proof of Theorem 1.5 on the existence of pulsating fronts for large periods L .

3.1 Small periods L : the implicit function theorem

This section is devoted to the proof of Theorem 1.2. The strategy is similar to that used by Heinze in [31]. There, the homogeneous process for the following equation as $\varepsilon \rightarrow 0^+$ was considered

$$\begin{cases} u_t = d \Delta u + f(u), & t \in \mathbb{R}, x \in \Omega_\varepsilon, \\ u_\nu = 0, & t \in \mathbb{R}, x \in \partial\Omega_\varepsilon, \end{cases} \quad (3.1)$$

where d is a positive constant, $f : \mathbb{R} \rightarrow \mathbb{R}$ is a bistable function of class C^2 , $u_\nu = \frac{\partial u}{\partial \nu}$, ν denotes the exterior normal vector to Ω_ε and $\Omega_\varepsilon = \varepsilon \Omega$, with Ω being a smooth open connected set of \mathbb{R}^n which is 1-periodic in all directions x_i ($1 \leq i \leq n$). Assuming the existence of a traveling wave for a homogenized problem and then using the implicit function theorem in an appropriate function space, Heinze obtained a unique (up to shift in time) pulsating front for the equation (3.1) at small ε . Although a portion of the arguments of Theorem 1.2 follows the same lines as those used in [31] for problem (3.1), the oscillations in the diffusion coefficient a_L and the nonlinearity f_L in equation (1.1) make the analysis different and more complicated. In addition, we provide a different approach in the convergence to the homogeneous process (see Lemma 3.2 below). As a matter of fact, the approach we use here allows us to prove some continuity results at any $L > 0$ and not only at $L = 0^+$ (see Lemma 3.4 below). This strategy can then later be applied to the proof of Theorem 1.8 in Section 4, where a pulsating front for equation (1.1) is assumed to exist at a fixed $L_0 > 0$. Thus, for the sake of completeness of the proof here and also for convenience of that of Theorem 1.8, we include the details as follows.

We assume that the homogenized equation (1.9) has a (unique up to shifts) front ϕ_0 , with speed $c_0 \neq 0$. Without loss of generality, one may assume that the speed satisfies $c_0 > 0$ throughout this subsection. Indeed, if $c_0 < 0$, then the function $\psi_0(x) = 1 - \phi_0(-x)$ solves (1.9) with speed $-c_0 (> 0)$ instead of c_0 and with $\bar{g}(u) = -\bar{f}(1 - u)$ instead of \bar{f} , where $g(x, u) = -f(-x, 1 - u)$. Furthermore, if $u(t, x) = \phi(x - c_L t, x/L)$ is a pulsating front for (1.1) with speed c_L , then $v(t, x) = 1 - \phi(-x - c_L t, -x/L)$ is a pulsating front with speed $-c_L$ for the equation $v_t = (\tilde{a}_L v_x)_x + g_L(x, v)$ with $\tilde{a}(x) = a(-x)$ (and $\tilde{a}_H = a_H$). Therefore, even if it means changing a into \tilde{a} and f into g , one can assume here that $c_0 > 0$.

Define the new variables (ξ, y) as in (2.3). For a given $L > 0$, finding pulsating fronts $u(t, x) = \phi_L(x - c_L t, x/L)$ of (1.1) with a speed $c_L \neq 0$ amounts to finding solutions $\phi_L(\xi, y)$ for the problem (2.4). We also restricted equation (2.4) in $y \in \mathbb{T} := \mathbb{R}/\mathbb{Z}$, due to the periodicity condition. Let $L^2(\mathbb{R} \times \mathbb{T})$ and $H^1(\mathbb{R} \times \mathbb{T})$ be the Banach spaces defined by

$$\begin{cases} L^2(\mathbb{R} \times \mathbb{T}) &= \{v \in L^2_{loc}(\mathbb{R} \times \mathbb{R}) \mid v \in L^2(\mathbb{R} \times (0, 1)) \text{ and } v(\xi, y + 1) = v(\xi, y) \text{ a.e. in } \mathbb{R}^2\}, \\ H^1(\mathbb{R} \times \mathbb{T}) &= \{v \in H^1_{loc}(\mathbb{R} \times \mathbb{R}) \mid v \in H^1(\mathbb{R} \times (0, 1)) \text{ and } v(\xi, y + 1) = v(\xi, y) \text{ a.e. in } \mathbb{R}^2\}, \end{cases}$$

endowed with the norms $\|v\|_{L^2(\mathbb{R} \times \mathbb{T})} = \|v\|_{L^2(\mathbb{R} \times (0, 1))}$ and $\|v\|_{H^1(\mathbb{R} \times \mathbb{T})} = \|v\|_{H^1(\mathbb{R} \times (0, 1))} = (\|v\|_{L^2(\mathbb{R} \times \mathbb{T})} + \|\partial_\xi v\|_{L^2(\mathbb{R} \times \mathbb{T})} + \|\partial_y v\|_{L^2(\mathbb{R} \times \mathbb{T})})^{1/2}$, respectively.

For the homogenization limit as $L \rightarrow 0^+$, we introduce some auxiliary operators. Namely, fix a real $\beta > 0$ and for any $c > 0$, define

$$\begin{aligned} M_{c,L}(v) &= \tilde{\partial}_L(a \tilde{\partial}_L v) + c \partial_\xi v - \beta v, \quad v \in \mathcal{D}_L = \{v \in H^1(\mathbb{R} \times \mathbb{T}) \mid \tilde{\partial}_L(a \tilde{\partial}_L v) \in L^2(\mathbb{R} \times \mathbb{T})\}, \quad L \in \mathbb{R}^*, \\ M_{c,0}(v) &= a_H v'' + c v' - \beta v, \quad v \in D(M_{c,0}) = H^2(\mathbb{R}), \end{aligned} \quad (3.2)$$

where $a_H > 0$ is the harmonic mean of a defined in (1.10). The fact that $v \in \mathcal{D}_L$ means that $v \in H^1(\mathbb{R} \times \mathbb{T})$ and there is a constant $C > 0$ such that $|\int_{\mathbb{R} \times \mathbb{T}} a \tilde{\partial}_L v \tilde{\partial}_L \varphi| \leq C \|\varphi\|_{L^2(\mathbb{R} \times \mathbb{T})}$ and $\int_{\mathbb{R} \times \mathbb{T}} a \tilde{\partial}_L v \tilde{\partial}_L \varphi =$

$-\int_{\mathbb{R} \times \mathbb{T}} \tilde{\partial}_L(a\tilde{\partial}_L v)\varphi$ for all $\varphi \in H^1(\mathbb{R} \times \mathbb{T})$. Notice that the operators $M_{c,L}$ are also defined for negative values of L , that the domain \mathcal{D}_L is dense in $H^1(\mathbb{R} \times \mathbb{T})$ and that $M_{c,L}(v) \in L^2(\mathbb{R} \times \mathbb{T})$ for all $v \in \mathcal{D}_L$ and $L \in \mathbb{R}^*$. Furthermore, the domain $D(M_{c,0}) = H^2(\mathbb{R})$ of $M_{c,0}$ is dense in $H^1(\mathbb{R})$ and $M_{c,0}(v) \in L^2(\mathbb{R})$ for all $v \in D(M_{c,0})$. We first state in the following three lemmas some of the basic properties of the operators $M_{c,L}$, $M_{c,0}$ and their inverses.

Lemma 3.1. *The operators $M_{c,0} : H^2(\mathbb{R}) \rightarrow L^2(\mathbb{R})$ and $M_{c,L} : \mathcal{D}_L \rightarrow L^2(\mathbb{R} \times \mathbb{T})$ for $L \neq 0$ are invertible for every $c > 0$. Furthermore, for every $r_1 > 0$ and $r_2 > 0$, there is a constant $C = C(r_1, r_2, \beta, a)$ such that for all $c \geq r_1$, $|L| \leq r_2$, $g \in L^2(\mathbb{R} \times \mathbb{T})$ and $\varphi \in L^2(\mathbb{R})$,*

$$\|M_{c,L}^{-1}(g)\|_{H^1(\mathbb{R} \times \mathbb{T})} \leq C\|g\|_{L^2(\mathbb{R} \times \mathbb{T})} \text{ if } L \neq 0, \quad \text{and} \quad \|M_{c,0}^{-1}(\varphi)\|_{H^1(\mathbb{R})} \leq C\|\varphi\|_{L^2(\mathbb{R})}.$$

The following lemma deals with the convergence of M_{c_n, L_n}^{-1} to $M_{c,0}^{-1}$ when $L_n \rightarrow 0$ with $L_n \in \mathbb{R}^*$, $c_n \rightarrow c > 0$ and the operators M_{c_n, L_n}^{-1} are applied to g_n with $g_n \rightarrow g$ in $L^2(\mathbb{R} \times \mathbb{T})$.

Lemma 3.2. *Fix $\beta > 0$ and $c > 0$. Then for every $g \in L^2(\mathbb{R} \times \mathbb{T})$,*

$$M_{c_n, L_n}^{-1}(g_n) \rightarrow M_{c,0}^{-1}(\bar{g}) \text{ in } H^1(\mathbb{R} \times \mathbb{T}) \quad \text{and} \quad M_{c_n, 0}^{-1}(\varphi_n) \rightarrow M_{c,0}^{-1}(\bar{g}) \text{ in } H^1(\mathbb{R}) \quad (3.3)$$

as $n \rightarrow +\infty$ for every sequences $(g_n)_{n \in \mathbb{N}}$ in $L^2(\mathbb{R} \times \mathbb{T})$, $(\varphi_n)_{n \in \mathbb{N}}$ in $L^2(\mathbb{R})$, $(c_n)_{n \in \mathbb{N}}$ in $(0, +\infty)$ and $(L_n)_{n \in \mathbb{N}}$ in \mathbb{R}^* such that $\|g_n - g\|_{L^2(\mathbb{R} \times \mathbb{T})} \rightarrow 0$, $\|\varphi_n - \bar{g}\|_{L^2(\mathbb{R})} \rightarrow 0$, $c_n \rightarrow c$ and $L_n \rightarrow 0$ as $n \rightarrow +\infty$, where $\bar{g} \in L^2(\mathbb{R})$ is defined as

$$\bar{g}(\xi) = \int_{\mathbb{T}} g(\xi, y) dy \quad \text{for } \xi \in \mathbb{R}, \quad (3.4)$$

and $M_{c,0}^{-1}(\bar{g}) \in H^2(\mathbb{R})$ is viewed as an $H^2(\mathbb{R} \times \mathbb{T})$ function by extending it trivially in the y -variable. Furthermore, the limits (3.3) are uniform in the ball $B_A = \{g \in L^2(\mathbb{R} \times \mathbb{T}) \mid \|g\|_{L^2(\mathbb{R} \times \mathbb{T})} \leq A\}$ for any $A > 0$.

The following lemma is the analogue of Lemma 3.2, when $L_n \rightarrow L \neq 0$ as $n \rightarrow +\infty$.

Lemma 3.3. *Fix $\beta > 0$, $c > 0$ and $L \in \mathbb{R}^*$. Then for every $g \in L^2(\mathbb{R} \times \mathbb{T})$ and every sequences $(g_n)_{n \in \mathbb{N}}$ in $L^2(\mathbb{R} \times \mathbb{T})$, $(c_n)_{n \in \mathbb{N}}$ in $(0, +\infty)$ and $(L_n)_{n \in \mathbb{N}}$ in \mathbb{R}^* such that $\|g_n - g\|_{L^2(\mathbb{R} \times \mathbb{T})} \rightarrow 0$, $c_n \rightarrow c$ and $L_n \rightarrow L$ as $n \rightarrow +\infty$, there holds $M_{c_n, L_n}^{-1}(g_n) \rightarrow M_{c,L}^{-1}(g)$ in $H^1(\mathbb{R} \times \mathbb{T})$ as $n \rightarrow +\infty$. Furthermore, the limit is uniform with respect to $g \in B_A$ for every $A > 0$.*

In order not to lengthen the course of the proof of Theorem 1.2, the proofs of these auxiliary lemmas are postponed in the Appendix (Section 6).

Coming back to the solution (ϕ_0, c_0) of the homogeneous equation (1.9), it is well known that there are some positive constants A_1 and A_2 such that $\phi_0(\xi) \sim A_1 e^{-\lambda_1 \xi}$ as $\xi \rightarrow +\infty$ and $1 - \phi_0(\xi) \sim A_2 e^{\lambda_2 \xi}$ as $\xi \rightarrow -\infty$, with $\lambda_1 = (c_0 + (c_0^2 - 4a_H \bar{f}'(0))^{1/2}) / (2a_H) > 0$ and $\lambda_2 = (-c_0 + (c_0^2 - 4a_H \bar{f}'(1))^{1/2}) / (2a_H) > 0$. Now, in order to apply an implicit function theorem around the homogeneous front (ϕ_0, c_0) to get the existence of pulsating fronts for small L , we will rewrite the solutions (c_L, ϕ_L) of (2.4) in terms of zeroes of a function G introduced below. So we need to introduce a few more notations. Firstly, let $\chi \in C^2(\mathbb{R})$ be a solution of the equation $a(y)(\chi'(y) + 1) = a_H$. It is unique up to a constant and, by (1.10), χ is periodic. Therefore,

$$(a(\chi' + 1))' = 0 \text{ in } \mathbb{R} \quad \text{and} \quad \chi(y + 1) = \chi(y) \text{ for all } y \in \mathbb{R}. \quad (3.5)$$

Secondly, for any $v \in H^1(\mathbb{R} \times \mathbb{T})$, $c > 0$ and $L \in \mathbb{R}$, define

$$\begin{aligned} K(v, c, L)(\xi, y) = & (a_H + (a\chi)'(y))\phi_0''(\xi) + La(y)\chi(y)\phi_0^{(3)}(\xi) + c(\phi_0'(\xi) + L\chi(y)\phi_0''(\xi)) \\ & + f(y, v(\xi, y) + \phi_0(\xi) + L\chi(y)\phi_0'(\xi)) + \beta v(\xi, y). \end{aligned}$$

From the exponential convergence of ϕ_0 to its limits at $\pm\infty$ and from standard elliptic estimates, one has $\phi_0 \in L^2(0, +\infty)$, $1 - \phi_0 \in L^2(-\infty, 0)$ and $\phi_0' \in H^2(\mathbb{R})$. Since $f(y, u)$ is globally Lipschitz-continuous in u uniformly for $y \in \mathbb{T}$, it follows that $K(v, c, L) \in L^2(\mathbb{R} \times \mathbb{T})$ for any $v \in H^1(\mathbb{R} \times \mathbb{T})$ (and even for any $v \in L^2(\mathbb{R} \times \mathbb{T})$). Finally, for $v \in H^1(\mathbb{R} \times \mathbb{T})$, $c > 0$ and $L \in \mathbb{R}$, we set $G(v, c, L) = (G_1, G_2)(v, c, L)$ with

$$\begin{cases} G_1(v, c, L) &= \begin{cases} v + M_{c,L}^{-1}(K(v, c, L)) & \text{if } L \neq 0, \\ v + M_{c,0}^{-1}(\overline{K(v, c, 0)}) & \text{if } L = 0, \end{cases} \\ G_2(v, c, L) &= \int_{\mathbb{R}^+ \times \mathbb{T}} (\phi_0(\xi) + v(\xi, y) + L\chi(y)\phi_0'(\xi))^2 - \int_{\mathbb{R}^+} \phi_0^2, \end{cases} \quad (3.6)$$

where $\overline{K(v, c, 0)} \in L^2(\mathbb{R})$ is defined as \bar{g} in (3.4) (in particular, the term $(a\chi)'$ disappears in $\overline{K(v, c, 0)}$).² In view of Lemma 3.1, the function G maps $H^1(\mathbb{R} \times \mathbb{T}) \times (0, +\infty) \times \mathbb{R}$ into $H^1(\mathbb{R} \times \mathbb{T}) \times \mathbb{R}$. Note that $G(0, c_0, 0) = (0, 0)$ by the definition of (ϕ_0, c_0) and \bar{f} .

Moreover, it is also straightforward to check, using in particular (3.5) and $a(\chi' + 1) = a_H$, that a pair $(\phi_L, c_L) \in (\phi_0 + H^1(\mathbb{R} \times \mathbb{T})) \times (0, +\infty)$ solves the first two lines of (2.4) for $L \neq 0$ with

$$\int_{\mathbb{R}^+ \times \mathbb{T}} \phi_L^2 = \int_{\mathbb{R}^+} \phi_0^2, \quad (3.7)$$

if and only if $G(\phi_L - \phi_0 - L\chi\phi_0', c_L, L) = (0, 0)$. This is what led us to the definition of G and the introduction of χ .

The general strategy of the proof of Theorem 1.2 is to use the implicit function theorem for the existence and uniqueness of a solution of (2.4) and (3.7) for small L . For this, we use some continuity and differentiability properties of G .

Lemma 3.4. *The function $G : H^1(\mathbb{R} \times \mathbb{T}) \times (0, +\infty) \times \mathbb{R} \rightarrow H^1(\mathbb{R} \times \mathbb{T}) \times \mathbb{R}$ is continuous, and it is continuously Fréchet differentiable with respect to (v, c) . Furthermore, the operator $Q = \partial_{(v,c)}G(0, c_0, 0) : H^1(\mathbb{R} \times \mathbb{T}) \times \mathbb{R} \rightarrow H^1(\mathbb{R} \times \mathbb{T}) \times \mathbb{R}$ is invertible.*

The proof of Lemma 3.4 is quite lengthy and is therefore postponed in the Appendix (Section 6). We just point out here that the proof of the invertibility of the operator Q uses as key-points some properties of the linearization of (1.9) at ϕ_0 . Namely, denoting

$$H(u) = a_H u'' + c_0 u' + \bar{f}'(\phi_0)u = M_{c_0,0}(u) + \beta u + \bar{f}'(\phi_0)u \quad \text{for } u \in H^2(\mathbb{R}) \quad (3.8)$$

and the adjoint operator H^* being given by $H^*(u) = a_H u'' - c_0 u' + \bar{f}'(\phi_0)u$ for $u \in H^2(\mathbb{R})$ in such a way that $(H^*(v), u)_{L^2(\mathbb{R})} = (v, H(u))_{L^2(\mathbb{R})}$ for all $u, v \in H^2(\mathbb{R})$, it follows from Section 4 of [31] that the operators H and H^* have algebraically simple eigenvalue 0 and that the range of H is closed in $L^2(\mathbb{R})$. Furthermore, the kernel $\ker(H)$ of H is equal to $\ker(H) = \mathbb{R}\phi_0'$. We will see in the proof of Theorem 1.8 that similar properties hold for the linearization of the equation (2.4) around a pulsating front for a period $L_0 > 0$.

End of the proof of Theorem 1.2. From Lemma 3.4, one can apply the implicit function theorem for the function $G : H^1(\mathbb{R} \times \mathbb{T}) \times (0, +\infty) \times \mathbb{R} \rightarrow H^1(\mathbb{R} \times \mathbb{T}) \times \mathbb{R}$ (see, e.g., the remark of [16, Theorem 15.1]). Then there exists $L_* > 0$ such that for any $0 < L < L_*$, there is a unique $(v_L, c_L) \in H^1(\mathbb{R} \times \mathbb{T}) \times (0, +\infty)$ such that $G(v_L, c_L, L) = (0, 0)$ and $(v_L, c_L) \rightarrow (0, c_0)$ as $L \rightarrow 0$. Let $\phi_L(\xi, y) = \phi_0(\xi) + v_L(\xi, y) + L\chi(y)\phi_0'(\xi)$ for $(\xi, y) \in \mathbb{R} \times \mathbb{T}$. It follows in particular that $\phi_L - \phi_0 \rightarrow 0$ in $H^1(\mathbb{R} \times \mathbb{T})$ as $L \rightarrow 0^+$. According to

²The second component of the function G in (3.6) will fix the shift in ξ . Actually, one can choose any set with the form $(s, +\infty) \times \mathbb{T}$ for $s \in \mathbb{R}$ as an integral domain, while the set $\mathbb{R} \times \mathbb{T}$ is not suitable, since $\phi_0 \notin L^2(\mathbb{R})$. Similarly, (3.7) is used to fix the shift of ϕ_L in ξ .

the definition of G , for every $L \in (0, L_*)$, (ϕ_L, c_L) is a weak solution and then, by parabolic regularity, a bounded classical solution of the equation (2.4) which satisfies, in particular, the limiting conditions in (2.4) since $\partial_\xi \phi_L$ and $\partial_y \phi_L$ actually belong to $L^\infty(\mathbb{R} \times \mathbb{R})$. The strong maximum principle together with $f(y, u) > 0$ (resp. $f(y, u) < 0$) for all $(y, u) \in \mathbb{R} \times (-\infty, 0)$ (resp. $(y, u) \in \mathbb{R} \times (1, +\infty)$) implies that ϕ_L ranges in $(0, 1)$.

Lastly, for any given $L \in (0, L_*)$, if $\tilde{u}_L(t, x) = \tilde{\phi}_L(x - \tilde{c}_L t, x/L)$ is a pulsating front for (1.1), then $\tilde{c}_L = c_L > 0$ by Theorem 1.1,³ while $\tilde{v}_L(\xi, y) := \tilde{\phi}_L(\xi, y) - \phi_0(\xi) - L\chi(y)\phi_0'(\xi) \in H^1(\mathbb{R} \times \mathbb{T})$ from the general exponential decay estimates of $\tilde{\phi}_L$ and $1 - \tilde{\phi}_L$ as $\xi \rightarrow \pm\infty$ (see Lemma 2.1). By continuity, there is $\xi \in \mathbb{R}$ such that $\int_{\mathbb{R}^+ \times \mathbb{T}} \tilde{\phi}_L^2(\xi + \xi, y) = \int_{\mathbb{R}^+} \phi_0^2$, whence $G(\tilde{v}_L(\cdot + \xi, \cdot), c_L, L) = (0, 0)$ and $\tilde{\phi}_L(\xi + \xi, y) = \phi_L(\xi, y)$ for all $(\xi, y) \in \mathbb{R} \times \mathbb{T}$ by uniqueness of v_L . The proof of Theorem 1.2 is thereby complete. \square

3.2 Small periods L : the instability of L -periodic steady states

In this section, we do the proof of Theorem 1.4. To obtain the existence result, we employ the abstract theory in [22] by checking that the semiflow generated by the equation (1.17) satisfies the general assumptions, including in particular some stability properties, for bistable monotone semiflows.

To do so, we first need to define precisely the notion of stability of periodic steady states (and, actually, that of general steady states, since one will need this notion later in Theorem 4.3 below). Namely, let $L > 0$ and let $\bar{u} : \mathbb{R} \rightarrow [0, 1]$ denote a steady state of (1.1). For any $R > 0$, let $\lambda_{1,R}(L, \bar{u})$ be the unique real number λ such that there exists a $C^2([-R, R])$ function ψ satisfying

$$(a_L(x)\psi')' + \partial_u f_L(x, \bar{u}(x))\psi = \lambda\psi \text{ in } [-R, R], \quad \psi > 0 \text{ in } (-R, R), \quad \psi(-R) = \psi(R) = 0. \quad (3.9)$$

The real number $\lambda_{1,R}(L, \bar{u})$ is the principal eigenvalue of equation (3.9), and ψ is the (unique up to multiplication) corresponding eigenfunction. It is well known that $\lambda_{1,R}(L, \bar{u})$ exists uniquely, and that $\lambda_{1,R}(L, \bar{u})$ is increasing in R (see, e.g., [11, Lemma 2.5]).

Definition 3.5. *Let $\lambda_1(L, \bar{u}) = \lim_{R \rightarrow +\infty} \lambda_{1,R}(L, \bar{u})$. One says that \bar{u} is unstable if $\lambda_1(L, \bar{u}) > 0$, stable if $\lambda_1(L, \bar{u}) < 0$, and semistable if $\lambda_1(L, \bar{u}) \leq 0$.*

By comparison, there holds $\inf_{x \in \mathbb{R}} (\partial_u f_L(x, \bar{u}(x))) \leq \lambda_1(L, \bar{u}) \leq \sup_{x \in \mathbb{R}} (\partial_u f_L(x, \bar{u}(x)))$. It also follows from [11] that if \bar{u} is L -periodic, then $\lambda_1(L, \bar{u})$ is the principal eigenvalue of the periodic eigenvalue problem

$$(a_L(x)\varphi')' + \partial_u f_L(x, \bar{u}(x))\varphi = \lambda\varphi \text{ in } \mathbb{R}, \quad \varphi > 0 \text{ in } \mathbb{R}, \quad \varphi \text{ is } L\text{-periodic}. \quad (3.10)$$

In particular, the steady state $\bar{u} \equiv 0$ is stable since $\partial_u f(x, 0) \leq -\gamma$. Similarly, the steady state $\bar{u} \equiv 1$ is stable. Then the Dancer-Hess connecting orbit theorem (see, e.g., [34, Proposition 9.1]) implies that there exists at least one L -periodic steady state \bar{u} such that $0 < \bar{u} < 1$ in \mathbb{R} . In addition, it turns out that for small $L > 0$, all such intermediate L -periodic steady states are unstable under the assumption (1.12), as the following lemma shows.

Lemma 3.6. *Under the assumption (1.12), there is $\tilde{L}_* > 0$ such that $\lambda_1(L, \bar{u}) > 0$ for every $0 < L < \tilde{L}_*$ and for every L -periodic steady state \bar{u} of (1.1) with $0 < \bar{u} < 1$.*

³We point out that the uniqueness of the speed, that is $\tilde{c}_L = c_L$, can not be proved directly by the uniqueness of the solution of $G(v_L, c_L, L) = (0, 0)$. Actually, since the function G is defined on $H^1(\mathbb{R} \times \mathbb{T}) \times (0, +\infty) \times \mathbb{R}$, the implicit function theorem only guarantees the uniqueness of positive speed, while it can not exclude the case where $c_L > 0$ and $\tilde{c}_L = 0$.

Proof. Assume by contradiction that there are some sequences $(L_n)_{n \in \mathbb{N}}$ in $(0, +\infty)$, $(\bar{u}_n)_{n \in \mathbb{N}}$ and $(\psi_n)_{n \in \mathbb{N}}$ in $C^2(\mathbb{R})$ such that $L_n \rightarrow 0^+$ as $n \rightarrow +\infty$ and, for each $n \in \mathbb{N}$, \bar{u}_n satisfies

$$(a_{L_n} \bar{u}'_n)' + f_{L_n}(x, \bar{u}_n) = 0 \quad \text{in } \mathbb{R}, \quad \bar{u}_n \text{ is } L_n\text{-periodic}, \quad 0 < \bar{u}_n < 1 \text{ in } \mathbb{R}, \quad (3.11)$$

and ψ_n satisfies

$$(a_{L_n} \psi'_n)' + \partial_u f_{L_n}(x, \bar{u}_n) \psi_n = \lambda_1(L_n, \bar{u}_n) \psi_n \quad \text{in } \mathbb{R}, \quad \psi_n \text{ is } L_n\text{-periodic}, \quad \psi_n > 0 \text{ in } \mathbb{R}, \quad (3.12)$$

with principal eigenvalue $\lambda_1(L_n, \bar{u}_n) \leq 0$. Since

$$\min_{x \in \mathbb{R}, u \in [0,1]} (\partial_u f_{L_n}(x, u)) \leq \lambda_1(L_n, \bar{u}_n) \leq \max_{x \in \mathbb{R}, u \in [0,1]} (\partial_u f_{L_n}(x, u)), \quad (3.13)$$

the sequence $(\lambda_1(L_n, \bar{u}_n))_{n \in \mathbb{N}}$ is then bounded. Up to extraction of some subsequence, there is a real number $\tilde{\lambda}_1 \leq 0$ such that $\lambda_1(L_n, \bar{u}_n) \rightarrow \tilde{\lambda}_1$ as $n \rightarrow +\infty$. Now, denote $v_n(y) = \bar{u}_n(L_n y)$. Each function v_n is 1-periodic and obeys $a(y)v''_n(y) + a'(y)v'_n(y) + L_n^2 f(y, v_n(y)) = 0$ for all $y \in \mathbb{R}$. It then follows from standard elliptic estimates that there is a 1-periodic $C^2(\mathbb{R})$ function $0 \leq v_\infty \leq 1$ such that, up to extraction of some subsequence, $v_n \rightarrow v_\infty$ in $C^2(\mathbb{R})$ as $n \rightarrow +\infty$, and the function v_∞ solves $av''_\infty + a'v'_\infty = 0$ in \mathbb{R} . Thus, av'_∞ is a constant function, and then v'_∞ has a sign. Since v_∞ is 1-periodic, v_∞ is then a constant function.

Next, one shows that $v_\infty = \bar{\theta}$. Integrating $(a_{L_n} \bar{u}'_n)' + f_{L_n}(x, \bar{u}_n) = 0$ over $[0, L_n]$ yields

$$0 = \frac{1}{L_n} \int_0^{L_n} f_{L_n}(x, \bar{u}_n(x)) dx = \int_0^1 f(y, v_n(y)) dy \rightarrow \bar{f}(v_\infty) \quad \text{as } n \rightarrow +\infty.$$

Therefore, $\bar{f}(v_\infty) = 0$. If $v_\infty = 0$, then the assumption (1.3) would imply that $0 < v_n \leq \delta$ in \mathbb{R} for n large enough, whence $f(y, v_n(y)) \leq -\gamma v_n(y) < 0$ and $(av'_n)' = -L_n^2 f(y, v_n) > 0$ in \mathbb{R} for n large enough, which contradicts the fact that av'_n is 1-periodic. Similarly, one obtains that $v_\infty \neq 1$. It then follows from the assumption (1.12) that $v_\infty = \bar{\theta}$.

Finally, for any $n \in \mathbb{N}$, multiply the equation (3.12) by ψ_n^{-1} and integrate by parts over $[0, L_n]$. It then follows that $\int_0^{L_n} (a_{L_n}(x)(\psi'_n(x))^2 / (\psi_n(x))^2 + \partial_u f_{L_n}(x, \bar{u}_n(x))) dx = L_n \lambda_1(L_n, \bar{u}_n)$. As a consequence,

$$\lambda_1(L_n, \bar{u}_n) \geq \frac{1}{L_n} \int_0^{L_n} \partial_u f_{L_n}(x, \bar{u}_n(x)) dx = \int_0^1 \partial_u f(y, v_n(y)) dy.$$

Taking the limit as $n \rightarrow +\infty$ yields that $\tilde{\lambda}_1 \geq \bar{f}'(\bar{\theta}) > 0$, which contradicts the assumption that $\tilde{\lambda}_1 \leq 0$. The proof of Lemma 3.6 is thereby complete. \square

A consequence of Lemma 3.6 is the following non-existence result. Before doing so, we first introduce an important notation: in the sequel, for any $u_0 \in C(\mathbb{R}, [0, 1])$, $u(t, x; u_0)$ denotes the unique solution of equation (1.1) with initial value $u(0, x; u_0) = u_0(x)$.

Lemma 3.7. *For every $0 < L < \tilde{L}_*$ and for every L -periodic steady state $0 < \bar{u} < 1$ of (1.1), there is no steady state v of (1.1) such that $0 < v < \bar{u}$ and there is no steady state w of (1.1) such that $\bar{u} < w < 1$.*

Proof. We only prove the first conclusion, since the proof of the second one is similar. Thus, let $0 < L < \tilde{L}_*$, let $0 < \bar{u} < 1$ be an L -periodic steady state of (1.1) and let v be a steady state of (1.1) such that $0 \leq v < \bar{u}$. Our goal is to show that $v \equiv 0$ in \mathbb{R} . We emphasize that a difficulty comes from the fact that v is not assumed to be periodic.

Step 1: $\sup_{x \in \mathbb{R}} (v(x) - \bar{u}(x)) < 0$. First, since $\lambda_1(L, \bar{u}) > 0$ by Lemma 3.6, it follows from Definition 3.5 that there is $R > L/2$ large enough such that $\lambda_{1,R}(L, \bar{u}) > 0$, where $\lambda_{1,R}(L, \bar{u})$ is the principal eigenvalue of (3.9). For any $\varepsilon > 0$, define

$$v_\varepsilon(x) = \begin{cases} \bar{u}(x) - \varepsilon\psi_R(x) & \text{if } |x| < R, \\ \bar{u}(x) & \text{if } |x| \geq R, \end{cases} \quad (3.14)$$

where ψ_R is the positive eigenfunction of (3.9) corresponding to $\lambda_{1,R}(L, \bar{u})$ with normalization $\|\psi_R\|_{L^\infty((-R,R))} = 1$. Choose $\varepsilon_0 > 0$ small enough such that, for all $0 < \varepsilon \leq \varepsilon_0$, $0 < v_\varepsilon \leq \bar{u}$ in \mathbb{R} and

$$f_L(x, v_\varepsilon) - f_L(x, \bar{u}) \leq -\partial_u f_L(x, \bar{u}) \times \varepsilon\psi_R + \frac{\lambda_{1,R}(L, \bar{u})}{2} \times \varepsilon\psi_R \quad \text{in } (-R, R).$$

It then follows that

$$\begin{aligned} (a_L(v_\varepsilon)_x)_x + f_L(x, v_\varepsilon) &= (a_L\bar{u}_x)_x - (a_L(\varepsilon\psi_R)_x)_x + f_L(x, v_\varepsilon) - f_L(x, \bar{u}) + f_L(x, \bar{u}) \\ &\leq -\lambda_{1,R}(L, \bar{u}) \times \varepsilon\psi_R + \frac{\lambda_{1,R}(L, \bar{u})}{2} \times \varepsilon\psi_R < 0 \quad \text{in } (-R, R) \end{aligned} \quad (3.15)$$

for all $0 < \varepsilon \leq \varepsilon_0$. Furthermore, since \bar{u} is a stationary solution of equation (1.1), and since $v'_\varepsilon(x-) \geq v'_\varepsilon(x+)$ at $x = \pm R$, it follows that v_ε is a supersolution of equation (1.1).

Now, for any $k \in \mathbb{Z}$ and for any $0 < \varepsilon \leq \varepsilon_0$, the function $v_\varepsilon(\cdot - kL)$ is also a supersolution of (1.1). Since $v < \bar{u}$ in \mathbb{R} , it follows then from the strong elliptic maximum principle that, for every $0 < \varepsilon \leq \varepsilon_0$, there holds $v(x) < v_\varepsilon(x - kL)$ for all $x \in (kL - R, kL + R)$ and for all $k \in \mathbb{Z}$. Since $R > L/2$ and ψ_R is continuous and positive in $(-R, R)$, one infers that $\sup_{x \in \mathbb{R}} (v(x) - \bar{u}(x)) < 0$.

Step 2: $v \equiv 0$ in \mathbb{R} . Finally, let φ be a principal eigenfunction of the periodic problem (3.10), associated with the principal eigenvalue $\lambda_1(L, \bar{u})$. With calculations similar to the ones above, there is $\eta_0 > 0$ such that for all $0 < \eta \leq \eta_0$, the L -periodic function $\bar{u} - \eta\varphi$ satisfies $v < \bar{u} - \eta\varphi < \bar{u}$ and

$$(a_L(\bar{u} - \eta\varphi)_x)_x + f_L(x, \bar{u} - \eta\varphi) < 0 \quad \text{in } \mathbb{R}, \quad (3.16)$$

that is $\bar{u} - \eta\varphi$ is a strict supersolution of (1.1). As a consequence, the solution $u(t, x; \bar{u} - \eta_0\varphi)$ of (1.1) with initial condition $\bar{u} - \eta_0\varphi$ is decreasing in $t > 0$ and, from standard parabolic estimates, it converges as $t \rightarrow +\infty$ to an L -periodic steady state $u_\infty(x)$ of (1.1) such that $0 \leq v \leq u_\infty < \bar{u} - \eta_0\varphi < \bar{u} < 1$ in \mathbb{R} . If $u_\infty \not\equiv 0$ in \mathbb{R} , then $0 < u_\infty < 1$ from the strong maximum principle, whence u_∞ is unstable from Lemma 3.6, in the sense that $\lambda_1(L, u_\infty) > 0$. Therefore, as above, by calling ψ a principal periodic eigenfunction of the periodic problem (3.10) associated with u_∞ , it follows that the functions $u_\infty + \kappa\psi$ are subsolutions of (1.1) for all $\kappa > 0$ small enough. In particular, since $u_\infty < \bar{u} - \eta_0\varphi$ in \mathbb{R} and both functions are L -periodic and continuous, there is $\kappa_0 > 0$ such that $u_\infty + \kappa_0\psi$ is a subsolution of (1.1) and $u_\infty + \kappa_0\psi < \bar{u} - \eta_0\varphi$ in \mathbb{R} , whence $u_\infty + \kappa_0\psi < u(t, \cdot; \bar{u} - \eta_0\varphi)$ in \mathbb{R} for all $t > 0$, from the maximum principle. Finally, passing to the limit as $t \rightarrow +\infty$ gives $u_\infty + \kappa_0\psi \leq u_\infty$ in \mathbb{R} , which is impossible. Hence, $u_\infty \equiv 0$ and $v \equiv 0$ in \mathbb{R} , and the proof of Lemma 3.7 is complete. \square

As a consequence of Lemma 3.7, for every $0 < L < \tilde{L}_*$ and for every L -periodic steady state $0 < \bar{u} < 1$, equation (1.1) restricted to $E_1 = \{u \in C(\mathbb{R}, [0, 1]) \mid 0 \leq u \leq \bar{u} \text{ in } \mathbb{R}\}$, and to $E_2 = \{u \in C(\mathbb{R}, [0, 1]) \mid \bar{u} \leq u \leq 1 \text{ in } \mathbb{R}\}$ respectively, has a monostable structure. In order to prove the existence of pulsating fronts for (1.1), one will verify a counter-propagation condition on the spreading speeds of these subsystems, as defined in [22]. To do so, denote

$$\mathcal{C}^-(0, \bar{u}) = \left\{ u \in C(\mathbb{R}, [0, 1]) \mid 0 \leq u \leq \bar{u}, \limsup_{x \rightarrow +\infty} (u(x) - \bar{u}(x)) < 0 \text{ and } u(x) = \bar{u}(x) \text{ for } x \ll -1 \right\},$$

$$\mathcal{C}^+(\bar{u}, 1) = \left\{ u \in C(\mathbb{R}, [0, 1]) \mid \bar{u} \leq u \leq 1, \liminf_{x \rightarrow -\infty} (u(x) - \bar{u}(x)) > 0 \text{ and } u(x) = \bar{u}(x) \text{ for } x \gg 1 \right\}.$$

Lemma 3.8. *For every $0 < L < \tilde{L}_*$ and for every L -periodic steady state $0 < \bar{u} < 1$ of (1.1), there are some real numbers $c^+ > 0$ and $c^- > 0$ such that*

$$\begin{cases} \limsup_{t \rightarrow +\infty, x \geq -c^-t} u(t, x; u_0) = 0 & \text{for all } u_0 \in \mathcal{C}^-(0, \bar{u}), \\ \liminf_{t \rightarrow +\infty, x \leq c^+t} u(t, x; \tilde{u}_0) = 1 & \text{for all } \tilde{u}_0 \in \mathcal{C}^+(\bar{u}, 1). \end{cases} \quad (3.17)$$

Proof. We only give the proof of the first assertion (3.17), since the arguments for the other one are similar. First, one claims that for any $u_0 \in \mathcal{C}^-(0, \bar{u})$ and any constant $C \in \mathbb{R}$, there holds

$$\lim_{t \rightarrow +\infty} u(t, x; u_0) = 0 \quad \text{uniformly for } x \in [C, +\infty). \quad (3.18)$$

So, fix any $u_0 \in \mathcal{C}^-(0, \bar{u})$, any real number C , any $k_0 \in \mathbb{N}$ such that $C \geq -k_0L$, and let $\eta > 0$ be arbitrary. There are then $\varepsilon > 0$ small enough and $n_0 \in \mathbb{N}$ large enough such that $u_0(\cdot + nL) \leq v_\varepsilon$ for all $n \geq n_0$, $n \in \mathbb{N}$, where v_ε is defined in (3.14) and is a strict supersolution of (1.1), in the sense of (3.15). It follows from the parabolic maximum principle that $u(t, x; v_\varepsilon) < v_\varepsilon(x)$ and $u(t, x; v_\varepsilon)$ is decreasing in $t > 0$. By standard parabolic estimates, $u(t, x; v_\varepsilon)$ converges as $t \rightarrow +\infty$ locally uniformly in $x \in \mathbb{R}$ to a stationary solution $v_{\varepsilon, \infty}$ of equation (1.1) with $0 \leq v_{\varepsilon, \infty} < \bar{u}$. Lemma 3.7 and the strong elliptic maximum principle imply that $v_{\varepsilon, \infty} \equiv 0$. Therefore, there is $T > 0$ such that

$$0 \leq u(t, y; v_\varepsilon) \leq \eta \quad \text{for all } t \geq T \text{ and } |y| \leq (k_0 + n_0 + 1)L.$$

For any $x \geq C$ ($\geq -k_0L$), there is $l_x \in \mathbb{Z}$ such that $l_x \geq -k_0$ and $l_xL \leq x \leq (l_x + 1)L$. With $n_x = k_0 + n_0 + l_x \geq n_0$, one has $|x - n_xL| \leq |x - l_xL| + (k_0 + n_0)L \leq (k_0 + n_0 + 1)L$. Hence, from the maximum principle and the periodicity of (1.1), it follows that, for all $t \geq T$,

$$0 \leq u(t, x; u_0) = u(t, x - n_xL; u_0(\cdot + n_xL)) \leq u(t, x - n_xL; v_\varepsilon) \leq \eta.$$

The claim (3.18) is thereby proved.

Next, we fix a real number σ such that $0 < \sigma < \min_{\mathbb{R}} \bar{u}$ and a function $w_0 \in \mathcal{C}^-(0, \bar{u})$ such that $\sigma \leq w_0 \leq \bar{u}$ in \mathbb{R} and $w_0 = \sigma$ in \mathbb{R}^+ . From (3.18) applied to w_0 , and since $0 \leq u(t, x; w_0) \leq \bar{u}(x)$ for all $t \geq 0$ and $x \in \mathbb{R}$, there is a time $t_1 > 0$ such that $0 \leq u(t_1, x; w_0) \leq w_0(x + L)$ for all $x \in \mathbb{R}$. From the maximum principle, it follows by immediate induction that

$$0 \leq u(nt_1, x; w_0) \leq w_0(x + nL) \quad \text{for all } n \in \mathbb{N} \text{ and } x \in \mathbb{R}. \quad (3.19)$$

Finally, one shows that the first assertion in (3.17) holds with any positive constant c^- such that $0 < c^- < L/t_1$. Fix any function $u_0 \in \mathcal{C}^-(0, \bar{u})$. By (3.18) and $u(t, \cdot; u_0) \leq \bar{u}$, there is $T > 0$ such that $0 \leq u(T, \cdot; u_0) \leq w_0$, whence

$$0 \leq u(T + nt_1, x; u_0) \leq u(\tau t_1, x; w_0) \leq w_0(x + nL) \quad \text{for all } n \in \mathbb{N} \text{ and } x \in \mathbb{R} \quad (3.20)$$

by (3.19) and the maximum principle. Let us now argue by contradiction and assume that $\limsup_{t \rightarrow +\infty, x \geq -c^-t} u(t, x; u_0) > 0$. Then there are some sequences $(\tau_k)_{k \in \mathbb{N}}$ in $(0, +\infty)$ and $(x_k)_{k \in \mathbb{N}}$ in \mathbb{R} such that $x_k \geq -c^- \tau_k$ for all $k \in \mathbb{N}$, $\tau_k \rightarrow +\infty$ as $k \rightarrow +\infty$ and $\liminf_{k \rightarrow +\infty} u(\tau_k, x_k; u_0) > 0$. For k large enough, one can write $\tau_k = T + n_k t_1 + \tilde{\tau}_k$ with $n_k \in \mathbb{N}$, $0 \leq \tilde{\tau}_k \leq t_1$ and $n_k \rightarrow +\infty$ as $k \rightarrow +\infty$. Write also $x_k = x'_k + x''_k$ with $x'_k \in L\mathbb{Z}$ and $-L \leq x''_k \leq 0$. Up to extraction of a subsequence, one can assume that $\tilde{\tau}_k \rightarrow \tau \in \mathbb{R}$ and $x''_k \rightarrow y \in \mathbb{R}$ as $k \rightarrow +\infty$. For k large enough, denote $u_k(t, x) = u(t + \tau_k, x + x'_k; u_0)$ for $t \geq -\tau_k$ and $x \in \mathbb{R}$. From standard parabolic estimates, the functions u_k converge locally uniformly in \mathbb{R}^2 , up to extraction of a subsequence, to a solution $u_\infty(t, x)$ of (1.1)

defined for all $(t, x) \in \mathbb{R}^2$ and such that $0 \leq u_\infty(t, x) \leq \bar{u}(x)$ for all $(t, x) \in \mathbb{R}^2$, while $u_\infty(0, y) > 0$. Furthermore, for any given $m \in \mathbb{Z}$ and $x \in \mathbb{R}$, one has, for all k large enough,

$$0 \leq u_k(-mt_1 - \tilde{\tau}_k, x) = u(T + n_k t_1 - mt_1, x + x'_k; u_0) \leq w_0(x + x'_k + (n_k - m)L) \quad (3.21)$$

by (3.20). But $x'_k = x_k - x''_k \geq x_k \geq -c^- \tau_k \geq -c^-(T + n_k t_1 + t_1)$, whence $x'_k + n_k L \rightarrow +\infty$ as $k \rightarrow +\infty$ since $c^- < L/t_1$ and $n_k \rightarrow +\infty$. As a consequence, it follows from (3.21) and the definitions of u_∞ and w_0 that $0 \leq u_\infty(-mt_1 - \tau, x) \leq \sigma \leq w_0(x)$ for all $m \in \mathbb{Z}$ and $x \in \mathbb{R}$. One infers that $u_\infty \equiv 0$ in \mathbb{R}^2 . Indeed, for any $(t, x) \in \mathbb{R}^2$, one has, for all $m \in \mathbb{N}$ large enough,

$$0 \leq u_\infty(t, x) = u(t + mt_1 + \tau, x; u_\infty(-mt_1 - \tau, \cdot)) \leq u(t + mt_1 + \tau, x; w_0).$$

The property (3.18) applied with w_0 implies that $u(t + mt_1 + \tau, x; w_0) \rightarrow 0$ as $m \rightarrow +\infty$ whence $u_\infty(t, x) = 0$ for all $(t, x) \in \mathbb{R}^2$, which contradicts $u_\infty(0, y) > 0$. Therefore, the first assertion of (3.17) is shown and the proof of Lemma 3.8 is complete. \square

Based on the above preparations, one is ready to prove Theorem 1.4.

Proof of Theorem 1.4. Fix a period L such that $0 < L < \tilde{L}_*$. For any $t \geq 0$, define $Q_t : C(\mathbb{R}, [0, 1]) \rightarrow C(\mathbb{R}, [0, 1])$ by

$$Q_t[u_0] = u(t, \cdot; u_0). \quad (3.22)$$

By classical parabolic theory, together with Lemmas 3.6 and 3.8, the semiflow $(Q_t)_{t \geq 0}$ satisfies the following properties:

- (A1) (Periodicity) $T_y[Q_t[\varphi]] = Q_t[T_y[\varphi]]$ for all $\varphi \in C(\mathbb{R}, [0, 1])$, $t > 0$ and $y \in LZ$, where $T_y : C(\mathbb{R}, [0, 1]) \rightarrow C(\mathbb{R}, [0, 1])$ is the translation operator defined by $T_y[\psi] = \psi(\cdot - y)$.
- (A2) (Continuity) For any $t > 0$, Q_t is continuous with respect to the compact open topology.
- (A3) (Monotonicity) For any $t > 0$, Q_t is order preserving in the sense that $Q_t[\varphi_1] \geq Q_t[\varphi_2]$ whenever $\varphi_1 \geq \varphi_2$ in $C(\mathbb{R}, [0, 1])$.
- (A4) (Compactness) For any $t > 0$, Q_t is compact with respect to the compact open topology.
- (A5) (Bistability) Let \mathcal{C}_{per} be the set of L -periodic functions in $C(\mathbb{R}, [0, 1])$. For any $t > 0$, Q_t maps \mathcal{C}_{per} to itself and is strongly monotone on \mathcal{C}_{per} in the sense that $\inf_{x \in \mathbb{R}} (Q_t[\varphi_1](x) - Q_t[\varphi_2](x)) > 0$ whenever $\varphi_1 \geq \varphi_2$ in \mathcal{C}_{per} with $\varphi_1 \not\equiv \varphi_2$. Furthermore, the constant functions 0 and 1 ($\in \mathcal{C}_{per}$) are stationary solutions of (1.1) and they are strongly stable from above and below, respectively, in the sense of [22], namely, there is $\varepsilon_0 > 0$ such that $\sup_{x \in \mathbb{R}} (Q_t[\varepsilon](x) - \varepsilon) < 0$ and $\inf_{x \in \mathbb{R}} (Q_t[1 - \varepsilon](x) - (1 - \varepsilon)) > 0$ for all $0 < \varepsilon \leq \varepsilon_0$ and any $t > 0$, which follows from the assumption (1.3). Lastly, any stationary solution $0 < \bar{u} < 1$ in \mathcal{C}_{per} is strongly unstable from above and below in the sense of [22], since there is $\varepsilon_0 > 0$ such that $\inf_{x \in \mathbb{R}} (Q_t[\bar{u} + \varepsilon\varphi](x) - (\bar{u}(x) + \varepsilon\varphi(x))) > 0$ and $\sup_{x \in \mathbb{R}} (Q_t[\bar{u} - \varepsilon\varphi](x) - (\bar{u}(x) - \varepsilon\varphi(x))) < 0$ in \mathbb{R} for all $0 < \varepsilon \leq \varepsilon_0$ and any $t > 0$, where φ denotes the periodic principal eigenfunction of (3.10) with $\lambda = \lambda_1(L, \bar{u}) > 0$. Indeed, for every $t > 0$, the inequalities $Q_t[\bar{u} + \varepsilon\varphi] > \bar{u} + \varepsilon\varphi$ and $Q_t[\bar{u} - \varepsilon\varphi] < \bar{u} - \varepsilon\varphi$ in \mathbb{R} for all $0 < \varepsilon \leq \varepsilon_0$ follow from the fact that the L -periodic functions $\bar{u} + \varepsilon\varphi$ and $\bar{u} - \varepsilon\varphi$ are respectively strict sub- and supersolutions of the elliptic equation associated with (1.1), which can be verified by calculations similar to (3.16).
- (A6) (Counter-propagation) For each stationary solution $\bar{u} \in \mathcal{C}_{per}$ with $0 < \bar{u} < 1$, one has $c_*^-(0, \bar{u}) + c_*^+(\bar{u}, 1) > 0$, where $c_*^-(0, \bar{u})$ and $c_*^+(\bar{u}, 1)$ are the spreading speeds defined by

$$c_*^-(0, \bar{u}) = \sup \left\{ c \in \mathbb{R} \mid \limsup_{t \rightarrow +\infty, x \geq -ct} u(t, x; u_0) = 0 \text{ for all } u_0 \in \mathcal{C}^-(0, \bar{u}) \right\},$$

$$c_*^+(\bar{u}, 1) = \sup \left\{ c \in \mathbb{R} \mid \liminf_{t \rightarrow +\infty, x \leq ct} u(t, x; \tilde{u}_0) = 1 \text{ for all } \tilde{u}_0 \in \mathcal{C}^+(\bar{u}, 1) \right\}.$$

Indeed, Lemma 3.8 implies that $c_*^-(0, \bar{u}) \geq c^- > 0$ and $c_*^+(\bar{u}, 1) \geq c^+ > 0$, with the notations of Lemma 3.8. Following [22], $c_*^-(0, \bar{u})$ is called the leftward spreading speed of equation (1.1) on $\mathcal{C}^-(0, \bar{u})$, and $c_*^+(\bar{u}, 1)$ the rightward spreading speed of equation (1.1) on $\mathcal{C}^+(\bar{u}, 1)$ (Lemma 3.8 is then stronger than the counter-propagation condition given in [22], which is just defined as the positivity of the sum of these spreading speeds).

Having in hand the properties (A1)-(A6), we then see from [22, Proposition 3.1, Theorems 3.4 and 4.1, and Remark 4.1] that for any $0 < L < \tilde{L}_*$, equation (1.1) admits a pulsating front $u_L(t, x) = \phi_L(x - c_L t, x/L)$ with speed $c_L \in \mathbb{R}$ such that $\phi_L(\xi, x)$ is nonincreasing in ξ .

Lastly, the assumption (1.12) yields the existence (and uniqueness) of a front (ϕ_0, c_0) for the homogenized equation (1.9). If $c_0 \neq 0$, then Theorem 1.2 implies that the speeds c_L of the pulsating fronts given in the previous paragraph, which exist for all $0 < L < \tilde{L}_*$, are such that $c_L \rightarrow c_0$ as $L \rightarrow 0^+$. On the other hand, if $c_0 = 0$, then $\int_0^1 \bar{f}(u) du = 0$ and Lemma 2.2 implies that $c_L = 0$ for all $0 < L < \tilde{L}_*$. Hence, the proof of Theorem 1.4 is complete. \square

3.3 The case of large periods L

This section is devoted to the proof of Theorem 1.5. That is, under the assumption (1.13), we show that the equation (1.1), for any period $L > 0$ large enough, admits a pulsating front with positive speed. Firstly, as for the proof of Theorem 1.4, we will show that for L large enough, any L -periodic intermediate steady state $0 < \bar{u} < 1$ of (1.1) is unstable and, applying the abstract results in [22], we will then obtain the existence of a pulsating front with nonnegative speed. To complete the proof, we need to exclude the case of pulsating fronts with zero speed (stationary fronts), at least for L large enough. This proof, as well as that of the instability of the intermediate steady states of equation (1.1), will use a passage to the limit as $L \rightarrow +\infty$ and the properties of the solutions to

$$a(y)(u^y)''(x) + f^y(u^y(x)) = 0 \quad \text{and} \quad 0 < u^y(x) < 1 \quad \text{for all } x \in \mathbb{R}, \quad (3.23)$$

where y is any real number and $f^y(u) = f(y, u)$.

We first begin with the instability of all intermediate steady states of equation (1.1) at large L .

Lemma 3.9. *Under the assumption (1.13), there is $L^* > 0$ such that $\lambda_1(L, \bar{u}) > 0$ for every $L > L^*$ and for every L -periodic steady state \bar{u} of (1.1) with $0 < \bar{u} < 1$, where $\lambda_1(L, \bar{u})$ is the principal eigenvalue defined in (3.10).*

Proof. Assume by contradiction that there are some sequences $(L_n)_{n \in \mathbb{N}}$ in $(0, +\infty)$, $(\bar{u}_n)_{n \in \mathbb{N}}$ and $(\psi_n)_{n \in \mathbb{N}}$ in $C^2(\mathbb{R})$ such that $L_n \rightarrow +\infty$ as $n \rightarrow +\infty$ and, for each $n \in \mathbb{N}$, \bar{u}_n and ψ_n satisfy (3.11) and (3.12) with principal eigenvalue $\lambda_1(L_n, \bar{u}_n) \leq 0$. By (3.13), one can assume that, up to extraction of some subsequence, $\lambda_1(L_n, \bar{u}_n) \rightarrow \lambda_1 \in (-\infty, 0]$ as $n \rightarrow +\infty$.

One first observes from the assumption (1.2) that, for any $n \in \mathbb{N}$, there is $x_n \in [0, L_n]$ such that $\bar{u}_n(x_n) = \theta_{x_n/L_n}$. Otherwise, by continuity and L_n -periodicity of \bar{u}_n , one would have either $\theta_{x/L_n} < \bar{u}_n(x) < 1$ for all $x \in \mathbb{R}$ or $0 < \bar{u}_n(x) < \theta_{x/L_n}$ for all $x \in \mathbb{R}$ (notice also that, by (1.2) and (1.3), the function $x \mapsto \theta_x$ is continuous), whence the function $(a_{L_n} \bar{u}_n')'$ would have a fixed strict sign; this last property would contradict the fact that $a_{L_n} \bar{u}_n'$ is an L_n -periodic function.

Define now $p_n(x) = \bar{u}_n(x + x_n)$ for $x \in \mathbb{R}$ and $n \in \mathbb{N}$. Each function p_n is a solution to $(a_{L_n}(x + x_n)p_n')' + f_{L_n}(x + x_n, p_n) = 0$ in \mathbb{R} with $p_n(0) = \theta_{x_n/L_n}$ and $0 < p_n < 1$ in \mathbb{R} . Up to extraction of some subsequence, one can assume that $x_n/L_n \rightarrow x_\infty \in [0, 1]$ as $n \rightarrow +\infty$ and that, from standard elliptic estimates, there is a $C^2(\mathbb{R})$ function $0 \leq p_\infty \leq 1$ such that $p_n \rightarrow p_\infty$ in $C_{loc}^2(\mathbb{R})$ as $n \rightarrow +\infty$. Moreover, p_∞ solves

$$a(x_\infty)p_\infty'' + f(x_\infty, p_\infty) = 0 \quad \text{in } \mathbb{R}, \quad p_\infty(0) = \theta_{x_\infty} \quad \text{and} \quad 0 < p_\infty < 1 \quad \text{in } \mathbb{R}, \quad (3.24)$$

the strict inequalities following from the strong maximum principle. Similarly, by normalizing ψ_n in such a way that $\psi_n(x_n) = 1$, there is a nonnegative $C^2(\mathbb{R})$ function ψ_∞ such that, up to extraction of some subsequence, $\psi_n(\cdot + x_n) \rightarrow \psi_\infty$ in $C_{loc}^2(\mathbb{R})$ as $n \rightarrow +\infty$, and ψ_∞ solves

$$a(x_\infty)\psi_\infty'' + \partial_u f(x_\infty, p_\infty)\psi_\infty = \tilde{\lambda}_1\psi_\infty \text{ in } \mathbb{R}, \quad \psi_\infty(0) = 1 \text{ and } \psi_\infty > 0 \text{ in } \mathbb{R} \quad (3.25)$$

(notice here that the function ψ_∞ may not be bounded or periodic, since the convergence is only local as $L_n \rightarrow +\infty$).

By (1.2) and (1.13), according to phase diagrams of equation (3.24), the solution p_∞ can only be of one of the following three types: either a constant function, or a non-constant periodic function, or a ground state solution such that $p_\infty(\pm\infty) = 0$.⁴ In what follows, one will get a contradiction in each of these three cases.

Case 1: p_∞ is a constant solution, that is $p_\infty \equiv \theta_{x_\infty}$ in \mathbb{R} . In this case, ψ_∞ obeys the linear equation $\psi_\infty'' + \beta\psi_\infty = 0$ in \mathbb{R} with $\beta = (\partial_u f(x_\infty, \theta_\infty) - \tilde{\lambda}_1)/a(x_\infty)$. Since $\partial_u f(x_\infty, \theta_\infty) > 0$ and $\tilde{\lambda}_1 \leq 0$, it follows that $\beta > 0$ and that the positive function ψ_∞ is strictly concave in \mathbb{R} , which is impossible. Hence, Case 1 is ruled out.

Case 2: p_∞ is a non-constant \tilde{L} -periodic solution with $\tilde{L} > 0$. In this case, p_∞' is a non-signed \tilde{L} -periodic function satisfying

$$a(x_\infty)(p_\infty')'' + \partial_u f(x_\infty, p_\infty)p_\infty' = 0 \text{ in } \mathbb{R}, \quad (3.26)$$

whereas ψ_∞ solves $a(x_\infty)\psi_\infty'' + (\partial_u f(x_\infty, p_\infty) - \tilde{\lambda}_1)\psi_\infty = 0$ in \mathbb{R} . Since $\tilde{\lambda}_1 \leq 0$, it follows from Sturm comparison theorem that ψ_∞ must vanish somewhere, which is impossible since $\psi_\infty > 0$ in \mathbb{R} . Hence, Case 2 is ruled out too.

Case 3: p_∞ is a non-periodic solution and $\lim_{x \rightarrow \pm\infty} p_\infty(x) = 0$. Denote $F(s) = \int_0^s f(x_\infty, u)du$ for all $s \in [0, 1]$. From the assumptions (1.2) and $\int_0^1 f(x_\infty, u)du > 0$, there is a real number $\bar{s} \in (\theta_{x_\infty}, 1)$ such that $F(0) = F(\bar{s}) = 0$, $F(s) < 0$ for all $0 < s < \bar{s}$ and $F(s) > 0$ for all $\bar{s} < s \leq 1$. It then follows that there is $\bar{x} \in \mathbb{R}$ such that $p_\infty(\bar{x}) = \bar{s}$, $p_\infty'(\bar{x}) = 0$, $p_\infty' > 0$ in $(-\infty, \bar{x})$ and $p_\infty' < 0$ in $(\bar{x}, +\infty)$. Notice also by (1.2) that

$$p_\infty''(\bar{x}) = -\frac{f(x_\infty, p_\infty(\bar{x}))}{a(x_\infty)} = -\frac{f(x_\infty, \bar{s})}{a(x_\infty)} < 0$$

and that there is $\underline{x} < \bar{x}$ such that $p_\infty''(x) = -f(x_\infty, p_\infty(x))/a(x_\infty) > 0$ for all $x \leq \underline{x}$. Furthermore, $\lim_{x \rightarrow -\infty} p_\infty''(x) = \lim_{x \rightarrow -\infty} p_\infty'(x) = 0$. Denote $q(x) = \psi_\infty'(x)p_\infty'(x) - \psi_\infty(x)p_\infty''(x)$ for $x \in \mathbb{R}$. It follows from (3.25) and (3.26) that $q'(x) = \tilde{\lambda}_1\psi_\infty(x)p_\infty'(x)/a(x_\infty) \leq 0$ for all $x \leq \bar{x}$, whence

$$q(x) \geq q(\bar{x}) = -\psi_\infty(\bar{x})p_\infty''(\bar{x}) > 0 \text{ for all } x \leq \bar{x}. \quad (3.27)$$

Therefore, $\psi_\infty'(x)p_\infty'(x) \geq \psi_\infty(x)p_\infty''(x) > 0$ for all $x \leq \underline{x} (< \bar{x})$. In particular, $\psi_\infty'(x) > 0$ for all $x \leq \underline{x}$ and, since ψ_∞ is positive, the limit $\psi_\infty(-\infty) \in [0, +\infty)$ exists. By (3.25), the function ψ_∞'' has a finite limit as $x \rightarrow -\infty$ and it follows then from elementary arguments that $\psi_\infty'(x) \rightarrow 0$ as $x \rightarrow -\infty$. Lastly, since $p_\infty'(-\infty) = p_\infty''(-\infty) = 0$, one gets that $q(x) \rightarrow 0$ as $x \rightarrow -\infty$, which contradicts (3.27). As a consequence, Case 3 is ruled out too and the proof of Lemma 3.9 is complete. \square

⁴As a matter of fact, let $p(x) = p_\infty(x)$ and $q(x) = p_\infty'(x)$ for all $x \in \mathbb{R}$. Then finding solutions of (3.24) is equivalent to finding trajectories (p, q) to the system $p' = q$, $a(x_\infty)q^2 + 2\int_{\theta_{x_\infty}}^p f(x_\infty, s)ds = C$ for some constant $C = a(x_\infty)q(0)^2 \geq 0$ with $0 < p < 1$ (see, e.g. [4, 23]). Furthermore, if $C = 0$, then the trajectory (p, q) is a single point $(\theta_{x_\infty}, 0)$ in the pq -phase; if $0 < C < 2\int_{\theta_{x_\infty}}^0 f(x_\infty, s)ds = 2\int_0^{\theta_{x_\infty}} |f(x_\infty, s)|ds$, then the trajectory (p, q) is a smooth closed curve; if $C = 2\int_{\theta_{x_\infty}}^0 f(x_\infty, s)ds$, then the trajectory (p, q) is a smooth curve connecting from $(0, 0)$ to $(0, 0)$ but not including $(0, 0)$; while if $C > 2\int_{\theta_{x_\infty}}^0 f(x_\infty, s)ds$, then such a trajectory does not exist.

Proof of Theorem 1.5. For any fixed $L > L^*$, consider the semiflow $(Q_t)_{t \geq 0}$ generated by (3.22) with the period L , that is, by the equation (1.1) with L -periodic coefficients. The properties (A1)-(A4) used in the proof of Theorem 1.4 are easily verified. Because of Lemma 3.9, $(Q_t)_{t \geq 0}$ satisfies the bistability condition (A5) and the same analysis as that in Lemma 3.8 implies that $(Q_t)_{t \geq 0}$ satisfies the counter-propagation property (A6). Thus, it follows from [22] that for any $L > L^*$, equation (1.1) admits a pulsating front $u_L(t, x) = \phi_L(x - c_L t, x/L)$ with speed c_L . Furthermore, assumption (1.13) and Lemma 2.2 imply that $c_L \geq 0$. To end the proof, even if it means redefining L^* , one needs to show that $c_L > 0$ for all $L > L^*$ (large enough).

Assume by contraction that there is a sequence $(L_n)_{n \in \mathbb{N}}$ in $(L^*, +\infty)$ converging to $+\infty$ and such that $c_{L_n} = 0$ for all $n \in \mathbb{N}$. Namely, for each $n \in \mathbb{N}$, there is a $C^2(\mathbb{R})$ solution ϕ_n of

$$(a_{L_n} \phi_n')' + f_{L_n}(x, \phi_n) = 0 \text{ in } \mathbb{R}, \quad \phi_n(-\infty) = 1, \quad \phi_n(+\infty) = 0 \quad \text{and} \quad 0 < \phi_n < 1 \text{ in } \mathbb{R}. \quad (3.28)$$

Since $\int_0^1 f(x, u) du > 0$ for all $x \in \mathbb{R}$ and f is bounded in $\mathbb{R} \times [0, 1]$, there is $\tau \in \mathbb{R}$ such that

$$1 - \delta < \tau < 1 \quad \text{and} \quad \int_0^s f(x, u) du > 0 \text{ for all } x \in \mathbb{R} \text{ and } s \in [\tau, 1], \quad (3.29)$$

where $\delta > 0$ is the constant in (1.3). For every $n \in \mathbb{N}$, there is $y_n \in \mathbb{R}$ such that $\phi_n(y_n) = \tau$. Write $y_n = y_n' + \tilde{y}_n$, with $y_n' \in L_n \mathbb{Z}$ and $\tilde{y}_n \in [0, L_n]$, and set $v_n(x) = \phi_n(x + y_n)$ for $x \in \mathbb{R}$ and $n \in \mathbb{N}$. Since both a_{L_n} and f_{L_n} are L_n -periodic in x , each function v_n obeys

$$\begin{cases} (a_{L_n}(x + \tilde{y}_n)v_n')' + f_{L_n}(x + \tilde{y}_n, v_n) = 0 \text{ in } \mathbb{R}, \\ v_n(0) = \tau, \quad v_n(-\infty) = 1, \quad v_n(+\infty) = 0 \quad \text{and} \quad 0 < v_n < 1 \text{ in } \mathbb{R}. \end{cases}$$

Up to extraction of some subsequence, one can assume that $\tilde{y}_n/L_n \rightarrow y_\infty \in [0, 1]$ as $n \rightarrow +\infty$ and that, from standard elliptic estimates, $v_n \rightarrow v_\infty$ as $n \rightarrow +\infty$ in $C_{loc}^2(\mathbb{R})$, where the function $0 \leq v_\infty \leq 1$ solves

$$a(y_\infty)v_\infty'' + f(y_\infty, v_\infty) = 0 \text{ in } \mathbb{R} \quad (3.30)$$

and $v_\infty(0) = \tau$, whence $0 < v_\infty < 1$ in \mathbb{R} from the strong elliptic maximum principle. As for equation (3.24) used in Lemma 3.9, it follows from (1.13) that there are three types of solutions to equation (3.30): the constant solutions (equal to θ_{y_∞}), the non-constant periodic solutions and the non-periodic ground state solutions converging to 0 at $\pm\infty$. In all cases, by multiplying the equation (3.30) by v_∞' and integrating on suitable intervals, it follows easily that $\int_{\underline{s}}^{\bar{s}} f(y_\infty, u) du = 0$, where $0 \leq \inf_{\mathbb{R}} v_\infty = \underline{s} \leq \bar{s} = \max_{\mathbb{R}} v_\infty < 1$. It follows then from (1.2) and (3.30) that $\underline{s} \leq \theta_{y_\infty} \leq \bar{s}$ and that $\int_0^s f(y_\infty, u) du \leq 0$ for all $0 \leq s \leq \bar{s}$. In particular, since $v_\infty(0) = \tau \in [0, \bar{s}]$, one gets $\int_0^\tau f(y_\infty, u) du \leq 0$. One has then reached a contradiction with (3.29) and the proof of Theorem 1.5 is thereby complete. \square

4 The set E of periods L for which (1.1) admits pulsating fronts with nonzero speed

This section is devoted to the proof of Theorem 1.8 and further results (see Theorem 4.3 below) on the set E of periods L for which pulsating fronts with nonzero speed exist. Theorem 1.8 is similar to Theorem 1.2 in the sense that they are both concerned with the existence and convergence of pulsating fronts as L converges to a fixed $L_0 \geq 0$, given that (1.1) when $L_0 > 0$ (resp. (1.9) when $L_0 = 0$) admits a non-stationary pulsating front. Namely, to prove Theorem 1.8, we apply the implicit function theorem for some suitable function space as in Theorem 1.2, and the arguments are actually simpler since no singularity occurs when L converges to $L_0 > 0$. In Section 4.2, we prove further existence results at a point $L \in \partial E \cap (0, +\infty)$.

4.1 Proof of Theorem 1.8

Throughout the proof, we assume that equation (1.1) with $L = L_0 > 0$ admits a pulsating front

$$U(t, x) = \phi_{L_0}(x - c_{L_0}t, x/L_0)$$

with a nonzero speed c_{L_0} . From parabolic regularity applied to the equations satisfied by u and u_t , the function u is of class C^2 in \mathbb{R}^2 and so is the function ϕ_{L_0} . As in the proof of Theorem 1.2, one can assume without loss of generality that $(\phi_{L_0}(\xi, y), c_{L_0})$ solves (2.4) with $c_{L_0} > 0$.

We use here the same notations \mathcal{D}_L , \mathbb{T} , $L^2(\mathbb{R} \times \mathbb{T})$ and $H^1(\mathbb{R} \times \mathbb{T})$ as in Section 3.1. A positive real number $\beta > 0$ is given. For any $c > 0$ and $L > 0$, the linear operator $M_{c,L} : \mathcal{D}_L \mapsto L^2(\mathbb{R} \times \mathbb{T})$ defined in (3.2) is invertible by Lemma 3.1. Now for $v \in H^1(\mathbb{R} \times \mathbb{T})$, $c > 0$ and $L > 0$, we define $K(v, c, L) = f(y, v + \phi_{L_0}) + \beta v + \tilde{\partial}_L(a\tilde{\partial}_L\phi_{L_0}) + c\partial_\xi\phi_{L_0}$, where $\tilde{\partial}_L = \partial_\xi + L^{-1}\partial_y$, and

$$\tilde{G}(v, c, L) = \left(v + M_{c,L}^{-1}(K(v, c, L)), \int_{\mathbb{R} \times \mathbb{T}} (\phi_{L_0}(\xi, y) + v(\xi, y))^2 - \phi_{L_0}^2(\xi, y) \right).$$

Note that $\tilde{G}(0, c_{L_0}, L_0) = (0, 0)$. Moreover, as done in the proof of Theorem 1.2 and using also parabolic regularity, a pair $(\phi_L, c_L) \in (\phi_{L_0} + H^1(\mathbb{R} \times \mathbb{T})) \times (0, +\infty)$ solves (2.4) for $L \neq 0$ with the normalization $\int_{\mathbb{R} \times \mathbb{T}} \phi_L^2 = \int_{\mathbb{R} \times \mathbb{T}} \phi_{L_0}^2$ if and only if $\tilde{G}(\phi_L - \phi_{L_0}, c_L, L) = (0, 0)$. On the other hand, using Lemma 3.3 and similar arguments as in the proof of Lemma 3.4, it follows that, in $H^1(\mathbb{R} \times \mathbb{T}) \times (0, +\infty) \times (0, +\infty)$, the function \tilde{G} is continuous with respect to (v, c, L) and continuously differentiable with respect to (v, c) with derivative given by

$$\begin{aligned} & \partial_{(v,c)}\tilde{G}(v, c, L)(\tilde{v}, \tilde{c}) \\ &= \left(\tilde{v} + M_{c,L}^{-1}((\partial_u f(y, v + \phi_{L_0}) + \beta)\tilde{v}) - \tilde{c}M_{c,L}^{-1}(\partial_\xi(M_{c,L}^{-1}(K(v, c, L)) - \phi_{L_0})), 2 \int_{\mathbb{R} \times \mathbb{T}} (\phi_{L_0} + v)\tilde{v} \right) \end{aligned}$$

for all $(\tilde{v}, \tilde{c}) \in H^1(\mathbb{R} \times \mathbb{T}) \times \mathbb{R}$. In particular, $\tilde{Q} := \partial_{(v,c)}\tilde{G}(0, c_{L_0}, L_0)$ is given by

$$\tilde{Q}(\tilde{v}, \tilde{c}) = \left(\tilde{v} + M_{c_{L_0}, L_0}^{-1}((\partial_u f(y, \phi_{L_0}) + \beta)\tilde{v}) + \tilde{c}M_{c_{L_0}, L_0}^{-1}(\partial_\xi\phi_{L_0}), 2 \int_{\mathbb{R} \times \mathbb{T}} \phi_{L_0}\tilde{v} \right).$$

Now, in order to apply the implicit function theorem for \tilde{G} around the point $(0, c_{L_0}, L_0)$, one needs to show that the operator \tilde{Q} is invertible as a map from $H^1(\mathbb{R} \times \mathbb{T}) \times \mathbb{R}$ to itself. The method used in Lemma 3.4 can be adapted to prove this property under the condition that the linearization of equation (2.4) at (ϕ_{L_0}, c_{L_0}) satisfies properties similar to the ones of the operators H and H^* given by (3.8). More precisely, let

$$H_{L_0}(u) = \tilde{\partial}_{L_0}(a\tilde{\partial}_{L_0}u) + c_{L_0}\partial_\xi u + \partial_u f(y, \phi_{L_0})u \quad \text{for } u \in \mathcal{D}_{L_0} \quad (4.1)$$

and let the adjoint operator $H_{L_0}^*$ be defined by $H_{L_0}^*(u) = \tilde{\partial}_{L_0}(a\tilde{\partial}_{L_0}u) - c_{L_0}\partial_\xi u + \partial_u f(y, \phi_{L_0})u$ for $u \in \mathcal{D}_{L_0}$. Let us now work with complex valued functions. Namely, for $u = v + iw$ with $v, w \in \mathcal{D}_{L_0}$ and $i^2 = -1$, we set $H_{L_0}(u) = H_{L_0}(v) + iH_{L_0}(w)$ and similarly for $H_{L_0}^*(u)$. One has $\langle H_{L_0}^*(v), u \rangle_{L^2(\mathbb{R} \times \mathbb{T}, \mathbb{C})} = \langle v, H_{L_0}(u) \rangle_{L^2(\mathbb{R} \times \mathbb{T}, \mathbb{C})}$ for all $u, v \in \mathcal{D}_{L_0} + i\mathcal{D}_{L_0}$, with $\langle w, z \rangle_{L^2(\mathbb{R} \times \mathbb{T}, \mathbb{C})} = \int_{\mathbb{R} \times \mathbb{T}} w\bar{z}$ for $w, z \in L^2(\mathbb{R} \times \mathbb{T}, \mathbb{C})$.

Lemma 4.1. *The operators H_{L_0} and $H_{L_0}^*$ have algebraically simple eigenvalue 0 and the range of H_{L_0} is closed in $L^2(\mathbb{R} \times \mathbb{T}, \mathbb{C})$. Furthermore, if $\lambda \in \mathbb{C}^*$ is an eigenvalue of H_{L_0} , then $\text{Re}(\lambda) < 0$.*

Notice that H_{L_0} and $H_{L_0}^*$ are not elliptic operators in the variables (ξ, y) , but by the change of variable defined in (2.3) they are equivalent to standard parabolic operators in the variables (t, x) and the parabolic theory helps overcome this degeneracy. As a matter of fact, the simplicity of the eigenvalue 0 is highly dependent on the following maximum principle for H_{L_0} (similar results can be obtained for $H_{L_0}^*$).

Lemma 4.2. *Let ϕ be a $C^2(\mathbb{R} \times \mathbb{T}, \mathbb{R})$ solution of $H_{L_0}(\phi) \leq 0$ on $\mathbb{R} \times \mathbb{T}$ with $\phi \geq 0$ in $\mathbb{R} \times \mathbb{T}$. Then either $\phi \equiv 0$ in $\mathbb{R} \times \mathbb{T}$, or $\phi(\xi, y) > 0$ for all $(\xi, y) \in \mathbb{R} \times \mathbb{T}$.*

Proof. This conclusion follows from the strong parabolic maximum principle applied to the function $u(t, x) = \phi(x - c_{L_0}t, x/L_0)$ and from the periodicity of $\phi(\xi, y)$ in the y -variable (see also Proposition 3.1 of [53]). \square

Now one is ready to prove Lemma 4.1. Note that similar conclusions were obtained in [51] for the linearized operator of an equation with combustion nonlinearity. Special weighted spaces (requiring functions to decay to zero at a certain exponential rate as $|x| \rightarrow \infty$) are introduced in that paper, whereas they are not needed here due to the bistable assumption (1.3). The strategy for the proof of Lemma 4.1 is actually a little bit different from that used in Section 2 of [51].

Proof of Lemma 4.1. We proceed with five steps.

Step 1: 0 is a geometrically simple eigenvalue of H_{L_0} in $\mathcal{D}_{L_0} + i\mathcal{D}_{L_0}$. First, by parabolic regularity, the time-derivative U_t of the function $U(t, x) = \phi_{L_0}(x - c_{L_0}t, x/L_0)$ is of class $C^{1,2}(\mathbb{R}^2)$. Thus, one can differentiate the equation (2.4) (with $L = L_0$) satisfied by ϕ_{L_0} with respect to ξ . More precisely, the function $\partial_\xi \phi_{L_0}$ satisfies

$$\tilde{\partial}_{L_0}(a(y)\tilde{\partial}_{L_0}(\partial_\xi \phi_{L_0})) + c_{L_0}\partial_\xi(\partial_\xi \phi_{L_0}) + \partial_u f(y, \phi_{L_0})\partial_\xi \phi_{L_0} = 0 \quad \text{for all } (\xi, y) \in \mathbb{R} \times \mathbb{T},$$

where $\partial_\xi \phi_{L_0}(\xi, y) = -c_{L_0}^{-1}U_t((L_0y - \xi)/c_{L_0}, L_0y)$, $\tilde{\partial}_{L_0}(\partial_\xi \phi_{L_0})(\xi, y) = -c_{L_0}^{-1}U_{tx}((L_0y - \xi)/c_{L_0}, L_0y)$, $\partial_\xi(\partial_\xi \phi_{L_0})(\xi, y) = c_{L_0}^{-2}U_{tt}((L_0y - \xi)/c_{L_0}, L_0y)$ and

$$\tilde{\partial}_{L_0}(a(y)\tilde{\partial}_{L_0}(\partial_\xi \phi_{L_0}))(\xi, y) = -\frac{a(y)}{c_{L_0}}U_{txx}\left(\frac{L_0y - \xi}{c_{L_0}}, L_0y\right) - \frac{a'(y)}{L_0c_{L_0}}U_{tx}\left(\frac{L_0y - \xi}{c_{L_0}}, L_0y\right).$$

Therefore, it follows from Lemma 2.1 that $\partial_\xi \phi_{L_0} \in \mathcal{D}_{L_0}$. On the other hand, Theorem 1.1 and the strong parabolic maximum principle imply that $U_t > 0$ in \mathbb{R}^2 , whence $\partial_\xi \phi_{L_0}$ is a negative eigenfunction of H_{L_0} for the eigenvalue 0.

Next, suppose that $v \in \mathcal{D}_{L_0} + i\mathcal{D}_{L_0}$ satisfies $H_{L_0}(v) = 0$ and $v \not\equiv 0$. Without loss of generality, one can assume that v is real valued. By rewriting the equation $H_{L_0}(v) = 0$ in its weak form in the variables (t, x) , it follows from parabolic regularity theory and bootstrap arguments that v is of class $C^2(\mathbb{R}^2)$ and is a bounded classical solution of $H_{L_0}(v) = 0$ such that $v(\pm\infty, \cdot) = 0$ uniformly in \mathbb{T} . For any $\mu \in \mathbb{R}$ and $(\xi, y) \in \mathbb{R} \times \mathbb{T}$, let

$$w_\mu(\xi, y) = v(\xi, y) - \mu \partial_\xi \phi_{L_0}(\xi, y).$$

Each w_μ is a classical solution of $H_{L_0}(w_\mu) = \tilde{\partial}_{L_0}(a(y)\tilde{\partial}_{L_0}w_\mu) + c_{L_0}\partial_\xi w_\mu + \partial_u f(y, \phi_{L_0})w_\mu = 0$ in $\mathbb{R} \times \mathbb{T}$ with $w_\mu(\pm\infty, \cdot) = 0$ uniformly in \mathbb{T} . One sees from (1.3) and the uniform continuity of $\partial_u f$ in $\mathbb{R} \times [0, 1]$ that there is $N > 0$ large enough such that

$$\partial_u f(y, \phi_{L_0}(\xi, y)) \leq -\frac{\gamma}{2} < 0 \quad \text{for all } |\xi| \geq N \text{ and } y \in \mathbb{T}. \quad (4.2)$$

Since $\partial_\xi \phi_{L_0}$ is negative and continuous in $\mathbb{R} \times \mathbb{T}$, it follows that, for this chosen N , there exists $\mu_0 > 0$ such that $w_\mu > 0$ in $[-N, N] \times \mathbb{T}$ for all $\mu \geq \mu_0$. We claim that, for such μ , $w_\mu(\xi, y) > 0$ for all

$(\xi, y) \in \mathbb{R} \times \mathbb{T}$. Indeed, otherwise, w_μ achieves a nonpositive minimum at a point $(\xi_0, y_0) \in \mathbb{R} \times \mathbb{T}$ such that $|\xi_0| > N$. If $w_\mu(\xi_0, y_0) < 0$, then evaluating all terms of $H_{L_0}(w_\mu)$ at (ξ_0, y_0) yields

$$\begin{aligned} \tilde{\partial}_{L_0}(a\tilde{\partial}_{L_0}w_\mu)(\xi_0, y_0) + c_{L_0}\partial_\xi w_\mu(\xi_0, y_0) + \partial_u f(y, \phi_{L_0}(\xi_0, y_0))w_\mu(\xi_0, y_0) &\geq \partial_u f(y, \phi_{L_0}(\xi_0, y_0))w_\mu(\xi_0, y_0) \\ &\geq -\frac{\gamma}{2}w_\mu(\xi_0, y_0) > 0, \end{aligned}$$

which contradicts the equation $H_{L_0}(w_\mu) = 0$ in $\mathbb{R} \times \mathbb{T}$ (notice here that $H_{L_0}(w_\mu) \leq 0$ would have been sufficient to conclude, that is $H_{L_0}(v) \leq 0$ would have been sufficient). If $w_\mu(\xi_0, y_0) = 0$, then strong maximum principle in Lemma 4.2 shows that $w_\mu \equiv 0$, which is also impossible. Thus, one gets that $w_\mu > 0$ in $\mathbb{R} \times \mathbb{T}$.

Now define $\nu = \inf \{ \mu \in \mathbb{R} \mid w_\mu = v - \mu\partial_\xi\phi_{L_0} \geq 0 \text{ in } \mathbb{R} \times \mathbb{T} \}$. Obviously, $-\infty < \nu \leq \mu_0$ and $w_\nu = v - \nu\partial_\xi\phi_{L_0} \geq 0$ in $\mathbb{R} \times \mathbb{T}$. If $w_\nu > 0$ in the compact set $[-N, N] \times \mathbb{T}$, then $w_{\nu-\varepsilon} > 0$ in $[-N, N] \times \mathbb{T}$ for $\varepsilon > 0$ small enough. Hence, as in the previous paragraph, it follows that $w_{\nu-\varepsilon} > 0$ in $\mathbb{R} \times \mathbb{T}$ for all $\varepsilon > 0$ small enough, which contradicts the definition of ν . Therefore, w_ν vanishes somewhere in $[-N, N] \times \mathbb{R}$ and Lemma 4.2 again implies that $v - \nu\partial_\xi\phi_{L_0} = w_\nu = 0$ in $\mathbb{R} \times \mathbb{T}$. That is, $v = \nu\partial_\xi\phi_{L_0}$ in $\mathbb{R} \times \mathbb{T}$ (with $\nu \neq 0$ since $v \neq 0$).

Step 2: 0 is an algebraically simple eigenvalue of H_{L_0} . Suppose that $H_{L_0}^m(v) = 0$ for some integer $m \geq 2$ and $v \in \mathcal{D}_{L_0} + i\mathcal{D}_{L_0}$ such that $H_{L_0}(v), \dots, H_{L_0}^{m-1}(v) \in \mathcal{D}_{L_0} + i\mathcal{D}_{L_0}$. Without loss of generality, one can assume that v is real valued. Since $\ker(H_{L_0}) = \mathbb{C}\partial_\xi\phi_{L_0}$ and v is real valued, it follows that $H_{L_0}^{m-1}(v) = C_1\partial_\xi\phi_{L_0}$ with some constant $C_1 \in \mathbb{R}$. Without loss of generality, even if it means changing v into $-v$, one can assume that $C_1 \geq 0$. On the other hand, parabolic regularity theory implies that $H_{L_0}^{m-2}(v)$ is a bounded $C^2(\mathbb{R} \times \mathbb{T})$ solution of $H_{L_0}(H_{L_0}^{m-2}(v)) = C_1\partial_\xi\phi_{L_0} \leq 0$ in $\mathbb{R} \times \mathbb{T}$. By considering functions of the type $H_{L_0}^{m-2}(v) - \mu\partial_\xi\phi_{L_0}$ with $\mu \in \mathbb{R}$, it follows then as in Step 1 that $H_{L_0}^{m-2}(v) = C_2\partial_\xi\phi_{L_0}$ for some constant C_2 , whence $H_{L_0}^{m-1}(v) = 0$. By an immediate induction, one concludes that $v = C_3\partial_\xi\phi_{L_0}$ for some constant C_3 .

Step 3: if $\lambda \in \mathbb{C}^$ is an eigenvalue of H_{L_0} , then $\operatorname{Re}(\lambda) < 0$.* Let $\lambda \in \mathbb{C}$ be an eigenvalue of H_{L_0} , with an eigenfunction $\psi \in \mathcal{D}_{L_0} + i\mathcal{D}_{L_0}$, and assume that $\operatorname{Re}(\lambda) \geq 0$. By standard parabolic estimates applied to its real and imaginary parts, the function $u(t, x) = \psi(x - c_{L_0}t, x/L_0)$ is a classical solution of

$$u_t - (a_{L_0}(x)u_x)_x - \partial_u f_{L_0}(x, U(t, x))u = -\lambda u \text{ in } \mathbb{R}^2. \quad (4.3)$$

Furthermore, $u \in W^{1,\infty}(\mathbb{R}^2, \mathbb{C})$ and then $u(t, x) \rightarrow 0$ as $|x - c_{L_0}t| \rightarrow +\infty$. Denote $\rho = |u|$ the modulus of u . In the open set $\Omega := \{(t, x) \in \mathbb{R}^2 \mid \rho(t, x) > 0\}$, one can write $u(t, x) = \rho(t, x)e^{i\vartheta(t, x)}$ where the real-valued functions ρ and ϑ are of class C^1 with respect to t and C^2 with respect to x in Ω . By putting $u = \rho e^{i\vartheta}$ in (4.3) and taking the real part, one infers that

$$\rho_t - (a_{L_0}(x)\rho_x)_x - \partial_u f_{L_0}(x, U(t, x))\rho = -(\operatorname{Re}(\lambda) + a_{L_0}\vartheta_x^2)\rho \leq 0 \text{ in } \Omega. \quad (4.4)$$

By (1.2-1.3), there is $N > 0$ such that $\partial_u f_{L_0}(x, U(t, x)) \leq -\gamma/2 < 0$ for all $|x - c_{L_0}t| \geq N$. Since U_t is positive and continuous in \mathbb{R}^2 and since $U_t(t + L_0/c_{L_0}, x + L_0) = U_t(t, x)$ in \mathbb{R}^2 , one has $\inf_{|x - c_{L_0}t| \leq N} U_t(t, x) > 0$ and there is $\sigma > 0$ such that

$$\rho \leq \sigma U_t \text{ for all } (t, x) \in \mathbb{R}^2 \text{ with } |x - c_{L_0}t| \leq N.$$

It follows then as in the end of the proof of Lemma 2.1 that $\rho \leq \sigma U_t$ for all $|x - c_{L_0}t| \geq N$ (otherwise, there would exist $\varepsilon^* > 0$ with $z := \sigma U_t - \rho \geq -\varepsilon^*$ in $\{|x - c_{L_0}t| \geq N\}$ and a point (t^*, x^*) such that $x^* - c_{L_0}t^* > N$ and $z(t^*, x^*) = -\varepsilon^*$; since $\rho(t^*, x^*) = \sigma U_t(t^*, x^*) + \varepsilon^* > 0$, there holds $z_t - (a_{L_0}(x)z_x)_x - \partial_u f_{L_0}(x, U(t, x))z \geq 0$ in a neighborhood of (t^*, x^*) , and one gets a contradiction at

(t^*, x^*) , since $-\partial_u f_{L_0}(x^*, U(t^*, x^*)) z(t^*, x^*) = \varepsilon^* \partial_u f_{L_0}(x^*, U(t^*, x^*)) \leq -\varepsilon^* \gamma/2 < 0$. Similarly, $\rho \leq \sigma U_t$ for all $x - c_{L_0} t \leq -N$, whence $\rho \leq \sigma U_t$ in \mathbb{R}^2 .

Set now $\sigma^* = \inf \{ \varsigma \geq 0 \mid \rho \leq \varsigma U_t \text{ in } \mathbb{R}^2 \}$. One has $\sigma^* > 0$ since $\rho \not\equiv 0$, and $\rho \leq \sigma^* U_t$ in \mathbb{R}^2 . If $\inf_{|x - c_{L_0} t| \leq N} (\sigma^* U_t(t, x) - \rho(t, x)) > 0$, then there would exist $\sigma_* \in (0, \sigma^*)$ such that $\rho(t, x) \leq \sigma_* U_t(t, x)$ for all $|x - c_{L_0} t| \leq N$ (since U_t is bounded) and it would follow as in the previous paragraph that $\rho \leq \sigma_* U_t$ in \mathbb{R}^2 , contradicting the minimality of σ^* . Consequently, $\inf_{|x - c_{L_0} t| \leq N} (\sigma^* U_t(t, x) - \rho(t, x)) = 0$. By continuity and the properties

$$U_t(t + L_0/c_{L_0}, x + L_0) = U_t(t, x), \quad \rho(t + L_0/c_{L_0}, x + L_0) = \rho(t, x) \quad \text{for all } (t, x) \in \mathbb{R}^2, \quad (4.5)$$

there is $(t_0, x_0) \in \mathbb{R}^2$ such that $\rho(t_0, x_0) = \sigma^* U_t(t_0, x_0)$. Hence, $\rho > 0$ in (at least) a neighborhood of (t_0, x_0) and the strong parabolic maximum principle implies actually that $\rho = \sigma^* U_t > 0$ in $(-\infty, t_0] \times \mathbb{R}$ and then in \mathbb{R}^2 by (4.5). Therefore, $Re(\lambda) = 0$ and $\vartheta_x = 0$ in \mathbb{R}^2 , by (4.4). On the other hand, by taking the imaginary part of (4.3), one infers that $\vartheta_t = -Im(\lambda)$ in \mathbb{R}^2 . Finally, since $\vartheta(t + L_0/c_{L_0}, x + L_0) = \vartheta(t, x)$ in \mathbb{R}^2 , one gets that ϑ is constant in \mathbb{R}^2 and that $\lambda = 0$. As a conclusion, $Re(\lambda) < 0$ if $\lambda \neq 0$.

Step 4: the range of H_{L_0} is closed in $L^2(\mathbb{R} \times \mathbb{T}, \mathbb{C})$. Let $(v_n)_{n \in \mathbb{N}}$ in $\mathcal{D}_{L_0} + i\mathcal{D}_{L_0}$ and $(g_n)_{n \in \mathbb{N}}$ in $L^2(\mathbb{R} \times \mathbb{T}, \mathbb{C})$ be some sequences such that $H_{L_0}(v_n) = g_n \rightarrow g$ in $L^2(\mathbb{R} \times \mathbb{T}, \mathbb{C})$ as $n \rightarrow +\infty$. Without loss of generality, one can assume that all functions v_n, g_n and g are real valued and that v_n is orthogonal to $\partial_\xi \phi_{L_0}$ in $L^2(\mathbb{R} \times \mathbb{T}, \mathbb{R})$.

Let us now show that the sequence $(\|v_n\|_{L^2(\mathbb{R} \times \mathbb{T})})_{n \in \mathbb{N}}$ is bounded. Suppose the contrary, let $w_n = v_n / \|v_n\|_{L^2(\mathbb{R} \times \mathbb{T})}$ with $\|w_n\|_{L^2(\mathbb{R} \times \mathbb{T})} = 1$ and observe that $H_{L_0}(w_n) = g_n / \|v_n\|_{L^2(\mathbb{R} \times \mathbb{T})} \rightarrow 0$ as $n \rightarrow +\infty$. Notice that

$$M_{c_{L_0}, L_0}(w_n) = H_{L_0}(w_n) - (\partial_u f(y, \phi_{L_0}) + \beta) w_n \quad \text{for all } n \in \mathbb{N}.$$

By Lemma 3.1, the sequence $(w_n)_{n \in \mathbb{N}}$ is then bounded in $H^1(\mathbb{R} \times \mathbb{T})$ and then a subsequence converges in $H^1(\mathbb{R} \times \mathbb{T})$ weakly and in $L^2_{loc}(\mathbb{R} \times \mathbb{T})$ strongly to some $w_0 \in H^1(\mathbb{R} \times \mathbb{T})$. Furthermore, w_0 is orthogonal to $\partial_\xi \phi_{L_0}$ in $L^2(\mathbb{R} \times \mathbb{T})$ and $\int_{\mathbb{R} \times \mathbb{T}} a(y) (\tilde{\partial}_{L_0} w_0) (\tilde{\partial}_{L_0} \varphi) - c_{L_0} \varphi \partial_\xi w_0 - \partial_u f(y, \phi_{L_0}) w_0 \varphi = 0$ for all $\varphi \in H^1(\mathbb{R} \times \mathbb{T})$, whence $w_0 \in \mathcal{D}_{L_0}$ and $H_{L_0}(w_0) = 0$. Since $\ker(H_{L_0}) = \mathbb{C}(\partial_\xi \phi_{L_0})$, it follows that $w_0 = 0$. Let $N > 0$ be as in (4.2) and let $\varrho : \mathbb{R} \rightarrow [0, 1]$ be the piecewise affine function defined by $\varrho(\xi) = 0$ for all $\xi \leq N$, $\varrho(\xi) = \xi - N$ for all $\xi \in [N, N + 1]$ and $\varrho(\xi) = 1$ for all $\xi \geq N + 1$. Then, by integrating the equation $H_{L_0}(w_n) = g_n / \|v_n\|_{L^2(\mathbb{R} \times \mathbb{T})}$ against $w_n \varrho$, one gets that

$$\begin{aligned} & - \int_{(N, +\infty) \times \mathbb{T}} a(y) \varrho(\xi) (\tilde{\partial}_{L_0} w_n)^2 - \int_{(N, N+1) \times \mathbb{T}} a(y) w_n \tilde{\partial}_{L_0} w_n \\ & - \int_{(N, N+1) \times \mathbb{T}} \frac{c_{L_0}}{2} w_n^2 + \int_{(N, +\infty) \times \mathbb{T}} \varrho(\xi) \partial_u f(y, \phi_{L_0}) w_n^2 = \int_{(N, +\infty) \times \mathbb{T}} \frac{\varrho(\xi) g_n w_n}{\|v_n\|_{L^2(\mathbb{R} \times \mathbb{T})}} \xrightarrow{n \rightarrow +\infty} 0. \end{aligned}$$

Since the sequence $(w_n)_{n \in \mathbb{N}}$ is bounded in $H^1(\mathbb{R} \times \mathbb{T})$, since $w_n \rightarrow 0$ in $L^2_{loc}(\mathbb{R} \times \mathbb{T})$ and since both terms $-\int_{(N, +\infty) \times \mathbb{T}} a(y) \varrho(\xi) (\tilde{\partial}_{L_0} w_n)^2$ and $\int_{(N, +\infty) \times \mathbb{T}} \varrho(\xi) \partial_u f(y, \phi_{L_0}) w_n^2$ are nonpositive, it follows that they both converge to 0 as $n \rightarrow +\infty$. In particular, by (4.2), $\|w_n\|_{L^2((N+1, +\infty) \times \mathbb{T})} \rightarrow 0$ as $n \rightarrow +\infty$. Using the same analysis over $(-\infty, -N)$ implies that $\|w_n\|_{L^2((-\infty, -N-1) \times \mathbb{T})} \rightarrow 0$ as $n \rightarrow +\infty$. Finally the sequence $(w_n)_{n \in \mathbb{N}}$ tends to 0 strongly in $L^2(\mathbb{R} \times \mathbb{T})$ as $n \rightarrow +\infty$, which contradicts the fact that $\|w_n\|_{L^2(\mathbb{R} \times \mathbb{T})} = 1$. Hence, the sequence $(v_n)_{n \in \mathbb{N}}$ is bounded in $L^2(\mathbb{R} \times \mathbb{T})$.

Since $M_{c_{L_0}, L_0}(v_n) = g_n - (\partial_u f(y, \phi_{L_0}) + \beta) v_n$, Lemma 3.1 again implies that $(v_n)_{n \in \mathbb{N}}$ is bounded in $H^1(\mathbb{R} \times \mathbb{T})$. Therefore, a subsequence converges weakly in $H^1(\mathbb{R} \times \mathbb{T})$ to some $v \in \mathcal{D}_{L_0}$ such that $H_{L_0}(v) = g$.

Step 5: 0 is an algebraically simple eigenvalue of $H_{L_0}^$.* Choose a sufficient large real number λ_0 such that $\lambda_0 > \partial_u f(x, u)$ for all $(x, u) \in \mathbb{R} \times [0, 1]$. Denote $\tilde{H}_{L_0}(v) = H_{L_0}(v) - \lambda_0 v$ for $v \in \mathcal{D}_{L_0} + i\mathcal{D}_{L_0}$. The adjoint operator $H_{L_0}^*$ of \tilde{H}_{L_0} is given by $H_{L_0}^*(v) = H_{L_0}^*(v) - \lambda_0 v$ for $v \in \mathcal{D}_{L_0} + i\mathcal{D}_{L_0}$, in such

a way that $\langle \tilde{H}_{L_0}^*(v), u \rangle_{L^2(\mathbb{R} \times \mathbb{T}, \mathbb{C})} = \langle v, \tilde{H}_{L_0}(u) \rangle_{L^2(\mathbb{R} \times \mathbb{T}, \mathbb{C})}$ for all $u, v \in \mathcal{D}_{L_0} + i\mathcal{D}_{L_0}$. As in the proof of Lemma 3.1, it is easy to see that the kernels of \tilde{H}_{L_0} and $\tilde{H}_{L_0}^*$ are reduced to $\{0\}$. In addition, arguments similar to the ones in Step 4 imply that the range of \tilde{H}_{L_0} is closed in $L^2(\mathbb{R} \times \mathbb{T}, \mathbb{C})$. Thus, the operator $\tilde{H}_{L_0} : \mathcal{D}_{L_0} + i\mathcal{D}_{L_0} \rightarrow L^2(\mathbb{R} \times \mathbb{T}, \mathbb{C})$ is invertible. Then the arguments in p. 220 of [51] imply that there is a strictly positive function $v^* \in \mathcal{D}_{L_0}$ such that $H_{L_0}^*(v^*) = 0$. That is, 0 is an eigenvalue of $H_{L_0}^*$ with a positive eigenfunction v^* . Applying the above analysis in Step 1-2 to $H_{L_0}^*$ provides the algebraic simplicity of the eigenvalue 0. The proof of Lemma 4.1 is thereby complete. \square

Proof of Theorem 1.8. Given the above preparations, it follows as in Lemma 3.4 that the operator $\tilde{Q} = \partial_{(v,c)} \tilde{G}(0, c_0, L_0) : H^1(\mathbb{R} \times \mathbb{T}) \times \mathbb{R} \rightarrow H^1(\mathbb{R} \times \mathbb{T}) \times \mathbb{R}$ is invertible. The proof of Theorem 1.8 is then almost the same as that of Theorem 1.2, so we omit the details. \square

4.2 The case $L \in \partial E \cap (0, +\infty)$

The following theorem gives some information about the existence of steady states or other pulsating fronts of (1.1) at a positive boundary point of the set E . We first recall that if $L \in \partial E \cap (0, +\infty)$, then (1.1) cannot admit a pulsating front with a nonzero speed, as a consequence of Theorem 1.8.

Theorem 4.3. *If $\int_0^1 \bar{f}(u) du \neq 0$ and $L \in \partial E \cap (0, +\infty)$, then one of the following cases occurs:*

- (i) *either there is $c > 0$ such that equation (1.1) admits some L -periodic steady states $0 < \bar{u}(x), \bar{v}(x) < 1$, with \bar{u} being semistable, and some pulsating fronts*

$$\begin{cases} 0 < \phi(x - ct, x/L) = u(t, x) < v(t, x) = \psi(x - ct, x/L) < 1, \\ \phi(\xi, y) \text{ and } \psi(\xi, y) \text{ are 1-periodic in } y \end{cases} \quad (4.6)$$

with speed c and with limiting values

$$\begin{cases} \phi(-\infty, y) = \bar{u}(Ly), & \phi(+\infty, y) = 0, \\ \psi(-\infty, y) = 1, & \psi(+\infty, y) = \bar{v}(Ly), \end{cases} \quad \text{uniformly in } y \in \mathbb{R}; \quad (4.7)$$

- (ii) *or there is $c < 0$ such that equation (1.1) admits some L -periodic steady states $0 < \bar{u}(x), \bar{v}(x) < 1$, with \bar{v} being semistable, and some pulsating fronts $0 < u(t, x) < v(t, x) < 1$, with speed c , satisfying (4.6) and (4.7);*

- (iii) *or equation (1.1) admits a semistable L -periodic steady state $0 < \bar{u} \leq 1$ and a semistable steady state u such that $0 < u < \bar{u}$, $u(\cdot + L) < u$ with the limiting values $u(x) - \bar{u}(x) \rightarrow 0$ as $x \rightarrow -\infty$ and $u(x) \rightarrow 0$ as $x \rightarrow +\infty$;*

- (iv) *or equation (1.1) admits a semistable L -periodic steady state $0 \leq \bar{v} < 1$ and a semistable steady state v such that $\bar{v} < v < 1$, $v(\cdot + L) < v$ with the limiting values $v(x) \rightarrow 1$ as $x \rightarrow -\infty$ and $v(x) - \bar{v}(x) \rightarrow 0$ as $x \rightarrow +\infty$.*

Furthermore, if $\int_0^1 \bar{f}(u) du > 0$, then only cases (i) and (iii) can occur, while only cases (ii) and (iv) can occur if $\int_0^1 \bar{f}(u) du < 0$.

Remark 4.4. It follows in particular that if $L \in \partial E \cap (0, +\infty)$, then equation (1.1) admits either at least one semistable L -periodic steady state $0 < \bar{u} < 1$ or a stationary front connecting 0 and 1. Cases (i), (ii), (iii) and (iv) have some similarities to the limiting behavior of homogeneous equations of the type

$$u_t = u_{xx} + f_n(u), \quad (4.8)$$

where $(f_n)_{n \in \mathbb{N}}$ is a family of $C^1([0, 1])$ functions satisfying (1.3) uniformly in n with $f_n(0) = f_n(1) = 0$, and converging uniformly in $[0, 1]$ to a $C^1([0, 1])$ function f . On the one hand, if, for instance, each function f_n has a unique zero θ_n in $(0, 1)$, $\theta_n \rightarrow \theta \in (0, 1)$, $\int_0^1 f_n \neq 0$, $f < 0$ in $(0, \theta)$, $f > 0$ in $(\theta, 1)$ and $\int_0^1 f = 0$, then each equation (4.8) admits a traveling front $\phi_n(x - c_n t)$ connecting 0 and 1, with $c_n \neq 0$, while the limiting equation $u_t = u_{xx} + f(u)$ admits a stationary front but does not admit any non-stationary front connecting 0 and 1. The conclusion would then be in some sense similar to that of cases (iii) and (iv) in Theorem 4.3. On the other hand, assume now that there are $0 < \theta_{1,n} < \theta_{2,n} < \theta_{3,n} < 1$ such that $f_n(\theta_{1,n}) = f_n(\theta_{2,n}) = f_n(\theta_{3,n}) = 0$, $f_n < 0$ in $(0, \theta_{1,n}) \cup (\theta_{2,n}, \theta_{3,n})$, $f_n > 0$ in $(\theta_{1,n}, \theta_{2,n}) \cup (\theta_{3,n}, 1)$ and let c'_n and c''_n be the speeds of the traveling fronts of (4.8) connecting 0 and $\theta_{2,n}$, and $\theta_{2,n}$ and 1, respectively. If $c'_n < c''_n$, then (4.8) admits a traveling front connecting 0 and 1, with a speed c_n such that $c'_n < c_n < c''_n$, see [23]. Now, if the real numbers $0 < \theta_{1,n} < \theta_{2,n} < \theta_{3,n} < 1$ converge to $0 < \theta_1 < \theta_2 < \theta_3 < 1$, if $f < 0$ in $(0, \theta_1) \cup (\theta_2, \theta_3)$, $f > 0$ in $(\theta_1, \theta_2) \cup (\theta_3, 1)$, and if c'_n and c''_n converge to the same real number c , then the limiting equation $u_t = u_{xx} + f(u)$ does not admit any traveling front connecting 0 and 1 [23], but it admits some traveling fronts with speed c connecting 0 and θ_2 , and θ_2 and 1, respectively. Furthermore, $\theta_2 \in (0, 1)$ is necessarily a semistable steady state of the limiting equation in the sense that $f'(\theta_2) \leq 0$. If $c > 0$ or $c < 0$, then the conclusion for this limiting equation is similar to that of cases (i) or (ii) in Theorem 4.3.

A key-step in the proof of Theorem 4.3 is to show that the speeds c_{L_n} are bounded when $L_n \in E$ approaches $L \in \partial E \cap (0, +\infty)$ (see Lemma 4.6 below). This property could actually be viewed as a consequence of the more general boundedness property (1.16), which follows from an even more general boundedness result on the global mean speeds of transition fronts, see [17]. Here, for the sake of completeness, Lemma 4.6 is proved. Then, the strategy of the proof of Theorem 4.3 is the following: if for some sequence the speeds c_{L_n} converge to a nonzero real number as $L_n \rightarrow L$ with $L_n \in E$, then equation (1.1) admits some pulsating fronts connecting 0, resp. 1, to some L -periodic steady states. On the other hand, if the speeds c_{L_n} converge to 0, then equation (1.1) admits either a semistable stationary front connecting 0 and 1, or some semistable stationary fronts connecting 0, resp. 1, to some semistable L -periodic steady states.

Before doing so, we first state an elementary lemma which will be used several times.

Lemma 4.5. *Let $\delta \in (0, 1/2)$ be as in (1.3) and let $L > 0$ be arbitrary. If u is a classical stationary solution of (1.1) such that $0 \leq u \leq \delta$ in \mathbb{R} , then $u \equiv 0$ in \mathbb{R} . Similarly, if u is a classical stationary solution of (1.1) such that $1 - \delta \leq u \leq 1$ in \mathbb{R} , then $u \equiv 1$ in \mathbb{R} .*

Proof. We only prove the first assertion, since the second one is similar. Let u be a classical steady state of (1.1) such that $0 \leq u \leq \delta$. From (1.3), the function $a_L u'$ is nondecreasing. Assume by contradiction that u is not constant in \mathbb{R} . Then there exists $x_0 \in \mathbb{R}$ such that $u'(x_0) \neq 0$. If $u'(x_0) > 0$, then $a_L(x_0)u'(x_0) \leq a_L(x)u'(x)$ for all $x_0 \leq x$ and $\inf_{x \geq x_0} u'(x) > 0$, contradicting the boundedness of u . Similarly, if $u'(x_0) < 0$, then $\sup_{x \leq x_0} u'(x) < 0$, which is impossible too. Finally, u is a constant, between 0 and δ , and assumption (1.3) yields $u \equiv 0$ in \mathbb{R} . \square

Lemma 4.6. *If $(L_n)_{n \in \mathbb{N}}$ is a sequence in E such that $0 < \inf_{n \in \mathbb{N}} L_n \leq \sup_{n \in \mathbb{N}} L_n < +\infty$, then the sequence $(c_n)_{n \in \mathbb{N}}$ of the front speeds associated with (1.1) and the periods L_n is bounded.*

Proof. Assume first by contradiction that, up to extraction of a subsequence, one has $0 < c_n \rightarrow +\infty$ and $L_n \rightarrow L \in (0, +\infty)$ as $n \rightarrow +\infty$. For each $n \in \mathbb{N}$, let $u_n(t, x) = \phi_{L_n}(x - c_n t, x/L_n)$ be a pulsating front associated with (1.1) and the period L_n . By Theorem 1.1, each function u_n is increasing in t . Since $u_n(t, \cdot) \rightarrow 0$ as $t \rightarrow -\infty$ and $u_n(t, \cdot) \rightarrow 1$ as $t \rightarrow +\infty$, locally uniformly in \mathbb{R} , there is by continuity a unique $t_n \in \mathbb{R}$ such that

$$\max_{[0, L_n]} u_n(t_n, \cdot) = \delta. \quad (4.9)$$

By standard parabolic estimates the functions $(t, x) \mapsto u_n(t + t_n, x)$ converge in $C_{loc}^{1,2}(\mathbb{R}^2)$, up to extraction of a subsequence, to a classical solution $0 \leq u(t, x) \leq 1$ of (1.1) such that $\max_{[0,L]} u(0, \cdot) = \delta$ and u is nondecreasing with respect to t . Furthermore, since

$$u_n\left(t + t_n + \frac{L_n}{c_n}, x + L_n\right) = u_n(t + t_n, x) \text{ for all } (t, x) \in \mathbb{R}^2 \text{ and } n \in \mathbb{N}, \quad (4.10)$$

one infers that $u(t, x + L) = u(t, x)$ for all $(t, x) \in \mathbb{R}^2$. In other words, u is L -periodic in x . By monotonicity in t and from standard parabolic estimates, one has $u(t, x) \rightarrow u^-(x)$ as $t \rightarrow -\infty$ uniformly in $x \in \mathbb{R}$, where $0 \leq u^- \leq 1$ is an L -periodic steady state of (1.1) such that $\max_{[0,L]} u^-(\cdot) \leq \max_{[0,L]} u(0, \cdot) = \delta$, whence $u^- \leq \delta$ in \mathbb{R} by L -periodicity. Lemma 4.5 implies that $u^- = 0$ in \mathbb{R} . As a consequence, there is $t_0 < 0$ such that $u(t_0, \cdot) \leq \delta/2$ in \mathbb{R} and, since $\delta/2$ is a supersolution of (1.1), it follows necessarily that $u(t, \cdot) \leq \delta/2$ in \mathbb{R} for all $t \geq t_0$, contradicting in particular $\max_{[0,L]} u(0, \cdot) = \delta$.

Lastly, if there is a subsequence such that $0 > c_n \rightarrow -\infty$ and $L_n \rightarrow L \in (0, +\infty)$, one reaches a similar contradiction by changing the normalization condition (4.9) into

$$\min_{[0,L_n]} u_n(\tau_n, \cdot) = 1 - \delta, \quad (4.11)$$

with $\tau_n \in \mathbb{R}$. The proof of Lemma 4.6 is thereby complete. \square

Proof of Theorem 4.3. Let $(L_n)_{n \in \mathbb{N}}$ be a sequence in E such that $L_n \rightarrow L \in \partial E \cap (0, +\infty)$ as $n \rightarrow +\infty$. Thus, for each $n \in \mathbb{N}$, equation (1.1) with the period L_n admits a pulsating front $u_n(t, x) = \phi_{L_n}(x - c_n t, x/L_n)$ with speed $c_n \neq 0$. It follows from Lemma 4.6 that, up to extraction of a subsequence, there is $c \in \mathbb{R}$ such that $c_n \rightarrow c$ as $n \rightarrow +\infty$. According to the sign of c , four cases may occur.

Case (i): $c > 0$. In that case, by Theorem 1.1, there holds necessarily $c_n > 0$ for each $n \in \mathbb{N}$ and $\int_0^1 \bar{f}(u) du > 0$. Furthermore, each function u_n is increasing in t . As in the proof of Lemma 4.6, for each $n \in \mathbb{N}$, there is a unique $t_n \in \mathbb{R}$ such that the normalization condition (4.9) holds. By standard parabolic estimates, up to extraction of a subsequence, the functions $(t, x) \mapsto u_n(t + t_n, x)$ converge in $C_{loc}^{1,2}(\mathbb{R}^2)$ to a classical solution $0 \leq u(t, x) \leq 1$ of (1.1) such that $\max_{[0,L]} u(0, \cdot) = \delta$ and u is nondecreasing with respect to t . The strong maximum principle implies that $0 < u(t, x) < 1$ for all $(t, x) \in \mathbb{R}^2$. Furthermore, by passing to the limit as $n \rightarrow +\infty$ in (4.10), one infers that

$$u\left(t + \frac{L}{c}, x + L\right) = u(t, x) \text{ for all } (t, x) \in \mathbb{R}^2, \quad (4.12)$$

that is, u can be written as

$$u(t, x) = \phi\left(x - ct, \frac{x}{L}\right),$$

where $\phi(\xi, y) = u((Ly - \xi)/c, Ly)$ is 1-periodic in y . Furthermore, by monotonicity in t and standard parabolic estimates, it follows by passing to the limit as $t \rightarrow \pm\infty$ in (4.12) that there exist two L -periodic steady states $0 \leq \tilde{u}(x) \leq \bar{u}(x) \leq 1$ such that

$$u(t, x) \rightarrow \tilde{u}(x) \text{ as } t \rightarrow -\infty \text{ and } u(t, x) \rightarrow \bar{u}(x) \text{ as } t \rightarrow +\infty, \text{ locally uniformly in } x \in \mathbb{R}.$$

The steady state $\tilde{u} \geq 0$ is L -periodic and satisfies $\max_{[0,L]} \tilde{u}(\cdot) \leq \max_{[0,L]} u(0, \cdot) = \delta$, whence $\tilde{u} = 0$ by Lemma 4.5. In other words, $\phi(+\infty, \cdot) = 0$. Furthermore, the steady state $\bar{u}(x) = \phi(-\infty, x/L)$ ($\geq u(t, x) > 0$) cannot be equal to 1, otherwise u would be a pulsating front (connecting 0 and 1) with the speed $c \neq 0$ and L would then belong to E , contradicting Theorem 1.8 and the assumption $L \in \partial E \cap (0, +\infty)$. Therefore, from the strong elliptic maximum principle, $0 < \bar{u} < 1$ is a non-trivial L -periodic steady state of (1.1). Notice also, from the strong parabolic maximum principle, that the

nonnegative function u_t is positive in \mathbb{R}^2 , whence $\phi(\xi, y)$ is decreasing in ξ and $0 < \phi(\xi, y) < \bar{u}(Ly)$ for all $(\xi, y) \in \mathbb{R}^2$.

Let us now show that \bar{u} is semistable. Suppose on the contrary that \bar{u} is unstable, that is $\lambda_1(L, \bar{u}) > 0$, where $\lambda_1(L, \bar{u})$ is the principal eigenvalue of (3.10) corresponding to the steady state \bar{u} . By Definition 3.5, one can choose R large enough such that $\lambda_{1,R}(L, \bar{u}) > 0$, where $\lambda_{1,R}(L, \bar{u})$ is the principal eigenvalue in (3.9), associated with a positive principal eigenfunction ψ_R . For any $\varepsilon > 0$, define v_ε as in (3.14). Since $u(t, x) < \bar{u}(x)$ for all $(t, x) \in \mathbb{R}^2$ and both functions are continuous, one can choose $\varepsilon > 0$ so small that $u(0, x) < v_\varepsilon(x)$ for all $x \in \mathbb{R}$ and, as in (3.15), v_ε is a supersolution of the elliptic equation associated with (1.1). It then follows from the parabolic maximum principle that $u(t, x) < v_\varepsilon(x)$ for all $t \geq 0$ and $x \in \mathbb{R}$. Hence, $\bar{u}(x) \leq v_\varepsilon(x)$ for all $x \in \mathbb{R}$, which is clearly impossible. Finally, $0 < \bar{u} < 1$ is a semistable L -periodic steady state of (1.1).

Now, instead of the normalization (4.9), one can choose $\tau_n \in \mathbb{R}$ such that (4.11) holds. Since $\delta < 1 - \delta$ and each function u_n is increasing in t , one infers that $t_n < \tau_n$. As above, up to extraction of a subsequence, the functions $(t, x) \mapsto u_n(t + \tau_n, x)$ ($> u_n(t + t_n, x)$) converge in $C_{loc}^{1,2}(\mathbb{R}^2)$ to a classical solution $0 < v(t, x) < 1$ of (1.1) such that $\min_{[0,L]} v(0, \cdot) = 1 - \delta$, v is nondecreasing with respect to t , $v \geq u$ in \mathbb{R}^2 , and v satisfies (4.12) that is v can be written as $v(t, x) = \psi(x - ct, x/L)$, where $\psi(\xi, y) = v((Ly - \xi)/c, Ly)$ is 1-periodic in y . Furthermore, there are two L -periodic steady states $0 \leq \bar{v}(x) \leq \tilde{v}(x) \leq 1$ such that $v(t, x) \rightarrow \bar{v}(x)$ as $t \rightarrow -\infty$ and $v(t, x) \rightarrow \tilde{v}(x)$ as $t \rightarrow +\infty$ locally uniformly in $x \in \mathbb{R}$. The steady state $\tilde{v} \leq 1$ is L -periodic and satisfies $\min_{[0,L]} \tilde{v}(\cdot) \geq \min_{[0,L]} v(0, \cdot) = 1 - \delta$, whence $\tilde{v} = 1$ by Lemma 4.5. In other words, $\psi(-\infty, \cdot) = 1$. In particular, since $\bar{u}(x) = u(+\infty, x) < 1 = v(+\infty, x)$ and $u \leq v$, it follows then from the strong maximum principle that

$$u(t, x) < v(t, x) \text{ for all } (t, x) \in \mathbb{R}^2.$$

Lastly, the steady state $\bar{v}(x) = \psi(+\infty, x/L)$ ($\leq v(t, x) < 1$) cannot be equal to 0, otherwise v would be a pulsating front (connecting 0 and 1) with the speed $c \neq 0$, contradicting Theorem 1.8 and the assumption $L \in \partial E \cap (0, +\infty)$. Therefore, $0 < \bar{v} < 1$ is a non-trivial L -periodic steady state of (1.1). Notice that, in this case, \bar{v} may not be semistable in general, the maximum principle leading to no obvious contradiction if \bar{v} were assumed to be unstable.

Case (ii): $c < 0$. The analysis is similar to that done in case (i), but now $\int_0^1 \bar{f}(u) du < 0$ and the functions u_n and their limits u and v are nonincreasing in t . One has $\lim_{t \rightarrow +\infty} u(t, x) = 0 < \bar{u}(x) = \lim_{t \rightarrow -\infty} u(t, x) < 1$ and $0 < \bar{v}(x) = \lim_{t \rightarrow +\infty} v(t, x) < 1 = \lim_{t \rightarrow -\infty} v(t, x)$. Lastly, the functions \bar{u} and \bar{v} are L -periodic steady states of (1.1) and \bar{v} is semistable.

Case (iii): $c = 0$ and $\int_0^1 \bar{f}(u) du > 0$. Hence, $c_n > 0$ for all $n \in \mathbb{N}$, by Theorem 1.1. Let $t_n \in \mathbb{R}$ be as in (4.9). Up to extraction of a subsequence, the functions $(t, x) \mapsto u_n(t + t_n, x)$ converge in $C_{loc}^{1,2}(\mathbb{R}^2)$ to a classical solution $0 < u_\infty(t, x) < 1$ of (1.1) such that $\max_{[0,L]} u_\infty(0, \cdot) = \delta$ and u_∞ is nondecreasing with respect to t . It also follows that $u_\infty(t, x) \rightarrow u(x)$ as $t \rightarrow +\infty$ locally uniformly in $x \in \mathbb{R}$, where $0 \leq u \leq 1$ is a steady state of (1.1). One has $\max_{[0,L]} u \geq \max_{[0,L]} u_\infty(0, \cdot) = \delta$, whence $u > 0$ in \mathbb{R} from the strong maximum principle. Furthermore, for every $x \in \mathbb{R}$ and $t \in \mathbb{R}$, since u_n is increasing in time, there holds $u_n(t + t_n, x + L_n) = u_n(t + t_n - L_n/c_n, x) < u_n(t + t_n, x)$, whence $u_\infty(t, x + L) \leq u_\infty(t, x)$ and

$$u(x + L) \leq u(x) \text{ for all } x \in \mathbb{R}. \quad (4.13)$$

Now, for any fixed $t \in \mathbb{R}$ and $x > L$, and for all n large enough, one has $t - L_n/c_n \leq 0$ and there is $k_n \in \mathbb{N}$ such that $k_n \geq 1$ and $k_n L_n \leq x \leq (k_n + 1)L_n$, whence $t - k_n L_n/c_n \leq 0$ and

$$u_n(t + t_n, x) = u_n\left(t + t_n - \frac{k_n L_n}{c_n}, x - k_n L_n\right) \leq u_n(t_n, x - k_n L_n) \leq \max_{[0, L_n]} u_n(t_n, \cdot) = \delta$$

by (4.9) and the monotonicity of u_n with respect to t . Therefore, $u_\infty(t, x) \leq \delta$ for all $t \in \mathbb{R}$ and $x > L$ (and $x \geq L$ by continuity), whence $u(x) \leq \delta$ for all $x \geq L$. In particular, the strong maximum principle

yields $u < 1$ in \mathbb{R} . Furthermore, by (4.13) and standard elliptic estimates, the functions $x \mapsto u(x + kL)$ (with parameter $k \in \mathbb{N}$) converge decreasingly as $k \rightarrow +\infty$ in $C_{loc}^2(\mathbb{R})$ to an L -periodic steady state $\underline{u}(x)$ of (1.1) such that $0 \leq \underline{u}(x) \leq \delta$ for all $x \in \mathbb{R}$. Lemma 4.5 implies that $\underline{u} \equiv 0$ in \mathbb{R} , whence $u(x) \rightarrow 0$ as $x \rightarrow +\infty$. Since u is (strictly) positive in \mathbb{R} , it then follows from (4.13) and the strong maximum principle that

$$u(x + L) < u(x) \quad \text{for all } x \in \mathbb{R}. \quad (4.14)$$

Similarly, the functions $x \mapsto u(x - kL)$ (with parameter $k \in \mathbb{N}$) converge increasingly as $k \rightarrow +\infty$ in $C_{loc}^2(\mathbb{R})$ to an L -periodic steady state $\bar{u}(x)$ of (1.1) such that $0 < \bar{u}(x) \leq 1$ in \mathbb{R} . In particular,

$$u(x) - \bar{u}(x) \rightarrow 0 \quad \text{as } x \rightarrow -\infty. \quad (4.15)$$

Notice that (4.14) and (4.15), together with the L -periodicity of \bar{u} , imply that $u(x) < \bar{u}(x)$ for all $x \in \mathbb{R}$. We also point out that, if \bar{u} is equal to 1, then u is a stationary front (connecting 0 and 1).

Let us now prove that, whether \bar{u} be equal to 1 or less than 1, both steady states $0 < u(x) < 1$ and $0 < \bar{u}(x) \leq 1$ are semistable. We will actually first prove that u is semistable, and \bar{u} will then immediately be semistable too by (4.15). So, assume first by contradiction that u is unstable. By Definition 3.5, there is $R > 0$ large enough such that $R > L$ and $\lambda_{1,R}(L, u) > 0$, where $\lambda_{1,R}(L, u)$ denotes the principal eigenvalue of (3.9) in $[-R, R]$, associated with a principal eigenfunction ψ . As in (3.15), there is then $\varepsilon_0 > 0$ such that, for all $\varepsilon \in (0, \varepsilon_0]$, the function

$$v_\varepsilon(x) = \begin{cases} u(x) - \varepsilon\psi(x) & \text{if } |x| < R, \\ u(x) & \text{if } |x| \geq R, \end{cases}$$

satisfies $0 < v_\varepsilon \leq u$ in \mathbb{R} and is a supersolution of the elliptic equation associated with (1.1). On the other hand, since $u_\infty(t, x) \leq u(x)$ for all $(t, x) \in \mathbb{R}^2$, the strong parabolic maximum principle implies that either $u_\infty(t, x) = u(x)$ for all $(t, x) \in \mathbb{R}^2$, or $u_\infty(t, x) < u(x)$ for all $(t, x) \in \mathbb{R}^2$. In the latter case, by continuity, there would be $\varepsilon \in (0, \varepsilon_0]$ such that $u_\infty(0, x) \leq v_\varepsilon(x)$ for all $x \in \mathbb{R}$, whence $u_\infty(t, x) \leq v_\varepsilon(x)$ for all $t \geq 0$ and $x \in \mathbb{R}$ from the maximum principle. By passing to the limit as $t \rightarrow +\infty$, one would infer that $u \leq v_\varepsilon$ in \mathbb{R}^2 , which is clearly impossible. Therefore, $u_\infty(t, x) = u(x)$ for all $(t, x) \in \mathbb{R}^2$. Now, since $0 < v_{\varepsilon_0} < 1$ is continuous and since, for each $n \in \mathbb{N}$, u_n is continuous and increasing in t with $u_n(-\infty, \cdot) = 0$ and $u_n(+\infty, \cdot) = 1$, there is a unique $t'_n \in \mathbb{R}$ such that $u_n(t'_n, \cdot) \leq v_{\varepsilon_0}$ in $[-R, R]$ with equality somewhere in $[-R, R]$, that is

$$\max_{[-R, R]} (u_n(t'_n, \cdot) - v_{\varepsilon_0}) = 0.$$

Since $R > L$ and $v_{\varepsilon_0} - u = -\varepsilon_0\psi$ is continuous and negative in $(-R, R)$, one has $L_n < (R + L)/2 < R$ for n large enough, and there is $\eta > 0$ such that

$$\max_{[0, L_n]} u_n(t'_n, \cdot) \leq \max_{[0, L_n]} v_{\varepsilon_0} < \max_{[0, L_n]} u - \eta = \max_{[0, L_n]} u_\infty(0, \cdot) - \eta,$$

for n large enough, whence $\max_{[0, L_n]} u_n(t'_n, \cdot) < \max_{[0, L_n]} u_n(t_n, \cdot)$. Therefore, $t'_n < t_n$ for n large enough and the functions $(t, x) \mapsto u_n(t + t'_n, x)$ converge in $C_{loc}^{1,2}(\mathbb{R}^2)$, up to extraction of a subsequence, to a classical solution \tilde{u}_∞ of (1.1) such that $0 \leq \tilde{u}_\infty(t, x) \leq u_\infty(t, x) = u(x) < 1$ for all $(t, x) \in \mathbb{R}^2$ and $\max_{[-R, R]} (\tilde{u}_\infty(0, \cdot) - v_{\varepsilon_0}) = 0$. In particular, $\tilde{u}_\infty(0, \cdot) \leq v_{\varepsilon_0}$ in \mathbb{R} with equality somewhere in $[-R, R]$. The maximum principle yields $\tilde{u}_\infty(t, x) \leq v_{\varepsilon_0}(x)$ for all $t \geq 0$ and $x \in \mathbb{R}$ and since \tilde{u}_∞ is nondecreasing in t , the function $\tilde{u}(x) = \lim_{t \rightarrow +\infty} \tilde{u}_\infty(t, x)$ is a classical steady state of (1.1) such that $\tilde{u} \leq v_{\varepsilon_0}$ in \mathbb{R} with equality at a point $x_0 \in [-R, R]$. If $|x_0| = R$, one has $\tilde{u} \leq u$ in \mathbb{R} with equality at x_0 , whence $\tilde{u} \equiv u$ in \mathbb{R} by the strong maximum principle which is clearly impossible since $\tilde{u} \leq v_{\varepsilon_0} < u$ in $(-R, R)$. If $|x_0| < R$,

then $\tilde{u} \equiv v_{\varepsilon_0}$ in $(-R, R)$ from the strong maximum principle, whence $\tilde{u}(\pm R) = v_{\varepsilon_0}(\pm R) = u(\pm R)$ by continuity, which is again impossible. Finally, one has reached a contradiction and one has shown that $0 < u < 1$ is a semistable steady state of (1.1).

Let us now conclude that the L -periodic steady state $0 < \bar{u} \leq 1$ is also semistable. Remember that $0 < u < \bar{u}$ in \mathbb{R} . Actually, if \bar{u} were unstable, then the arguments of Step 1 of the proof of Lemma 3.7 would imply that $\sup_{x \in \mathbb{R}} (u(x) - \bar{u}(x)) < 0$. This is clearly impossible by (4.15). Therefore, \bar{u} is semistable.

Case (iv): $c = 0$ and $\int_0^1 \bar{f}(u) du < 0$. Here, $c_n < 0$. For each $n \in \mathbb{N}$, let τ_n be the unique real number such that (4.11) holds. As in case (iii), up to extraction of a subsequence, the functions $(t, x) \mapsto u_n(t + \tau_n, x)$ converge in $C_{loc}^{1,2}(\mathbb{R}^2)$ to a classical solution $0 < v_\infty(t, x) < 1$ of (1.1) such that $\min_{[0, L]} v_\infty(0, \cdot) = 1 - \delta$ and v_∞ is nonincreasing with respect to t . Therefore, $v_\infty(t, x) \rightarrow v(x)$ as $t \rightarrow +\infty$ locally uniformly in $x \in \mathbb{R}$, where $0 \leq v < 1$ is a steady state of (1.1). As in case (iii), there holds $v_\infty(t, x + L) \leq v_\infty(t, x)$ and $v(x + L) \leq v(x)$ for all $(t, x) \in \mathbb{R}^2$, while $v_\infty(t, x) \geq 1 - \delta$ for all $t \in \mathbb{R}$ and $x \leq 0$. As a consequence, $v(x) \geq 1 - \delta$ for all $x \leq 0$ and $v(x) \rightarrow 1$ as $x \rightarrow -\infty$ by using Lemma 4.5. Hence $v(x + L) < v(x)$ for all $x \in \mathbb{R}$ by the strong maximum principle. Lastly, there is an L -periodic steady state $0 \leq \bar{v}(x) < 1$ of (1.1) such that $\bar{v}(x) < v(x) < 1$ for all $x \in \mathbb{R}$ and $v(x) - \bar{v}(x) \rightarrow 0$ as $x \rightarrow +\infty$. The semistability of v and \bar{v} can then be proved as it was done in case (iii) for u and \bar{u} . The proof of Theorem 4.3 is thereby complete. \square

5 Exponential stability of pulsating fronts

In this section, we first prove Theorem 1.9 on the exponential stability of the non-stationary pulsating fronts of (1.1). The proof is divided into two parts. In the first part, in Section 5.1, we present a dynamical systems approach to the global stability of the fronts. Namely, the solution of the Cauchy problem (1.17) with an initial value satisfying (1.18) converges at large time to a translate of the pulsating front. In the second part, in Section 5.2, by using spectral analysis we show that this convergence admits an exponential rate that is independent of the initial values. Lastly, in Section 5.3, initial conditions satisfying assumptions of the type (1.20) are considered and Theorem 1.10 is proved. For the sake of simplicity, throughout this section, even if it means rescaling the variables and renormalizing the reaction, one assumes that $L = 1$ and that equation (1.1) admits a pulsating front $U(t, x) = \phi(x - ct, x)$ with a nonzero speed c . Without loss of generality, as explained in Sections 3 and 4, one can assume that $c > 0$.

5.1 Global stability of pulsating fronts

Consider the moving coordinates

$$(\xi, t) = (x - ct, t), \tag{5.1}$$

and write the solution of (1.1) as $v(t, \xi) = u(t, x)$, so that $v(t, \xi)$ satisfies the following T -periodic parabolic equation with $T = 1/c$:

$$v_t = (a(\xi + ct)v_\xi)_\xi + cv_\xi + f(\xi + ct, v). \tag{5.2}$$

Clearly, the assumption (1.3) implies that 0 and 1 are two stable T -periodic solutions of (5.2). Note that for any $\tau \in \mathbb{R}$,

$$V^\tau(t, \xi) := \phi(\xi + \tau, \xi + ct) \tag{5.3}$$

is also a T -periodic solution of (5.2). Let P be the Poincaré map of the T -periodic equation (5.2), that is,

$$P(g) = v(T, \cdot; g), \tag{5.4}$$

where $v(t, \xi; g)$ is the unique solution of the Cauchy problem of (5.2) with initial condition $v(0, \cdot; g) = g \in C(\mathbb{R}, [0, 1])$. Throughout this section, we denote $\|\cdot\| = \|\cdot\|_{L^\infty(\mathbb{R})}$. It easily follows that 0, 1 and $V^\tau(0, \cdot)$ (for any $\tau \in \mathbb{R}$) are fixed points of P in $C(\mathbb{R}, [0, 1])$. Since $\phi(\xi, x)$ is decreasing in ξ by Theorem 1.1, there holds $V^{\tau_1}(0, \xi) > V^{\tau_2}(0, \xi)$ for all $\tau_1 < \tau_2$ and $\xi \in \mathbb{R}$. Hence, the set $\{V^\tau(0, \cdot) \mid \tau \in \mathbb{R}\}$ is totally ordered in $C(\mathbb{R}, [0, 1])$. In order to prove the global stability of the pulsating front $U(t, x) = \phi(x - ct, x)$ with phase shift in time, we will apply the following convergence theorem to the Poincaré map P (Lemma 5.1 will be applied later with $E = C(\mathbb{R}, \mathbb{R})$ and $C = C(\mathbb{R}, [0, 1])$).

Lemma 5.1. ([57, THEOREM 2.2.4]) *Let C be a closed and partially ordered convex subset of a partially ordered Banach space E and let $F : C \rightarrow C$ be a continuous and monotone map. Assume that there exists an increasing homeomorphism h from $[0, 1]$ onto a subset of C such that*

(1) *for each $s \in [0, 1]$, $h(s)$ is a stable fixed point of F ;*

(2) *for each $x \in [h(0), h(1)]_E = \{x \in E \mid h(0) \leq_E x \leq_E h(1)\} \subset C$, the forward orbit $\gamma^+(x) = \{F^n(x) \mid n \in \mathbb{N}\}$ is precompact;*

(3) *if $\omega(x) >_E h(s_0)$ for some $x \in [h(0), h(1)]_E$ and $s_0 \in [0, 1]$, then there exists $s_1 \in (s_0, 1)$ such that $\omega(x) \geq_E h(s_1)$. Here $\omega(x) = \bigcap_{k \in \mathbb{N}} \gamma^+(F^k(x))$ denotes the ω -limit set of $\{x\}$ for F .*

Then for any precompact forward orbit $\gamma^+(y)$ of F in C with $\omega(y) \cap [h(0), h(1)]_E \neq \emptyset$, there is $s^ \in [0, 1]$ such that $\omega(y) = \{h(s^*)\}$.*

This abstract convergence result and its continuous-time analog were used, respectively, to prove the global attractiveness and uniqueness of bistable traveling waves for two classes of time-periodic reaction-diffusion equations in [57, 56] and an autonomous reaction-diffusion system in [55]. Here we should point out that the arguments used there are dependent on the property that both planar and time-periodic traveling fronts are monotone in the spatial variable. For equation (1.1), a pulsating front $\phi(x - ct, x)$ is no longer monotone in x in general, but it is in the first variable $\xi = x - ct$. Thus, to make use of this monotonicity, we introduced the new variable τ in (5.3). In what follows, we provide a series of lemmas to verify that the strategy in [57] works for the functions $V^\tau(0, \cdot)$.

Lemma 5.2. *For any $g \in C(\mathbb{R}, [0, 1])$ satisfying (1.18) and any $\varepsilon > 0$, there exist some integers $\tilde{k} = \tilde{k}(g, \varepsilon)$ and $\tilde{m} = \tilde{m}(g, \varepsilon)$ such that $V^{\tilde{k}}(0, \xi) - \varepsilon \leq v(\tilde{m}T, \xi; g) \leq V^{-\tilde{k}}(0, \xi) + \varepsilon$ for all $\xi \in \mathbb{R}$.*

Proof. Let us first set a few notations. Recall that $\delta \in (0, 1/2)$ and $\gamma > 0$ are given in (1.3). Denote $w_1^+(t) = 1 + (1 - \delta)e^{-\gamma t}$ and $w_2^+(t) = \delta e^{-\gamma t}$ for $t \geq 0$, and notice that $(w_1^+)'(t) = \gamma(1 - w_1^+(t))$, $(w_2^+)'(t) = -\gamma w_2^+(t)$ and $0 < w_2^+(t) < w_1^+(t) \leq 2 - \delta$ for all $t \geq 0$. Set $\eta(\xi) = (1 + \tanh(-\xi/2))/2$ for $\xi \in \mathbb{R}$ and notice that $\eta' = -\eta(1 - \eta)$ and $\eta'' = \eta(1 - \eta)(1 - 2\eta)$ in \mathbb{R} . Furthermore, since the function $f(x, u)$ is of class $C^{1,1}$ in u uniformly for $x \in \mathbb{R}$, there exists $K > 0$ such that

$$|f(x, s_1) - f(x, s_2)| + |\partial_u f(x, s_1) - \partial_u f(x, s_2)| \leq K|s_1 - s_2| \quad \text{for all } x, s_1, s_2 \in \mathbb{R}. \quad (5.5)$$

Lastly, define $c^+ = c - \|a\| - \|a'\| - 2K$ and

$$w^+(t, \xi) = w_1^+(t) \eta(\xi + c^+t) + w_2^+(t) (1 - \eta(\xi + c^+t)) \quad \text{for } t \geq 0 \text{ and } \xi \in \mathbb{R}.$$

Let now $g \in C(\mathbb{R}, [0, 1])$ satisfy (1.18). There is $\xi_0 \in \mathbb{N}$ such that $g(\xi + \xi_0) \leq \delta$ for all $\xi \geq 0$. Without loss of generality, even if it means working with the shifted function $g(\cdot + \xi_0)$, one can assume that $\xi_0 = 0$. Next, one shows that w^+ is a supersolution of (5.2). To do so, observe first that $v(0, \xi; g) = g(\xi) \leq w^+(0, \xi)$ for all $\xi \in \mathbb{R}$. On the other hand, for all $t > 0$ and $\xi \in \mathbb{R}$,

$$\begin{aligned} \mathcal{L}(w^+) &:= w_t^+ - c w_\xi^+ - (a(\xi + ct) w_\xi^+)_\xi - f(\xi + ct, w^+) \\ &= \gamma(1 - w_1^+) \eta - \gamma w_2^+ (1 - \eta) - f(\xi + ct, w^+) + c^+ (w_1^+ \eta' - w_2^+ \eta') \\ &\quad - c (w_1^+ \eta' - w_2^+ \eta') - a'(\xi + ct) (w_1^+ \eta' - w_2^+ \eta') - a(\xi + ct) (w_1^+ \eta'' - w_2^+ \eta''), \end{aligned}$$

where η , η' and η'' are taken at $\xi + ct$, while w_1^+ and w_2^+ are taken at t . Remember that $f(x, u) = \partial_u f(x, 1)(u - 1)$ for all $u \geq 1$ and $x \in \mathbb{R}$, with $\partial_u f(x, 1) \leq -\gamma$. It follows from (1.3) and (5.5) that

$$\begin{aligned} & \gamma(1 - w_1^+)\eta - \gamma w_2^+(1 - \eta) - f(\xi + ct, w^+) \\ & \geq f(\xi + ct, w_1^+)\eta + f(\xi + ct, w_2^+)(1 - \eta) - f(\xi + ct, w^+)\eta - f(\xi + ct, w^+)(1 - \eta) \\ & = (\partial_u f(\xi + ct, \vartheta_1 w_1^+ + (1 - \vartheta_1)w^+) - \partial_u f(\xi + ct, \vartheta_2 w_2^+ + (1 - \vartheta_2)w^+))(w_1^+ - w_2^+)\eta(1 - \eta) \\ & \geq -K(w_1^+ - w_2^+)^2 \eta(1 - \eta), \end{aligned}$$

where $\vartheta_1 = \vartheta_1(t, \xi)$, $\vartheta_2 = \vartheta_2(t, \xi) \in [0, 1]$. Then, owing to the definitions of η and c^+ , one has

$$\begin{aligned} \mathcal{L}(w^+) & \geq -K(w_1^+ - w_2^+)^2 \eta(1 - \eta) + (-c^+ + c + a'(\xi + ct))(w_1^+ - w_2^+)\eta(1 - \eta) \\ & \quad - a(\xi + ct)(w_1^+ - w_2^+)\eta(1 - \eta)(1 - 2\eta) \\ & = (2K - K(w_1^+ - w_2^+))(w_1^+ - w_2^+)\eta(1 - \eta) + (\|a'\| + a'(\xi + ct))(w_1^+ - w_2^+)\eta(1 - \eta) \\ & \quad + (\|a\| - a(\xi + ct)(1 - 2\eta))(w_1^+ - w_2^+)\eta(1 - \eta) \\ & \geq 0 \end{aligned}$$

in $(0, +\infty) \times \mathbb{R}$. The parabolic maximum principle implies that $v(t, \xi; g) \leq w^+(t, \xi)$ for all $(t, \xi) \in [0, +\infty) \times \mathbb{R}$.

Finally, let $\varepsilon > 0$ be any positive real number. There exist an integer $\tilde{m} = \tilde{m}(g, \varepsilon)$ and a positive real number $C = C(g, \varepsilon)$ such that $1 < w_1^+(\tilde{m}T) \leq 1 + \varepsilon/2$, $0 < w_2^+(\tilde{m}T) \leq \varepsilon/2$ and $(w_1^+(\tilde{m}T) - w_2^+(\tilde{m}T))\eta(\xi + c^+\tilde{m}T) \leq \varepsilon/2$ for all $\xi \geq C$. Thus, it follows that, for all $\xi \geq C$,

$$v(\tilde{m}T, \xi; g) \leq w^+(\tilde{m}T, \xi) = (w_1^+(\tilde{m}T) - w_2^+(\tilde{m}T))\eta(\xi + c^+\tilde{m}T) + w_2^+(\tilde{m}T) \leq \varepsilon \leq V^0(0, \xi) + \varepsilon.$$

In the case where $\xi < C$, since $\lim_{s \rightarrow +\infty} V^0(0, \xi - s) = 1$ uniformly for $\xi < C$, there exists an integer $\tilde{k} = \tilde{k}(g, \varepsilon)$ such that $v(\tilde{m}T, \xi; g) \leq 1 \leq V^0(0, \xi - \tilde{k}) + \varepsilon = V^{-\tilde{k}}(0, \xi) + \varepsilon$ for all $\xi < C$. Since $V^0(0, \xi) = \phi(\xi, \xi) \leq \phi(\xi - \tilde{k}, \xi) = V^{-\tilde{k}}(0, \xi)$ for all $\xi \in \mathbb{R}$ by Theorem 1.1, one finally gets that $v(\tilde{m}T, \xi; g) \leq V^{-\tilde{k}}(0, \xi) + \varepsilon$ for all $\xi \in \mathbb{R}$.

Similarly, even if it means increasing the integers \tilde{m} and \tilde{k} , one can show that $V^{\tilde{k}}(0, \xi) - \varepsilon \leq v(\tilde{m}T, \xi; g)$ for all $\xi \in \mathbb{R}$, by constructing an analogous subsolution of equation (5.2). More precisely, letting $w_1^-(t) = 1 - \delta e^{-\gamma t}$, $w_2^-(t) = -(1 + \delta)e^{-\gamma t}$ and $c^- = c + \|a\| + \|a'\| + 2K$, the function $w^-(t, \xi) = w_1^-(t)\eta(\xi + c^-t) + w_2^-(t)(1 - \eta(\xi + c^-t))$ defined in $[0, +\infty) \times \mathbb{R}$ is a subsolution of (5.2) and one can conclude as in the previous paragraph. Therefore, the proof of Lemma 5.2 is complete. \square

The above lemma reveals that a ‘‘vaguely resembling wave initial condition’’ (i.e. g satisfying (1.18)) evolves into a ‘‘resembling wave front’’ (i.e. close to 0 and 1 as $\xi \rightarrow \pm\infty$) after a certain time. Next by constructing similar super- and subsolutions of (5.2) as in [23, 52], one shows that a ‘‘resembling wave front’’ preserves its structure uniformly at later times.

Lemma 5.3. (i) *There exist some positive real numbers ε_0 and k_0 such that for any $g \in C(\mathbb{R}, [0, 1])$ satisfying $g \leq V^{\tau_0}(0, \cdot) + \varepsilon$ (resp. $g \geq V^{\tau_0}(0, \cdot) - \varepsilon$) in \mathbb{R} for some $\varepsilon \in (0, \varepsilon_0]$ and $\tau_0 \in \mathbb{R}$, then $v(t, \xi; g) \leq V^{\tau_0 - k_0 \varepsilon}(t, \xi) + \varepsilon e^{-\gamma t/2}$ (resp. $v(t, \xi; g) \geq V^{\tau_0 + k_0 \varepsilon}(t, \xi) - \varepsilon e^{-\gamma t/2}$) for all $t \geq 0$ and $\xi \in \mathbb{R}$.*
(ii) *There exists a positive real number k_1 such that if $\|g - V^{\tau_0}(0, \cdot)\| \leq \varepsilon$ for some $\varepsilon \in (0, \varepsilon_0]$ and $\tau_0 \in \mathbb{R}$, then $\|v(t, \cdot; g) - V^{\tau_0}(t, \cdot)\| \leq k_1 \varepsilon$ for all $t \geq 0$.*

Proof. (i) We only consider the case $g \leq V^{\tau_0}(0, \cdot) + \varepsilon$, since the case $g \geq V^{\tau_0}(0, \cdot) - \varepsilon$ can be treated similarly. The general strategy can be described as follows. We set

$$\bar{V}(t, \xi) := V^{\tau(t)}(t, \xi) + q(t) \quad \text{for } t \geq 0 \text{ and } \xi \in \mathbb{R},$$

where τ and q are $C^1([0, +\infty))$ functions such that $\tau(0) = \tau_0$, $\tau'(t) < 0$ for all $t \geq 0$, $q(0) = \varepsilon$ and $0 < q(t) \leq \varepsilon$ for all $t \geq 0$. Here $\varepsilon > 0$ will be chosen small enough and $\tau_0 \in \mathbb{R}$ is arbitrary. The assumption $g \leq V^{\tau_0}(0, \cdot) + \varepsilon$ in \mathbb{R} means that $g \leq \bar{V}(0, \cdot)$ in \mathbb{R} . By choosing appropriate functions $\tau(t)$ and $q(t)$, one will actually show that $\bar{V}(t, \xi)$ is a supersolution of equation (5.2).

To do so, let $\zeta(t, \xi) = \xi + \tau(t)$ and $x(t, \xi) = \xi + ct$, so that $\bar{V}(t, \xi) = \phi(\zeta(t, \xi), x(t, \xi)) + q(t)$. To avoid any confusion, let us denote here $\partial_1\phi$ and $\partial_2\phi$ the partial derivatives of ϕ with respect to its first and second arguments. A straightforward calculation gives, for all $t > 0$ and $\xi \in \mathbb{R}$,

$$\begin{aligned} \mathcal{L}\bar{V} &= \bar{V}_t - c\bar{V}_\xi - (a(\xi + ct)\bar{V}_\xi)_\xi - f(\xi + ct, \bar{V}) \\ &= \tau'(t)\partial_1\phi + c\partial_2\phi + q'(t) - c(\partial_1\phi + \partial_2\phi) - a'(x)(\partial_1\phi + \partial_2\phi) - a(x)(\partial_1 + \partial_2)^2\phi - f(x, \phi + q(t)) \\ &= \tau'(t)\partial_1\phi + q'(t) - f(x, \phi + q(t)) + f(x, \phi) \\ &\quad - (c\partial_1\phi + a'(x)(\partial_1\phi + \partial_2\phi) + a(x)(\partial_1 + \partial_2)^2\phi + f(x, \phi)), \end{aligned}$$

where ϕ , $\partial_1\phi$ and $\partial_2\phi$ are taken at $(\zeta(t, \xi), x(t, \xi))$, while $x = x(t, \xi)$. Since (ϕ, c) is a pulsating front of equation (1.1), it follows that, for all $t > 0$ and $\xi \in \mathbb{R}$,

$$\mathcal{L}\bar{V} = \tau'(t)\partial_1\phi + q'(t) + f(x, \phi) - f(x, \phi + q(t)). \quad (5.6)$$

Now, since $f(y, u)$ satisfies (1.3) and is of class $C^{1,1}$ in u uniformly in $y \in \mathbb{R}$, there exists a positive real number ε_0 such that, if $(\varepsilon, t, \xi) \in (0, \varepsilon_0] \times [0, +\infty) \times \mathbb{R}$ and $\phi(\zeta(t, \xi), x(t, \xi)) \in [0, \varepsilon_0] \cup [1 - \varepsilon_0, 1]$, then

$$f(x(t, \xi), \phi(\zeta(t, \xi), x(t, \xi))) - f(x(t, \xi), \phi(\zeta(t, \xi), x(t, \xi)) + q(t)) \geq \frac{\gamma q(t)}{2}. \quad (5.7)$$

On the other hand, since the derivative $\partial_1\phi$ is continuous and negative in $\mathbb{R} \times \mathbb{T}$ from Theorem 1.1 and the strong parabolic maximum principle applied to the function U_t , there is $\beta > 0$ such that, if $(\varepsilon, t, \xi) \in (0, \varepsilon_0] \times [0, +\infty) \times \mathbb{R}$ and $\phi(\zeta(t, \xi), x(t, \xi)) \in [\varepsilon_0, 1 - \varepsilon_0]$, then

$$\partial_1\phi(\zeta(t, \xi), x(t, \xi)) \leq -\beta. \quad (5.8)$$

Given these positive parameters ε_0 and β , let us now consider $\varepsilon \in (0, \varepsilon_0]$, $g \in C(\mathbb{R}, [0, 1])$ and $\tau_0 \in \mathbb{R}$ such that $g \leq V^{\tau_0}(0, \cdot) + \varepsilon$ in \mathbb{R} , and let us then choose $q(t)$ and $\tau(t)$ so that

$$q(0) = \varepsilon, \quad q'(t) = -\frac{\gamma q(t)}{2} \text{ for all } t \geq 0, \quad \tau(0) = \tau_0 \text{ and } \tau'(t) = -\frac{2K + \gamma}{2\beta} q(t) \text{ for all } t \geq 0, \quad (5.9)$$

that is $q(t) = \varepsilon e^{-\gamma t/2}$ and $\tau(t) = \tau_0 - \varepsilon(2K + \gamma)(1 - e^{-\gamma t/2})/(\gamma\beta)$ for all $t \geq 0$. It is then easy to check from (5.5-5.9) that $\mathcal{L}\bar{V} \geq 0$ for all $t > 0$ and $\xi \in \mathbb{R}$, while $g \leq \bar{V}(0, \cdot)$ in \mathbb{R} . That is, \bar{V} is a supersolution of (5.2). As a consequence, by the comparison principle, one infers that

$$v(t, \xi; g) \leq V^{\tau(t)}(t, \xi) + q(t) \text{ for all } t \geq 0 \text{ and } \xi \in \mathbb{R}.$$

Since $V^s(t, \xi)$ is decreasing in $s \in \mathbb{R}$, letting $k_0 = (2K + \gamma)/(\gamma\beta) > 0$, one has $\tau(t) \geq \tau_0 - k_0\varepsilon$ for all $t \geq 0$, whence $v(t, \xi; g) \leq V^{\tau_0 - k_0\varepsilon}(t, \xi) + \varepsilon e^{-\gamma t/2}$ for all $t \geq 0$ and $\xi \in \mathbb{R}$. The proof of assertion (i) is thereby complete.

(ii) Since $V^{\tau_0}(0, \xi) - \varepsilon \leq g(\xi) \leq V^{\tau_0}(0, \xi) + \varepsilon$ for all $\xi \in \mathbb{R}$, one sees from assertion (i) that $V^{\tau_0 + k_0\varepsilon}(t, \xi) - \varepsilon e^{-\gamma t/2} \leq v(t, \xi; g) \leq V^{\tau_0 - k_0\varepsilon}(t, \xi) + \varepsilon e^{-\gamma t/2}$ for all $t \geq 0$ and $\xi \in \mathbb{R}$. Therefore,

$$v(t, \xi; g) - V^{\tau_0}(t, \xi) \leq V^{\tau_0 - k_0\varepsilon}(t, \xi) - V^{\tau_0}(t, \xi) + \varepsilon e^{-\gamma t/2} = \phi(\xi + \tau_0 - k_0\varepsilon, \xi + ct) - \phi(\xi + \tau_0, \xi + ct) + \varepsilon e^{-\gamma t/2},$$

and, similarly, $v(t, \xi; g) - V^{\tau_0}(t, \xi) \geq \phi(\xi + \tau_0 + k_0\varepsilon, \xi + ct) - \phi(\xi + \tau_0, \xi + ct) - \varepsilon e^{-\gamma t/2}$ for all $t \geq 0$ and $\xi \in \mathbb{R}$. Since ϕ is globally Lipschitz-continuous, there exists a positive real number k_1 depending only on ϕ and k_0 such that $\|v(t, \cdot; g) - V^{\tau_0}(t, \cdot)\| \leq k_1\varepsilon$ for all $t \geq 0$. The proof of Lemma 5.3 is thereby complete. \square

Lemma 5.3 implies in particular that for each $\tau \in \mathbb{R}$, $V^\tau(0, \cdot)$ is a Lyapunov stable fixed point of the Poincaré map P defined in (5.4). Now we are in a position to employ Lemma 5.1 to prove that the non-stationary pulsating fronts of (1.1) are globally stable. Due to Lemmas 5.2-5.3 and the monotonicity of $V^\tau(t, \xi)$ in τ , the arguments in [57, Theorem 10.2.1] carry through with minor modification. For the sake of completeness, we include the details below.

Proposition 5.4. *Let $\phi(x - ct, x)$ be a pulsating front of equation (1.1) with $L = 1$, $c \neq 0$ and let $u(t, x; g)$ be the solution of (1.17) with $u(0, \cdot; g) = g \in L^\infty(\mathbb{R}, [0, 1])$ satisfying (1.18). Then there exists $\tau_g \in \mathbb{R}$ such that*

$$\sup_{x \in \mathbb{R}} |u(t, x; g) - U(t + \tau_g, x)| = \sup_{x \in \mathbb{R}} |u(t, x; g) - \phi(x - ct - c\tau_g, x)| \rightarrow 0 \text{ as } t \rightarrow +\infty,$$

that is, $\|v(t, \cdot; g) - V^{-c\tau_g}(t, \cdot)\| \rightarrow 0$ as $t \rightarrow +\infty$.

Proof. Recall that $P : C(\mathbb{R}, [0, 1]) \rightarrow C(\mathbb{R}, [0, 1])$ is the Poincaré map defined in (5.4), that is, $P(\varphi) = v(T, \cdot; \varphi)$ for all $\varphi \in C(\mathbb{R}, [0, 1])$. We are going to apply Lemma 5.1 with $E = C(\mathbb{R}, \mathbb{R})$ endowed with the norm $\|\cdot\| = \|\cdot\|_{L^\infty(\mathbb{R})}$ and the standard order between real-valued functions, $C = C(\mathbb{R}, [0, 1])$ and $F = P$. We first notice that C is a closed and ordered convex subset of E and that the map $P : C \rightarrow C$ is monotone and continuous, by the parabolic maximum principle.

Consider now any $g \in L^\infty(\mathbb{R}, [0, 1])$ satisfying (1.18). Since $v(t, \cdot; g) \in C(\mathbb{R}, [0, 1])$ for all $t > 0$ and since $\limsup_{\xi \rightarrow -\infty} (1 - v(t, \xi; g)) \leq (\limsup_{\xi \rightarrow -\infty} (1 - g(\xi)))e^{Kt}$ and $\limsup_{\xi \rightarrow +\infty} v(t, \xi; g) \leq (\limsup_{\xi \rightarrow +\infty} g(\xi))e^{Kt}$ for all $t > 0$ with K as in (5.5), one can assume without loss of generality that $g \in C(\mathbb{R}, [0, 1])$ satisfies (1.18), even if it means replacing g by $v(\rho, \cdot; g)$ for some small enough $\rho > 0$. Under the notations ε_0 and k_0 of Lemma 5.3 (i), fix any $\varepsilon \in (0, \varepsilon_0]$. Lemmas 5.2 and 5.3 provide the existence of some integers $\tilde{k} = \tilde{k}(g, \varepsilon)$ and $\tilde{m} = \tilde{m}(g, \varepsilon)$ such that

$$V^{\tilde{k}+k_0\varepsilon}(t, \xi) - \varepsilon e^{-\gamma t/2} \leq v(\tilde{m}T + t, \xi; g) \leq V^{-\tilde{k}-k_0\varepsilon}(t, \xi) + \varepsilon e^{-\gamma t/2} \text{ for all } t \geq 0 \text{ and } \xi \in \mathbb{R}. \quad (5.10)$$

Since the sequence $(P^n(g))_{n \geq 1} = (v(nT, \cdot; g))_{n \geq 1}$ is bounded in $C^1(\mathbb{R}, \mathbb{R})$ by standard parabolic estimates and since $V^\tau(t, -\infty) = 1$ and $V^\tau(t, +\infty) = 0$ uniformly in $t \in \mathbb{R}$, it then follows from (5.10) that the forward orbit $\gamma^+(g) = \{P^n(g) \mid n \in \mathbb{N}\}$ is precompact in $C(\mathbb{R}, [0, 1])$. Hence, the ω -limit set $\omega(g)$ is nonempty, compact and invariant by P . Letting $p = \tilde{k} + k_0\varepsilon > 0$ and $t = nT$ in (5.10), one then concludes that

$$\omega(g) \subset I := \{\varphi \in C(\mathbb{R}, [0, 1]) \mid V^p(0, \cdot) \leq \varphi \leq V^{-p}(0, \cdot) \text{ in } \mathbb{R}\} \subset C.$$

Now define $h(s) = V^{p-2ps}(0, \cdot)$ for $s \in [0, 1]$. Thus, $I = [h(0), h(1)]_E$ and h is an increasing homeomorphism from $[0, 1]$ onto a subset of C . On the other hand, by Lemma 5.3 (ii), $h(s)$ is a stable fixed point for P for each $s \in [0, 1]$. As done for g , one can also observe that for each $\varphi \in I = [h(0), h(1)]_E$, the forward orbit $\gamma^+(\varphi)$ is included in I and precompact in $C(\mathbb{R}, [0, 1])$.

Let us finally check the last condition in Lemma 5.1. To do so, assume that $h(s_0) <_E \omega(\varphi_0)$ for some $s_0 \in [0, 1)$ and $\varphi_0 \in I$. In other words, one has $h(s_0) <_E \varphi$, that is, $V^{p-2ps_0}(0, \cdot) \leq \varphi$ in \mathbb{R} and $V^{p-2ps_0}(0, \cdot) \not\equiv \varphi$, for all $\varphi \in \omega(\varphi_0)$. By the strong maximum principle, there holds $V^{p-2ps_0}(t, \xi) < v(t, \xi; \varphi)$ for all $t > 0$ and $\xi \in \mathbb{R}$, whence $V^{p-2ps_0}(T, \cdot) < P(\varphi)$ in \mathbb{R} . By the T -periodicity of V^{p-2ps_0} and the invariance of $\omega(\varphi_0)$ for P , it then follows that

$$V^{p-2ps_0}(0, \cdot) < \varphi \text{ in } \mathbb{R} \text{ for all } \varphi \in \omega(\varphi_0). \quad (5.11)$$

Furthermore, since $V^\tau(0, \xi) = \phi(\xi + \tau, \xi)$ and $\lim_{\xi \rightarrow \pm\infty} \partial_\xi \phi(\xi, x) = 0$ uniformly in $x \in \mathbb{R}$, there is $M > 0$ such that

$$0 < \tilde{\delta} := \sup_{s, s' \in [0, 3/2], s \neq s', |\xi| \geq M} \frac{|V^{p-2ps}(0, \xi) - V^{p-2ps'}(0, \xi)|}{|s - s'|} \leq \min\left(\frac{2\varepsilon_0}{5}, \frac{2p}{5k_0}\right). \quad (5.12)$$

On the other hand, since $\omega(\varphi_0)$ is compact, it follows then from (5.11) that there exists a real number $s_1 \in (s_0, 1)$ such that $V^{p-p(3s_1-s_0)}(0, \xi) < \varphi(\xi)$ for all $\xi \in [-M, M]$ and $\varphi \in \omega(\varphi_0)$.

Let $\varphi \in \omega(\varphi_0)$ be given. Then there is a sequence $n_j \rightarrow +\infty$ such that $\|P^{n_j}(\varphi_0) - \varphi\| \rightarrow 0$ as $j \rightarrow +\infty$. Let $n_k \in \mathbb{N}$ be such that $\|P^{n_k}(\varphi_0) - \varphi\| \leq \tilde{\delta}(s_1 - s_0)$. Since $\varphi(\xi) - V^{p-p(3s_1-s_0)}(0, \xi) > 0$ for all $\xi \in [-M, M]$ and $\varphi(\xi) - V^{p-p(3s_1-s_0)}(0, \xi) > V^{p-2ps_0}(0, \xi) - V^{p-p(3s_1-s_0)}(\xi)$ for all $\xi \in \mathbb{R}$, one infers that

$$\begin{aligned} P^{n_k}(\varphi_0)(\xi) - V^{p-p(3s_1-s_0)}(0, \xi) &\geq -\|P^{n_k}(\varphi_0) - \varphi\| + \varphi(\xi) - V^{p-p(3s_1-s_0)}(0, \xi) \\ &\geq -\tilde{\delta}(s_1 - s_0) - \sup_{|\xi| \geq M} |V^{p-2ps_0}(0, \xi) - V^{p-p(3s_1-s_0)}(0, \xi)| \\ &\geq -\frac{5\tilde{\delta}(s_1 - s_0)}{2} \geq -\varepsilon_0 \end{aligned}$$

for all $\xi \in \mathbb{R}$, by (5.12). Thus, by Lemma 5.3 (i), there holds

$$v(t, \xi; P^{n_k}(\varphi_0)) \geq V^{p-p(3s_1-s_0)+5k_0\tilde{\delta}(s_1-s_0)/2}(t, \xi) - \frac{5\tilde{\delta}(s_1 - s_0)}{2} e^{-\gamma t/2} \text{ for all } t > 0 \text{ and } \xi \in \mathbb{R}.$$

Letting $t = (n_j - n_k)T$ and $j \rightarrow +\infty$ yields $\varphi \geq V^{p-p(3s_1-s_0)+5k_0\tilde{\delta}(s_1-s_0)/2}(0, \cdot) \geq V^{p-2ps_1}(0, \cdot)$ in \mathbb{R} since $p - p(3s_1 - s_0) + 5k_0\tilde{\delta}(s_1 - s_0)/2 \leq p - 2ps_1$ by (5.12) and V^τ is decreasing with respect to τ . Hence, $\omega(\varphi_0) \geq_E V^{p-2ps_1}(0, \cdot) = h(s_1)$.

Finally, since $\emptyset \neq \omega(g) \subset I = [h(0), h(1)]_E$, it follows from Lemma 5.1 that there is $s_g \in [0, 1]$ such that $\omega(g) = \{h(s_g)\} = \{V^{p-2ps_g}(0, \cdot)\}$. That is, $\lim_{n \rightarrow +\infty} \|P^n(g) - V^{p-2ps_g}(0, \cdot)\| = 0$. It then follows from Lemma 5.3 (ii) that $\lim_{t \rightarrow +\infty} \|v(t, \cdot; g) - V^{p-2ps_g}(t, \cdot)\| = 0$. Since $v(t, x - ct; g) = u(t, x; g)$ and $V^{p-2ps_g}(t, x - ct) = \phi(x - ct + p - 2ps_g, x)$ for all $t \geq 0$ and $x \in \mathbb{R}$, one gets the conclusion of Proposition 5.4 with $\tau_g = (2ps_g - p)/c$. \square

Remark 5.5. Proposition 5.4 gives the global stability of non-stationary pulsating fronts for equation (1.1), if they exist. The proof only relies on the assumption (1.3) and that $f(x, 0) = f(x, 1) = 0$ for all $x \in \mathbb{R}$, as well as the time-monotonicity property of non-stationary pulsating fronts stated in Theorem 1.1. Furthermore, the uniqueness results stated in Theorem 1.1 can be viewed as consequences of Proposition 5.4 (see the proof of Theorem 1.1 in Section 2.2).

5.2 Exponential stability of pulsating fronts

Here, we prove Theorem 1.9 by using the general theory of exponential stability of invariant manifolds with asymptotic phase. This theory was first established by Henry [33] in the context of reaction-diffusion equations, and then applied to bistable time-periodic equations in [2]. Once again, one assumes that $L = 1$ and that (1.1) admits a pulsating front $U(t, x) = \phi(x - ct, x)$ with a speed $c > 0$. Consider the moving coordinates (ξ, t) defined in (5.1) and the resulting time-periodic parabolic equation (5.2). One uses the notations $T = 1/c$ and V^τ given in (5.3), and $P : C(\mathbb{R}, [0, 1]) \rightarrow C(\mathbb{R}, [0, 1])$ is the Poincaré map defined in (5.4). Note that $\widetilde{\mathcal{M}} := \{V^\tau \mid \tau \in \mathbb{R}\} \subset C(\mathbb{R}^2, [0, 1])$ is a one-dimensional manifold of special solutions of (5.2). By Proposition 5.4, $\widetilde{\mathcal{M}}$ attracts the solutions of the Cauchy problem of (5.2) with initial values g satisfying (1.18). In order to show that this convergence is also exponential in time, it is sufficient to prove the local exponential stability of the manifold

$$\mathcal{M} := \{V^\tau(0, \cdot) \mid \tau \in \mathbb{R}\} \subset C(\mathbb{R}, [0, 1]).$$

Notice that since each element in \mathcal{M} is a fixed point of P , the manifold \mathcal{M} is invariant under P .

One is thus interested in the linearization of P around the points of \mathcal{M} . Without loss of generality, consider the point $V_0 := V^0(0, \cdot)$. Let $\mathcal{X} = BUC(\mathbb{R}, \mathbb{C})$ be the Banach space of bounded and uniformly continuous functions on \mathbb{R} , with the norm $\| \cdot \| = \| \cdot \|_{L^\infty(\mathbb{R}, \mathbb{C})}$. It is easy to check that the derivative of P at V_0 is given by $P'(V_0)(w) = W(T, \cdot; w)$ for $w \in \mathcal{X}$, where $W(t, \xi; w)$ obeys

$$\begin{cases} W_t = (a(\xi + ct)W_\xi)_\xi + cW_\xi + \partial_u f(\xi + ct, V^0(t, \xi))W, & t > 0, \xi \in \mathbb{R}, \\ W(0, \xi) = w(\xi), & \xi \in \mathbb{R}. \end{cases}$$

Denote $W^0(t, \xi) := \partial_\tau V^\tau(t, \xi)|_{\tau=0} = \partial_1 \phi(\xi, \xi + ct)$ and notice that 1 is an eigenvalue of $P'(V_0)$ with eigenfunction $w_0 := W^0(0, \cdot) \in \mathcal{X}$. As in [2], in order to prove the local exponential stability of \mathcal{M} , we need to show that 1 is algebraically simple, and that the rest of the spectrum is contained in a disk of radius strictly less than 1. Namely, we prove the following two lemmas.

Lemma 5.6. *The value 1 is an algebraically simple eigenvalue of $P'(V_0)$ with eigenfunction w_0 and, if $\lambda \in \mathbb{C}$ is an eigenvalue of $P'(V_0)$ with eigenfunction $w \notin \mathbb{C}w_0$, then $|\lambda| < 1$.*

Proof. Assume that $\lambda \in \mathbb{C}^*$ is an eigenvalue of $P'(V_0)$ with eigenfunction $w \in \mathcal{X}$. Let $\mu \in \mathbb{C}$ be such that $e^{\mu T} = 1/\lambda$ and set $h(t, \xi) = e^{\mu t}W(t, \xi; w)$ for $t \geq 0$ and $\xi \in \mathbb{R}$. The function h satisfies

$$\begin{cases} h_t - (a(\xi + ct)h_\xi)_\xi - ch_\xi - \partial_u f(\xi + ct, V^0(t, \xi))h = \mu h & \text{for all } t > 0 \text{ and } \xi \in \mathbb{R}, \\ h(0, \xi) = h(T, \xi) & \text{for all } \xi \in \mathbb{R}. \end{cases} \quad (5.13)$$

Hence, the eigenvalue problem $P'(V_0)(w) = \lambda w$ can be recast as the spectral problem (5.13) in the space of time periodic functions $\{h \in C(\mathbb{R}^2, \mathbb{C}) \mid h(t, \cdot) = h(t + T, \cdot) \text{ for all } t \in \mathbb{R}\}$. Clearly, W^0 solves (5.13) with $\mu = 0$. In addition, following arguments similar to the ones in Step 3 of the proof of Lemma 4.1 or in [2, Lemma A.2], one infers that if $h \notin \mathbb{C}W^0$ solves (5.13) with some $\mu \in \mathbb{C}$, then $\text{Re}(\mu) > 0$. In other words, if $w \notin \mathbb{C}w_0$, then $|\lambda| < 1$.

On the other hand, since $t = (x - \xi)/c$, setting $\psi(\xi, x) = h(t, \xi)$ in (5.13) yields

$$\tilde{\partial}(a(x)\tilde{\partial}\psi) + c\partial_\xi\psi + \partial_u f(x, \phi(\xi, x))\psi = -\mu\psi \text{ for all } (\xi, x) \in \mathbb{R}^2, \quad \psi(\xi, x+1) = \psi(\xi, x) \text{ for all } (\xi, x) \in \mathbb{R}^2,$$

where $\tilde{\partial} = \partial_\xi + \partial_x$. But, from Lemma 4.1 and standard parabolic estimates, it follows that 0 is an algebraically simple eigenvalue of the operator H_1 defined in (4.1) with $L_0 = 1$ in the space of spatially periodic functions $\mathcal{E} := \{\psi \in BUC(\mathbb{R}^2, \mathbb{C}) \mid \psi(\xi, x) = \psi(\xi, x+1) \text{ for all } (\xi, x) \in \mathbb{R}^2\}$.⁵ Thus, 1 is an algebraically simple eigenvalue of $P'(V_0)$ and the proof of Lemma 5.6 is complete. \square

Lemma 5.7. *The essential spectrum of $P'(V_0)$ is contained in the disk $\{\lambda \in \mathbb{C} \mid |\lambda| \leq e^{-\gamma T/2}\}$. Thus, if λ is in the spectrum of $P'(V_0)$ and $|\lambda| > e^{-\gamma T/2}$, then λ is an eigenvalue, and for any $r > e^{-\gamma T/2}$, there are only finitely many eigenvalues of $P'(V_0)$ in $\{\lambda \in \mathbb{C} \mid |\lambda| \geq r\}$.*

Proof. Firstly, (1.3) yields the existence of $N > 0$ such that $\partial_u f(\xi + ct, V^0(t, \xi)) \leq -\gamma/2$ for all $t \in \mathbb{R}$ and $|\xi| \geq N$. Let $\kappa_1(t, \xi)$ and $\kappa_2(t, \xi)$ be the continuous T -periodic functions defined by

$$\kappa_1(t, \xi) = \begin{cases} \partial_u f(\xi + ct, V^0(t, \xi)) & \text{if } \xi \leq -N, \\ \partial_u f(-N + ct, V^0(t, -N)) & \text{if } \xi > -N, \end{cases} \quad \kappa_2(t, \xi) = \begin{cases} \partial_u f(\xi + ct, V^0(t, \xi)) & \text{if } \xi \geq N, \\ \partial_u f(N + ct, V^0(t, N)) & \text{if } \xi < N. \end{cases}$$

⁵We point out that for any $\psi \in \mathcal{E}$ such that $H_1(\psi) = 0$ in the sense of distributions, one can assume without loss of generality that ψ is real valued, and the function ψ is a classical solution by parabolic estimates. Hence $\psi(\pm\infty, x) = 0$ uniformly in $x \in \mathbb{R}$ because of (1.3) and ψ and its derivatives decay exponentially as $\xi \rightarrow \pm\infty$, as in Lemma 2.1. Thus, $\psi \in \mathcal{D}_1$.

Let $\varsigma \in C(\mathbb{R}, [0, 1])$ be a function satisfying $\varsigma(\xi) = 0$ for $\xi \leq -N$ and $\varsigma(\xi) = 1$ for $\xi \geq N$, and define $\kappa(t, \xi) = (1 - \varsigma(\xi))\kappa_1(t, \xi) + \varsigma(\xi)\kappa_2(t, \xi)$ for $(t, \xi) \in \mathbb{R}^2$. The function κ is continuous in \mathbb{R}^2 , bounded, T -periodic with respect to t , and $\kappa \leq -\gamma/2$ in \mathbb{R}^2 . Consider now the operator \mathcal{K} defined on \mathcal{X} by $\mathcal{K}(w) = \widehat{W}(T, \xi; w)$ for $w \in \mathcal{X}$, where $\widehat{W}(t, \xi; w)$ solves the equation

$$\begin{cases} \widehat{W}_t = (a(\xi + ct)\widehat{W}_\xi)_\xi + c\widehat{W}_\xi + \kappa(t, \xi)\widehat{W}, & t > 0, \xi \in \mathbb{R} \\ \widehat{W}(0, \cdot; w) = w. \end{cases}$$

By the maximum principle, $\|\widehat{W}(t, \cdot; w)\| \leq e^{-\gamma t/2}\|w\|$ for all $t > 0$, whence $\|\mathcal{K}(w)\| \leq e^{-\gamma T/2}\|w\|$ for all $w \in \mathcal{X}$. Thus, the spectral radius of \mathcal{K} is at most $e^{-\gamma T/2}$.

Next, one shows that $\mathcal{K} - P'(V_0) : \mathcal{X} \rightarrow \mathcal{X}$ is a compact operator. To do so, consider a bounded sequence $(w_n)_{n \in \mathbb{N}}$ in \mathcal{X} and denote $\eta_n = (\mathcal{K} - P'(V_0))(w_n)$ for $n \in \mathbb{N}$. From standard parabolic estimates, up to extraction of some subsequence, the functions η_n converge to a function η_∞ , locally uniformly as $n \rightarrow +\infty$, with $\eta_\infty \in \mathcal{X}$. To show the uniform convergence in \mathbb{R} , one needs to estimate the values of $\eta_n(\xi)$ for $|\xi| \geq N$ uniformly in $n \in \mathbb{N}$. Without loss of generality, one can assume that the functions w_n (and η_n) are real-valued and one only considers the case $\xi \leq -N$ since the case $\xi \geq N$ can be dealt with similarly. For each $n \in \mathbb{N}$, let $\Phi_n(t, \xi) := \widehat{W}(t, \xi; w_n) - W(t, \xi; w_n)$ for $t \geq 0$ and $\xi \leq -N$. Owing to the definition of κ , each function Φ_n solves

$$\begin{cases} (\Phi_n)_t = (a(\xi + ct)(\Phi_n)_\xi)_\xi + c(\Phi_n)_\xi + \kappa(t, \xi)\Phi_n, & t > 0, \xi \leq -N, \\ \Phi_n(0, \xi) = 0, & \xi \leq -N. \end{cases} \quad (5.14)$$

As in Lemma 2.1, for any $\nu \in \mathbb{R}$, the linear operator \mathcal{T}_ν defined on $\{\varphi \in C^2(\mathbb{R}) \mid \varphi = \varphi(\cdot + 1) \text{ in } \mathbb{R}\}$ by $\mathcal{T}_\nu[\varphi] := (a\varphi')' + 2\nu a\varphi' + (\nu a' + c\nu + a\nu^2 - \gamma/2)\varphi$ admits a principal eigenvalue $\lambda_1(\nu)$, and there is $\nu_1 > 0$ such that $\lambda_1(\nu_1) = 0$. Let φ_{ν_1} be a positive corresponding eigenfunction. Since $\sup_{t \in [0, T], n \in \mathbb{N}} \|\Phi_n(t, \cdot)\| < +\infty$ by the parabolic maximum principle and the boundedness of the sequence $(w_n)_{n \in \mathbb{N}}$ in \mathcal{X} , there is a constant $A > 0$ such that

$$Ae^{-\nu_1 N} \varphi_{\nu_1}(-N + ct) \geq |\Phi_n(t, -N)| \quad \text{for all } t \in [0, T] \text{ and } n \in \mathbb{N}.$$

An immediate computation shows that $Ae^{\nu_1 \xi} \varphi_{\nu_1}(\xi + ct)$ is a supersolution of (5.14) in $[0, T] \times (-\infty, -N]$, whence $|\eta_n(\xi)| = |\Phi_n(T, \xi)| \leq Ae^{\nu_1 \xi} \varphi_{\nu_1}(\xi + cT)$ for all $\xi \leq -N$ and $n \in \mathbb{N}$ by the maximum principle. Thus, $\eta_n(\xi)$ converges to 0 as $\xi \rightarrow \pm\infty$ uniformly in $n \in \mathbb{N}$. Together with the local convergence of the functions η_n to η_∞ , one concludes that $\|\eta_n - \eta_\infty\| \rightarrow 0$ as $n \rightarrow +\infty$.

Finally, there are then finitely many eigenvalues of $P'(V_0)$ in $\{\lambda \in \mathbb{C} \mid |\lambda| \geq r\}$ for any $r > e^{-\gamma T/2}$ and the essential spectrum of $P'(V_0)$ is the same as that of \mathcal{K} , whence the radius of essential spectrum of $P'(V_0)$ is not larger than $e^{-\gamma T/2}$. \square

End of the proof of Theorem 1.9. Consider any $g \in L^\infty(\mathbb{R}, [0, 1])$ satisfying (1.18). As in the proof of Proposition 5.4, one can assume that $g \in C(\mathbb{R}, [0, 1])$. By Proposition 5.4, there is $\tau_g \in \mathbb{R}$ such that $\|u(t, \cdot; g) - U(t + \tau_g, \cdot)\| = \|v(t, \cdot; g) - V^{-c\tau_g}(t, \cdot)\| \rightarrow 0$ as $t \rightarrow +\infty$. Without loss of generality, even if it means shifting U in time, one can assume that $\tau_g = 0$. From Lemmas 5.6 and 5.7, 1 is an algebraically simple eigenvalue of $P'(V_0)$ and the rest of the spectrum of $P'(V_0)$ is contained in a disk with radius $\tilde{r}(P'(V_0)) \in (0, 1)$. Therefore, the manifold \mathcal{M} is locally exponentially stable with asymptotic phase for P , see [33, Chapter 9]. Since $P(V_0) = V_0 = V^0(0, \cdot)$ and $\|P^n(g) - V_0\| = \|v(nT, \cdot; g) - V^0(nT, \cdot)\| \rightarrow 0$ as $n \rightarrow +\infty$, there are then some real numbers $\mu = -\ln((\tilde{r}(P'(V_0)) + 1)/2) > 0$ independent of g , and C depending on g , such that

$$\|v(nT, \cdot; g) - V_0\| = \|P^n(g) - V_0\| \leq Ce^{-\mu Tn} \quad \text{for all } n \in \mathbb{N}.$$

Under the notations of Lemma 5.3, there is then $n_0 \in \mathbb{N}$ such that $\|v(nT, \cdot; g) - V_0\| \leq Ce^{-\mu T n} \leq \varepsilon_0$ for all $n \in \mathbb{N}$ with $n \geq n_0$, whence $\|v(nT+t, \cdot; g) - V^0(t, \cdot)\| \leq k_1 Ce^{-\mu T n}$ for all $n \geq n_0$ and $t \in [0, T]$. Since V^0 is T -periodic in t , one infers that $\|v(t, \cdot; g) - V^0(t, \cdot)\| \leq k_1 Ce^{\mu T} e^{-\mu t}$ for all $t \geq n_0 T$. Finally, since $0 \leq v(\cdot, \cdot; g)$, $V^0 \leq 1$ in $[0, +\infty) \times \mathbb{R}$, there is a constant C_g (depending on g and on the parameters of (1.1)) such that $\|v(t, \cdot; g) - V^0(t, \cdot)\| \leq C_g e^{-\mu t}$ for all $t \geq 0$. Since $v(t, x - ct; g) = u(t, x; g)$ and $V^0(t, x - ct) = \phi(x - ct, x) = U(t, x)$, one concludes that $\|u(t, \cdot; g) - U(t, \cdot)\| \leq C_g e^{-\mu t}$ for all $t \geq 0$ and the proof of Theorem 1.9 is thereby complete. \square

5.3 Proof of Theorem 1.10

This section is devoted to the proof of Theorem 1.10. That is, we show that any solution of (1.17) with initial value satisfying (1.20) converges to a translate (in time) of the pulsating front of equation (1.1), and this convergence is exponential in time. Thanks to the assumption that all L -periodic stationary states of equation (1.1) are unstable, we will prove that such solution of (1.17) will evolve into a ‘‘front-like’’ wave (i.e., satisfying (1.18)) after a certain time. Then the conclusion of Theorem 1.10 will follow easily from Theorem 1.9.

Proof of Theorem 1.10. Since the initial value g satisfies (1.20), there is $\sigma > 0$ such that

$$\liminf_{x \rightarrow -\infty} (g(x) - \bar{u}_-(x)) \geq 2\sigma, \quad \bar{u}_- + 2\sigma < 1 \text{ in } \mathbb{R}, \quad (5.15)$$

and $\limsup_{x \rightarrow +\infty} (g(x) - \bar{u}_+(x)) \leq -2\sigma$ with $\bar{u}_+ - 2\sigma > 0$ in \mathbb{R} . Let $u^\pm(t, x)$ denote the solutions of the Cauchy problems

$$\begin{cases} u_t^\pm = (a_L(x)u_x^\pm)_x + f_L(x, u^\pm), & t > 0, \quad x \in \mathbb{R}, \\ u^\pm(0, x) = \bar{u}_\pm \mp \sigma, & x \in \mathbb{R}. \end{cases}$$

Since by assumption \bar{u}_\pm are unstable, it follows as in Step 2 of Lemma 3.7 that $u^-(t, x) \rightarrow 1$ and $u^+(t, x) \rightarrow 0$ as $t \rightarrow +\infty$ uniformly in $x \in \mathbb{R}$.

Next, one shows that $\liminf_{x \rightarrow -\infty} (u(t, x) - u^-(t, x)) > 0$ for all $t > 0$. Assume by contradiction that there are $t_0 > 0$ and a sequence $(x_n)_{n \in \mathbb{N}}$ with $\lim_{n \rightarrow +\infty} x_n = -\infty$ and

$$\lim_{n \rightarrow +\infty} (u(t_0, x_n) - u^-(t_0, x_n)) \leq 0. \quad (5.16)$$

By (5.15) and since g ranges in $[0, 1]$, there is a $C^{2,\alpha}(\mathbb{R}, [0, 1])$ function \underline{u}_0 such that $\underline{u}_0 \leq g$ in \mathbb{R} , $\underline{u}_0(x) = 0$ for $x \gg 1$ and $\underline{u}_0(x) = \bar{u}_-(x) + 3\sigma/2$ for $x \ll -1$. Let \underline{u} be the solution of the Cauchy problem (1.17) with initial condition $\underline{u}(0, \cdot) = \underline{u}_0$. The maximum principle yields $0 \leq \underline{u}(t, x) \leq u(t, x) \leq 1$ for all $t > 0$ and $x \in \mathbb{R}$. Write now $x_n = x'_n + x''_n$ with $x'_n \in L\mathbb{Z}$ and $x''_n \in [0, L]$, and set $\underline{u}_n(t, x) = \underline{u}(t, x + x'_n)$. Since a_L and f_L are L -periodic in x , the functions \underline{u}_n obey (1.1) for $t \geq 0$ and $x \in \mathbb{R}$. Up to extraction of some subsequence, one can assume that $x''_n \rightarrow x_\infty \in [0, L]$ as $n \rightarrow +\infty$ and that, from standard parabolic estimates, $\underline{u}_n(t, x) \rightarrow \underline{u}_\infty(t, x)$ as $n \rightarrow +\infty$ locally uniformly in $[0, +\infty) \times \mathbb{R}$, where \underline{u}_∞ solves (1.1).⁶ In particular, for any $x \in \mathbb{R}$, $\underline{u}_\infty(0, x) = \lim_{n \rightarrow +\infty} \underline{u}_n(0, x) = \bar{u}_-(x) + 3\sigma/2 > u^-(0, x)$, whence $\underline{u}_\infty(t, x) > u^-(t, x)$ for all $t \geq 0$ and $x \in \mathbb{R}$ by the maximum principle. On the other hand, since $\underline{u} \leq u$ and u^- is L -periodic in x , (5.16) yields

$$\underline{u}_\infty(t_0, x_\infty) = \lim_{n \rightarrow +\infty} \underline{u}_n(t_0, x''_n) = \lim_{n \rightarrow +\infty} \underline{u}(t_0, x_n) \leq \limsup_{n \rightarrow +\infty} u(t_0, x_n) \leq \limsup_{n \rightarrow +\infty} u^-(t_0, x_n) = u^-(t_0, x_\infty).$$

This contradicts $\underline{u}_\infty(t_0, x_\infty) > u^-(t_0, x_\infty)$. Hence $\liminf_{x \rightarrow -\infty} (u(t, x) - u^-(t, x)) > 0$ for every $t > 0$. Similarly, there holds $\lim_{t \rightarrow +\infty} u^+(t, x) = 0$ uniformly in $x \in \mathbb{R}$ and $\limsup_{x \rightarrow +\infty} (u(t, x) - u^+(t, x)) < 0$

⁶The reason why we introduced \underline{u} is that $\underline{u}(0, \cdot)$ is smooth and thus the functions \underline{u}_n converge locally in space up to time $t = 0$, while the translations of u do not in general if g is not smooth enough.

for every $t > 0$. Thus, there is $T > 0$ such that $\liminf_{x \rightarrow -\infty} u(T, x) > 1 - \delta$ and $\limsup_{x \rightarrow +\infty} u(T, x) < \delta$, where δ is the constant given in (1.3). By Theorem 1.9, as applied to initial value $u(T, \cdot)$, the conclusion of Theorem 1.10 follows. \square

6 Appendix

The appendix is devoted to the proof of some technical auxiliary lemmas which were stated in Section 3 and used in the proofs of Theorems 1.2 and 1.8. We first begin with the proofs of the properties of the operators $M_{c,L}$ and $M_{c,0}$ stated in Lemmas 3.1, 3.2 and 3.3.

Proof of Lemma 3.1. Consider only the case $L \neq 0$, since the case $L = 0$ follows the same lines, and is actually simpler. Let $\beta > 0$, $c > 0$ and $L > 0$ be fixed, and let v be in the kernel of $M_{c,L}$. Integrating $M_{c,L}(v) = 0$ against v in $L^2(\mathbb{R} \times \mathbb{T})$ gives $\int_{\mathbb{R} \times \mathbb{T}} (a(y)(\tilde{\partial}_L v)^2 + \beta v^2) = 0$, whence $v = 0$. The adjoint operator $M_{c,L}^*$ of $M_{c,L}$ is defined as $M_{c,L}^*(v) = \tilde{\partial}_L(a\tilde{\partial}_L v) - c\partial_\xi v - \beta v$ with domain \mathcal{D}_L , in such a way that $(M_{c,L}^*(v), u)_{L^2(\mathbb{R} \times \mathbb{T})} = (v, M_{c,L}(u))_{L^2(\mathbb{R} \times \mathbb{T})}$ for any $u, v \in \mathcal{D}_L$. The same arguments yield that the kernel of the operator $M_{c,L}^*$ is reduced to $\{0\}$. Then in order to get the invertibility of the linear operator $M_{c,L}$, it is sufficient to show that the range $R(M_{c,L})$ is closed in $L^2(\mathbb{R} \times \mathbb{T})$. To do so, let $M_{c,L}(v_n) = g_n$ with $v_n \in \mathcal{D}_L$ and $g_n \rightarrow g$ in $L^2(\mathbb{R} \times \mathbb{T})$ as $n \rightarrow +\infty$. Integrating $M_{c,L}(v_n) = g_n$ against v_n gives $\int_{\mathbb{R} \times \mathbb{T}} ((a(y)(\tilde{\partial}_L v_n)^2 + \beta v_n^2)) = - \int_{\mathbb{R} \times \mathbb{T}} g_n v_n$, whence

$$\int_{\mathbb{R} \times \mathbb{T}} a(y) (\tilde{\partial}_L v_n)^2 + \frac{\beta}{2} v_n^2 \leq \frac{1}{2\beta} \int_{\mathbb{R} \times \mathbb{T}} g_n^2. \quad (6.1)$$

For any $h > 0$, let us define the symmetric difference quotient in ξ -direction as follows: $D_h v_n(\xi, y) = (v_n(\xi + h, y) - v_n(\xi - h, y))/(2h)$ for $(\xi, y) \in \mathbb{R} \times \mathbb{T}$ and notice that $D_h v_n \in H^1(\mathbb{R} \times \mathbb{T})$. Taking it as a test function in $M_{c,L}(v_n) = g_n$, one gets that

$$\int_{\mathbb{R} \times \mathbb{T}} a(y) \tilde{\partial}_L v_n \tilde{\partial}_L D_h v_n - c \tilde{\partial}_L v_n D_h v_n + \beta v_n D_h v_n = - \int_{\mathbb{R} \times \mathbb{T}} g_n D_h v_n.$$

Observe that $\int_{\mathbb{R} \times \mathbb{T}} a(y) (\tilde{\partial}_L D_h v_n) \tilde{\partial}_L v_n = \int_{\mathbb{R} \times \mathbb{T}} \beta (D_h v_n) v_n = 0$, and that $D_h v_n \rightarrow \partial_\xi v_n$ in $L^2(\mathbb{R} \times \mathbb{T})$ weakly as $h \rightarrow 0^+$. Hence, by letting $h \rightarrow 0$, one concludes that

$$\int_{\mathbb{R} \times \mathbb{T}} c (\partial_\xi v_n)^2 = \int_{\mathbb{R} \times \mathbb{T}} g_n \partial_\xi v_n, \quad (6.2)$$

and then, by the Cauchy-Schwarz inequality,

$$\|\partial_\xi v_n\|_{L^2(\mathbb{R} \times \mathbb{T})} \leq \frac{\|g_n\|_{L^2(\mathbb{R} \times \mathbb{T})}}{c}. \quad (6.3)$$

The uniform L^2 -estimate for $\partial_y v_n$ can be obtained from (6.1) and (6.3) as follows:

$$\begin{aligned} \|\partial_y v_n\|_{L^2(\mathbb{R} \times \mathbb{T})} &= \|L(\tilde{\partial}_L v_n - \partial_\xi v_n)\|_{L^2(\mathbb{R} \times \mathbb{T})} \leq |L| (\|\tilde{\partial}_L v_n\|_{L^2(\mathbb{R} \times \mathbb{T})} + \|\partial_\xi v_n\|_{L^2(\mathbb{R} \times \mathbb{T})}) \\ &\leq |L| \|g_n\|_{L^2(\mathbb{R} \times \mathbb{T})} \left(\frac{1}{c} + \frac{1}{\sqrt{2\beta a^-}} \right) \end{aligned} \quad (6.4)$$

with $a^- := \min_{y \in \mathbb{R}} a(y) > 0$. Hence, there is a subsequence $(v_{n_i})_{i \in \mathbb{N}}$ such that $v_{n_i} \rightharpoonup v$ in $H^1(\mathbb{R} \times \mathbb{T})$ weakly as $i \rightarrow +\infty$. This implies that $\int_{\mathbb{R} \times \mathbb{T}} a(y) \tilde{\partial}_L v \tilde{\partial}_L \varphi - c(\partial_\xi v) \varphi + \beta v \varphi = - \int_{\mathbb{R} \times \mathbb{T}} g \varphi$ for all $\varphi \in H^1(\mathbb{R} \times \mathbb{T})$. It follows that $\tilde{\partial}_L(a\tilde{\partial}_L v) \in L^2(\mathbb{R} \times \mathbb{T})$. It follows that $v \in \mathcal{D}_L$, $M_{c,L}(v) = g$ and $g \in R(M_{c,L})$. Since the

kernel of $M_{c,L}$ is trivial, the limit v is unique and the whole sequence $(v_n)_{n \in \mathbb{N}}$ converges to v weakly in $H^1(\mathbb{R} \times \mathbb{T})$ as $n \rightarrow +\infty$. Finally, the calculations in (6.1), (6.3) and (6.4) imply that

$$\|v\|_{H^1(\mathbb{R} \times \mathbb{T})}^2 \leq \left(\frac{1}{\beta^2} + \frac{1}{c^2} + |L|^2 \left(\frac{1}{c} + \frac{1}{\sqrt{2\beta a^-}} \right)^2 \right) \|g\|_{L^2(\mathbb{R} \times \mathbb{T})}^2 \quad (6.5)$$

and the proof of Lemma 3.1 is thereby complete. \square

Proof of Lemma 3.2. We only give the proof of the first assertion in (3.3), the second one being obtained similarly and being actually simpler. For the proof, we first begin with the special case where the sequences $(c_n)_{n \in \mathbb{N}}$ and $(g_n)_{n \in \mathbb{N}}$ are constant, and we then deal with the general case.

Step 1: the case $c_n = c$ and $g_n = g$. Consider any sequence $(L_n)_{n \in \mathbb{N}}$ in \mathbb{R}^* converging to 0 and let $v_n = M_{c,L_n}^{-1}(g) \in H^1(\mathbb{R} \times \mathbb{T})$. By the estimate (6.5) and the Sobolev injections, the functions v_n converge, up to extraction of a subsequence, strongly in $L_{loc}^2(\mathbb{R} \times \mathbb{T})$ and weakly in $H^1(\mathbb{R} \times \mathbb{T})$, to some $v_0 \in H^1(\mathbb{R} \times \mathbb{T})$ as $n \rightarrow +\infty$. Note that $\partial_y v_0 = 0$ because of the estimate (6.4). Then the function v_0 can be viewed as an $H^1(\mathbb{R})$ function and we can set $v'_0 = \partial_\xi v_0$. For any $\phi \in H^2(\mathbb{R})$, taking $\psi(\xi, y) = \phi(\xi) + L_n \chi(y) \phi'(\xi) \in H^1(\mathbb{R} \times \mathbb{T})$ (where $\chi \in C^2(\mathbb{R})$ solves (3.5)) as a test function in $M_{c,L_n}(v_n) = g$ gives

$$\int_{\mathbb{R} \times \mathbb{T}} a((\chi' + 1)\phi' + L_n \chi \phi'') \tilde{\partial}_{L_n} v_n + \int_{\mathbb{R} \times \mathbb{T}} (-c \partial_\xi v_n + \beta v_n)(\phi + L_n \chi \phi') = - \int_{\mathbb{R} \times \mathbb{T}} g(\phi + L_n \chi \phi'),$$

where a , χ and χ' are evaluated at y , while ϕ , ϕ' and ϕ'' are evaluated at ξ . The second term of the left hand side clearly converges to $\int_{\mathbb{R}} (-c v'_0 + \beta v_0) \phi$ as $n \rightarrow +\infty$, and so does the right hand side to $-\int_{\mathbb{R} \times \mathbb{T}} g \phi = -\int_{\mathbb{R}} \bar{g} \phi$. The first term can be written as

$$\begin{aligned} \int_{\mathbb{R} \times \mathbb{T}} a((\chi' + 1)\phi' + L_n \chi \phi'') \tilde{\partial}_{L_n} v_n &= \int_{\mathbb{R} \times \mathbb{T}} -v_n \tilde{\partial}_{L_n} (a(\chi' + 1)\phi') + L_n a \chi \phi'' \tilde{\partial}_{L_n} v_n \\ &= \int_{\mathbb{R} \times \mathbb{T}} a(\chi' + 1)\phi' \partial_\xi v_n + (\partial_y v_n + L_n \partial_\xi v_n) a \chi \phi'', \end{aligned}$$

which converges to $\int_{\mathbb{R} \times \mathbb{T}} v'_0 a(\chi' + 1)\phi' = a_H \int_{\mathbb{R}} v'_0 \phi'$ as $n \rightarrow +\infty$, since $\partial_y v_0 = 0$. Hence, $\int_{\mathbb{R}} (a_H v'_0 \phi' - c v'_0 \phi + \beta v_0 \phi) = -\int_{\mathbb{R}} \bar{g} \phi$ for all $\phi \in H^2(\mathbb{R})$ and then for all $\phi \in H^1(\mathbb{R})$ by density. This implies that $v_0 \in H^2(\mathbb{R})$ and that $M_{c,0}(v_0) = \bar{g}$.

Next we show that v_n converges to v_0 in $L^2(\mathbb{R} \times \mathbb{T})$ as $n \rightarrow +\infty$ (the convergence has only been known in $L_{loc}^2(\mathbb{R} \times \mathbb{T})$ so far). Let $\zeta_n(\xi, y) = v_n(\xi, y) - v_0(\xi) - L_n \chi(y) v'_0(\xi)$. By Lemma 3.1, the sequence $(v_n)_{n \in \mathbb{N}}$ is bounded in $H^1(\mathbb{R} \times \mathbb{T})$ and so is the sequence $(\zeta_n)_{n \in \mathbb{N}}$. Taking ζ_n as a test function in $M_{c,L_n}(v_n) = g$ gives $\int_{\mathbb{R} \times \mathbb{T}} a \tilde{\partial}_{L_n} v_n \tilde{\partial}_{L_n} \zeta_n - c \zeta_n \partial_\xi v_n + \beta v_n \zeta_n = -\int_{\mathbb{R} \times \mathbb{T}} g \zeta_n$. Observe that

$$\begin{aligned} \int_{\mathbb{R} \times \mathbb{T}} a \tilde{\partial}_{L_n} v_n \tilde{\partial}_{L_n} \zeta_n &= \int_{\mathbb{R} \times \mathbb{T}} a (\tilde{\partial}_{L_n} \zeta_n)^2 + a v'_0 \tilde{\partial}_{L_n} \zeta_n + a \chi' v'_0 \tilde{\partial}_{L_n} \zeta_n + L_n a \chi v''_0 \tilde{\partial}_{L_n} \zeta_n \\ &= \int_{\mathbb{R} \times \mathbb{T}} a (\tilde{\partial}_{L_n} \zeta_n)^2 + a_H v'_0 \tilde{\partial}_{L_n} \zeta_n + L_n a \chi v''_0 \tilde{\partial}_{L_n} \zeta_n \\ &= \int_{\mathbb{R} \times \mathbb{T}} a (\tilde{\partial}_{L_n} \zeta_n)^2 - a_H v''_0 \zeta_n + L_n a \chi v''_0 \partial_\xi \zeta_n - (a \chi)' v''_0 \zeta_n, \end{aligned}$$

and that $\int_{\mathbb{R} \times \mathbb{T}} c \zeta_n \partial_\xi v_n = \int_{\mathbb{R} \times \mathbb{T}} c v'_0 \zeta_n + L_n c \chi v''_0 \zeta_n$ since $\int_{\mathbb{R} \times \mathbb{T}} \zeta_n \tilde{\partial}_{L_n} \zeta_n = 0$, while $\int_{\mathbb{R} \times \mathbb{T}} \beta v_n \zeta_n = \int_{\mathbb{R} \times \mathbb{T}} \beta \zeta_n^2 +$

$\beta v_0 \zeta_n + L_n \beta \chi v_0' \zeta_n$. Since $M_{c,0}(v_0) = \bar{g}$, one obtains that

$$\begin{aligned} \int_{\mathbb{R} \times \mathbb{T}} a (\tilde{\partial}_{L_n} \zeta_n)^2 + \beta \zeta_n^2 &= \int_{\mathbb{R} \times \mathbb{T}} (\bar{g} - g) \zeta_n + (a\chi)' v_0'' \zeta_n - L_n (a\chi v_0'' \partial_\xi \zeta_n - c\chi v_0'' \zeta_n + \beta \chi v_0' \zeta_n) \\ &= \int_{\mathbb{R} \times \mathbb{T}} (\bar{g} - g)(v_n - v_0) + (a\chi)' v_0'' (v_n - v_0) \\ &\quad - L_n \int_{\mathbb{R} \times \mathbb{T}} a\chi v_0'' \partial_\xi \zeta_n - c\chi v_0'' \zeta_n + \beta \chi v_0' \zeta_n + (\bar{g} - g)\chi v_0' + (a\chi)' v_0'' \chi v_0'. \end{aligned}$$

Since $v_n \rightharpoonup v_0$ in $L^2(\mathbb{R} \times \mathbb{T})$ weakly as $n \rightarrow +\infty$, and since the sequence $(\zeta_n)_{n \in \mathbb{N}}$ is bounded in $H^1(\mathbb{R} \times \mathbb{T})$ and $v_0 \in H^2(\mathbb{R})$, it follows that $\zeta_n \rightarrow 0$ in $L^2(\mathbb{R} \times \mathbb{T})$ and hence $v_n \rightarrow v_0$ in $L^2(\mathbb{R} \times \mathbb{T})$.

Finally, we prove that the sequence $(v_n)_{n \in \mathbb{N}}$ converges to v_0 in $H^1(\mathbb{R} \times \mathbb{T})$. Now by using the symmetric difference quotient in ξ -direction for v_n and v_0 as in (6.2) and the weak convergence of $\partial_\xi v_n$ to v_0' as $n \rightarrow +\infty$ in $L^2(\mathbb{R} \times \mathbb{T})$, one concludes that

$$c \int_{\mathbb{R} \times \mathbb{T}} (\partial_\xi v_n)^2 = \int_{\mathbb{R} \times \mathbb{T}} g \partial_\xi v_n \xrightarrow{n \rightarrow +\infty} \int_{\mathbb{R} \times \mathbb{T}} g v_0' = \int_{\mathbb{R}} \bar{g} v_0' = c \int_{\mathbb{R}} (v_0')^2. \quad (6.6)$$

By the weak convergence of $\partial_\xi v_n$ again, this implies that $\partial_\xi v_n$ converges to v_0' strongly in $L^2(\mathbb{R} \times \mathbb{T})$ as $n \rightarrow +\infty$. From arguments similar to (6.4), one has $\partial_y v_n \rightarrow 0$ in $L^2(\mathbb{R} \times \mathbb{T})$ as $n \rightarrow +\infty$. As a conclusion, v_n converges to v_0 in $H^1(\mathbb{R} \times \mathbb{T})$ as $n \rightarrow +\infty$ and this holds for the whole sequence by uniqueness of the limit. Lastly, once one knows the convergence of $(v_n)_{n \in \mathbb{N}}$ to v_0 in the strong sense in $H^1(\mathbb{R} \times \mathbb{T})$, it is easy to see that the above estimates show that the convergence is actually uniform with respect to g in the ball $B_A = \{g \in L^2(\mathbb{R} \times \mathbb{T}) \mid \|g\|_{L^2(\mathbb{R} \times \mathbb{T})} \leq A\}$, for every $A > 0$.

Step 2: the general case. We first claim that for any $r > 0$ and any $\omega \in L^2(\mathbb{R} \times \mathbb{T})$ such that $\|\omega\|_{L^2(\mathbb{R} \times \mathbb{T})} \leq r$, there holds

$$\|M_{c_n, L_n}^{-1}(\omega) - M_{c, L_n}^{-1}(\omega)\|_{H^1(\mathbb{R} \times \mathbb{T})} \leq C|c_n - c|r \quad \text{for all } n \in \mathbb{N}, \quad (6.7)$$

where C is a constant independent of n and r . In fact, let $p_n = M_{c_n, L_n}^{-1}(\omega)$ and $q_n = M_{c, L_n}^{-1}(\omega)$. Then $M_{c, L_n}(p_n - q_n) = (c - c_n)\partial_\xi p_n$. Testing it with the function $(p_n - q_n) \in H^1(\mathbb{R} \times \mathbb{T})$ and using arguments similar to the ones used (6.1), one obtains that

$$\int_{\mathbb{R} \times \mathbb{T}} a (\tilde{\partial}_{L_n} p_n - \tilde{\partial}_{L_n} q_n)^2 + \frac{\beta}{2} (p_n - q_n)^2 \leq \frac{(c_n - c)^2}{2\beta} \int_{\mathbb{R} \times \mathbb{T}} (\partial_\xi p_n)^2.$$

Similar arguments to (6.3) and (6.4) yield

$$\begin{cases} \|\partial_\xi(p_n - q_n)\|_{L^2(\mathbb{R} \times \mathbb{T})} &\leq |c_n - c| c^{-1} \|\partial_\xi p_n\|_{L^2(\mathbb{R} \times \mathbb{T})}, \\ \|\partial_y(p_n - q_n)\|_{L^2(\mathbb{R} \times \mathbb{T})} &\leq |L_n| |c_n - c| (c^{-1} + (2\beta a^-)^{-1/2}) \|\partial_\xi p_n\|_{L^2(\mathbb{R} \times \mathbb{T})}. \end{cases}$$

Note also that $\|\partial_\xi p_n\|_{L^2(\mathbb{R} \times \mathbb{T})} \leq (1/c_n) \|\omega\|_{L^2(\mathbb{R} \times \mathbb{T})}$ from the estimate (6.3). Then the proof of our claim (6.7) is finished, since the sequences $(L_n)_{n \in \mathbb{N}}$ and $(1/c_n)_{n \in \mathbb{N}}$ are bounded.

Next, we observe that

$$\begin{aligned} \|M_{c_n, L_n}^{-1}(g_n) - M_{c, 0}^{-1}(\bar{g})\|_{H^1(\mathbb{R} \times \mathbb{T})} &\leq \|M_{c_n, L_n}^{-1}(g_n) - M_{c, L_n}^{-1}(g_n)\|_{H^1(\mathbb{R} \times \mathbb{T})} \\ &\quad + \|M_{c, L_n}^{-1}(g_n) - M_{c, L_n}^{-1}(g)\|_{H^1(\mathbb{R} \times \mathbb{T})} + \|M_{c, L_n}^{-1}(g) - M_{c, 0}^{-1}(\bar{g})\|_{H^1(\mathbb{R} \times \mathbb{T})}. \end{aligned}$$

From (6.7), the first term of the right hand side converges to 0 as $n \rightarrow +\infty$, and this holds uniformly with respect to $g \in B_A$, for every $A > 0$. By Lemma 3.1 and the boundedness of the sequences $(L_n)_{n \in \mathbb{N}}$ and $(1/c_n)_{n \in \mathbb{N}}$, one has $\|M_{c, L_n}^{-1}(g_n - g)\|_{H^1(\mathbb{R} \times \mathbb{T})} \rightarrow 0$ as $n \rightarrow +\infty$, uniformly with respect to $g \in B_A$ for every $A > 0$. Lastly, the convergence of the last term to 0 follows from Step 1. Hence, the proof of Lemma 3.2 is finished. \square

Proof of Lemma 3.3. By Lemma 3.1 and (6.7), one only needs to prove that

$$M_{c,L_n}^{-1}(g) \rightarrow M_{c,L}^{-1}(g) \quad \text{in } H^1(\mathbb{R} \times \mathbb{T}) \quad \text{as } n \rightarrow +\infty, \quad (6.8)$$

uniformly for $g \in B_A$, for every $A > 0$, and for every sequence $(L_n)_{n \in \mathbb{N}} \in \mathbb{R}^*$ such that $L_n \rightarrow L$ as $n \rightarrow +\infty$. Given any $g \in L^2(\mathbb{R} \times \mathbb{T})$, let $w_n = M_{c,L_n}^{-1}(g)$ and $w = M_{c,L}^{-1}(g)$. Then, by similar estimates in Lemma 3.1, the functions w_n converge to w strongly in $L_{loc}^2(\mathbb{R} \times \mathbb{T})$ and weakly in $H^1(\mathbb{R} \times \mathbb{T})$ as $n \rightarrow +\infty$. Note that

$$M_{c,L_n}(w_n - w) = \underbrace{M_{c,L_n}(w_n)}_{=g} - \underbrace{M_{c,L}(w)}_{=g} - (M_{c,L_n}(w) - M_{c,L}(w)) = -\tilde{\partial}_{L_n}(a\tilde{\partial}_{L_n}w) + \tilde{\partial}_L(a\tilde{\partial}_Lw).$$

Integrating the above equation against $w_n - w$ yields

$$\begin{aligned} \int_{\mathbb{R} \times \mathbb{T}} a(\tilde{\partial}_{L_n}w_n - \tilde{\partial}_{L_n}w)^2 + \beta(w_n - w)^2 &= \int_{\mathbb{R} \times \mathbb{T}} (\tilde{\partial}_L(a\tilde{\partial}_Lw) - \tilde{\partial}_{L_n}(a\tilde{\partial}_{L_n}w))(w_n - w) \\ &= \int_{\mathbb{R} \times \mathbb{T}} (w_n - w)\tilde{\partial}_L(a\tilde{\partial}_Lw) + \frac{a\partial_y w(\tilde{\partial}_{L_n}w_n - \tilde{\partial}_{L_n}w)}{L_n} \\ &\quad + \int_{\mathbb{R} \times \mathbb{T}} a\partial_\xi w(\tilde{\partial}_{L_n}w_n - \tilde{\partial}_{L_n}w), \end{aligned}$$

which converges to 0 as $n \rightarrow +\infty$, since $\tilde{\partial}_L(a\tilde{\partial}_Lw) \in L^2(\mathbb{R} \times \mathbb{T})$ and $w \in H^1(\mathbb{R} \times \mathbb{T})$, and since $w_n \rightharpoonup w$ and $\tilde{\partial}_{L_n}w_n \rightharpoonup \tilde{\partial}_Lw$ weakly in $L^2(\mathbb{R} \times \mathbb{T})$. Thus, $\|w_n - w\|_{L^2(\mathbb{R} \times \mathbb{T})} \rightarrow 0$ and $\|\tilde{\partial}_{L_n}w_n - \tilde{\partial}_{L_n}w\|_{L^2(\mathbb{R} \times \mathbb{T})} \rightarrow 0$ as $n \rightarrow +\infty$. The convergence $\partial_\xi w_n \rightarrow \partial_\xi w$ in $L^2(\mathbb{R} \times \mathbb{T})$ follows then from the weak convergence and the fact that $\|\partial_\xi w_n\|_{L^2(\mathbb{R} \times \mathbb{T})}^2 = (1/c_n) \int_{\mathbb{R} \times \mathbb{T}} g\partial_\xi w_n \rightarrow (1/c) \int_{\mathbb{R} \times \mathbb{T}} g\partial_\xi w = \|\partial_\xi w\|_{L^2(\mathbb{R} \times \mathbb{T})}^2$, as in (6.6). On the other hand, observe that

$$\begin{aligned} \|\partial_y(w_n - w)\|_{L^2(\mathbb{R} \times \mathbb{T})} &= \|L_n(\tilde{\partial}_{L_n}w_n - \partial_\xi w_n) - L(\tilde{\partial}_Lw - \partial_\xi w)\|_{L^2(\mathbb{R} \times \mathbb{T})} \\ &\leq \|L_n\tilde{\partial}_{L_n}w_n - L\tilde{\partial}_Lw\|_{L^2(\mathbb{R} \times \mathbb{T})} + |L|\|\tilde{\partial}_{L_n}w - \tilde{\partial}_Lw\|_{L^2(\mathbb{R} \times \mathbb{T})} \\ &\quad + |L_n|\|\partial_\xi w_n - \partial_\xi w\|_{L^2(\mathbb{R} \times \mathbb{T})} + |L_n - L|\|\partial_\xi w\|_{L^2(\mathbb{R} \times \mathbb{T})}, \end{aligned}$$

which converges to 0 as $n \rightarrow +\infty$. Hence, the proof of the convergence (6.8) is complete. Lastly, the above calculations together with Lemma 3.1 imply that (6.8) holds uniformly with respect to the functions g such that $\|g\|_{L^2(\mathbb{R} \times \mathbb{T})} \leq A$, for every $A > 0$. \square

Next, we do the proof of the continuity and differentiability properties of the function G defined in (3.6), which were stated in Lemma 3.4.

Proof of Lemma 3.4. Step 1: the continuity of G . The continuity of G_2 is obvious from Cauchy-Schwarz inequality. Next we consider the continuity of G_1 at $(v, c, 0)$ with $(v, c) \in H^1(\mathbb{R} \times \mathbb{T}) \times (0, +\infty)$. To do so, we first prove that $M_{c_n, L_n}^{-1}(K(v_n, c_n, L_n)) \rightarrow M_{c, 0}^{-1}(\overline{K(v, c, 0)})$ in $H^1(\mathbb{R} \times \mathbb{T})$ as $n \rightarrow +\infty$ for any sequences $(v_n)_{n \in \mathbb{N}}$ in $L^2(\mathbb{R} \times \mathbb{T})$, $(c_n)_{n \in \mathbb{N}}$ in $(0, +\infty)$ and $(L_n)_{n \in \mathbb{N}}$ in \mathbb{R}^* such that $v_n \rightarrow v$ in $L^2(\mathbb{R} \times \mathbb{T})$, $c_n \rightarrow c$ and $L_n \rightarrow 0$. By Lemma 3.2, it is sufficient to show that $K(v_n, c_n, L_n) \rightarrow K(v, c, 0)$ in $L^2(\mathbb{R} \times \mathbb{T})$ as $n \rightarrow +\infty$. Since the function $f(y, u)$ is globally Lipschitz-continuous in u uniformly for $y \in \mathbb{T}$, one has that

$$\begin{aligned} &\|K_{c_n, L_n}(v_n) - K(v, c, 0)\|_{L^2(\mathbb{R} \times \mathbb{T})} \\ &= \|L_n a \chi \phi_0^{(3)} + (c_n - c)\phi_0' + c_n L_n \chi \phi_0'' + \beta(v_n - v) + f(y, v_n + \phi_0 + L_n \chi \phi_0') - f(y, v + \phi_0)\|_{L^2(\mathbb{R} \times \mathbb{T})} \\ &\leq |L_n| \|a \chi \phi_0^{(3)}\|_{L^2(\mathbb{R} \times \mathbb{T})} + |c_n - c| \|\phi_0'\|_{L^2(\mathbb{R})} + |c_n L_n| \|\chi \phi_0''\|_{L^2(\mathbb{R} \times \mathbb{T})} + \beta \|v_n - v\|_{L^2(\mathbb{R} \times \mathbb{T})} \\ &\quad + C \|v_n - v\|_{L^2(\mathbb{R} \times \mathbb{T})} + C |L_n| \|\chi \phi_0'\|_{L^2(\mathbb{R} \times \mathbb{T})}, \end{aligned}$$

where C is a constant depending only on f . Thus, $K(v_n, c_n, L_n) \rightarrow K(v, c, 0)$ in $L^2(\mathbb{R} \times \mathbb{T})$ as $n \rightarrow +\infty$. Similarly, the fact that $\overline{K(v_n, c_n, 0)} \rightarrow \overline{K(v, c, 0)}$ in $L^2(\mathbb{R})$ as $n \rightarrow +\infty$ together with Lemma 3.2 implies that $M_{c_n, 0}^{-1}(\overline{K(v_n, c_n, 0)}) \rightarrow M_{c, 0}^{-1}(\overline{K(v, c, 0)})$ in $H^1(\mathbb{R})$ as $n \rightarrow +\infty$. Therefore, the arguments of this paragraph show that G_1 is continuous at $(v, c, 0)$.

For the continuity of G_1 at $(v, c, L) \in H^1(\mathbb{R} \times \mathbb{T}) \times (0, +\infty) \times \mathbb{R}^*$, the arguments are similar to those for $L = 0$, the only additional fact being the use of Lemma 3.3 instead of Lemma 3.2.

Step 2: G is continuously Fréchet differentiable with respect to (v, c) . First, for $v \in H^1(\mathbb{R} \times \mathbb{T})$, we set $g[v](\xi, y) = f(y, \phi_0(\xi) + v(\xi, y))$ in $\mathbb{R} \times \mathbb{T}$ and we prove that the function g is continuously Fréchet differentiable from $H^1(\mathbb{R} \times \mathbb{T})$ to $L^2(\mathbb{R} \times \mathbb{T})$. Since the function $f(y, u)$ is globally Lipschitz-continuous in u uniformly for $y \in \mathbb{T}$, and since $\phi_0 \in L^2(\mathbb{R}^+)$ and $1 - \phi_0 \in L^2(\mathbb{R}^-)$, there is constant $C_1 > 0$ independent of v such that

$$\begin{aligned} \|g[v]\|_{L^2(\mathbb{R} \times \mathbb{T})}^2 &= \int_{\mathbb{R}^- \times \mathbb{T}} |f(y, \phi_0 + v) - f(y, 1)|^2 + \int_{\mathbb{R}^+ \times \mathbb{T}} |f(y, \phi_0 + v) - f(y, 0)|^2 \\ &\leq C_1 (\|1 - \phi_0\|_{L^2(\mathbb{R}^-)}^2 + \|\phi_0\|_{L^2(\mathbb{R}^+)}^2 + \|v\|_{L^2(\mathbb{R} \times \mathbb{T})}^2). \end{aligned}$$

Hence, $g : v \mapsto g[v]$ is a map from $H^1(\mathbb{R} \times \mathbb{T})$ to $L^2(\mathbb{R} \times \mathbb{T})$. Since $f(y, u)$ is of class $C^{1,1}$ in $u \in \mathbb{R}$ uniformly for $y \in \mathbb{T}$, it follows from Sobolev injections and Cauchy-Schwarz inequality that for any $v, h \in H^1(\mathbb{R} \times \mathbb{T})$ and $t \in (0, 1]$,

$$\begin{aligned} &\left\| \frac{g[v + th] - g[v]}{t} - \partial_u f(y, \phi_0 + v)h \right\|_{L^2(\mathbb{R} \times \mathbb{T})} \\ &= \|\partial_u f(y, \phi_0 + v + t\eta h)h - \partial_u f(y, \phi_0 + v)h\|_{L^2(\mathbb{R} \times \mathbb{T})} \\ &\leq \|\partial_u f(y, \phi_0 + v + t\eta h) - \partial_u f(y, \phi_0 + v)\|_{L^4(\mathbb{R} \times \mathbb{T})} \|h\|_{L^4(\mathbb{R} \times \mathbb{T})} \leq C_2 t \|h\|_{H^1(\mathbb{R} \times \mathbb{T})}^2, \end{aligned} \tag{6.9}$$

where η is a function from $\mathbb{R} \times \mathbb{T}$ to $[0, 1]$, and $C_2 > 0$ is independent on t . Thus,

$$\frac{g[v + th] - g[v]}{t} \rightarrow \partial_u f(y, \phi_0 + v)h \quad \text{in } L^2(\mathbb{R} \times \mathbb{T}) \text{ as } t \rightarrow 0^+,$$

which implies that g is Gâteaux differentiable at any point $v \in H^1(\mathbb{R} \times \mathbb{T})$ with its derivative given by $A(v)h = \partial_u f(y, \phi_0 + v)h$ for any $h \in H^1(\mathbb{R} \times \mathbb{T})$. Actually, (6.9) implies that g is Fréchet differentiable and since the map $v \mapsto A(v)$ from $H^1(\mathbb{R} \times \mathbb{T})$ to $\mathcal{L}(H^1(\mathbb{R} \times \mathbb{T}), L^2(\mathbb{R} \times \mathbb{T}))$ is continuous, the function g is continuously Fréchet differentiable in $H^1(\mathbb{R} \times \mathbb{T})$.

In order to show the Fréchet differentiability of G with respect to (v, c) , pick now any point $(v, c, L) \in H^1(\mathbb{R} \times \mathbb{T}) \times (0, +\infty) \times \mathbb{R}$. Consider first the case $L \neq 0$. Since g is Fréchet differentiable at v , $K(v, c, L)$ is also Fréchet differentiable with respect to v with

$$\partial_v K(v, c, L)(\tilde{v}) = (\partial_u f(y, v + \phi_0 + L\chi\phi'_0) + \beta)\tilde{v} \quad \text{for all } \tilde{v} \in H^1(\mathbb{R} \times \mathbb{T}).$$

Since the linear operator $M_{c,L}^{-1} : L^2(\mathbb{R} \times \mathbb{T}) \rightarrow \mathcal{D}_L \subset H^1(\mathbb{R} \times \mathbb{T})$ is bounded, one has $\partial_w (M_{c,L}^{-1}(w)) = M_{c,L}^{-1}$. Then, by the chain rule,

$$\partial_v (M_{c,L}^{-1}(K(v, c, L)))(\tilde{v}) = M_{c,L}^{-1}((\partial_u f(y, v + \phi_0 + L\chi\phi'_0) + \beta)\tilde{v}) \quad \text{for all } \tilde{v} \in H^1(\mathbb{R} \times \mathbb{T}).$$

On the other hand, $\partial_c K(v, c, L)(\tilde{c}) = (\phi'_0 + L\chi\phi''_0)\tilde{c}$ for all $\tilde{c} \in \mathbb{R}$ while, by Lemma 3.3,

$$\partial_c M_{c,L}^{-1}(v)(\tilde{c}) = \lim_{d \rightarrow c} M_{c,L}^{-1} \left(\frac{M_{c,L}(M_{d,L}^{-1}(v)) - v}{d - c} \right) \tilde{c} = -M_{c,L}^{-1}(\partial_\xi M_{c,L}^{-1}(v))\tilde{c} \quad \text{for all } \tilde{c} \in \mathbb{R}.$$

As a consequence,

$$\begin{aligned}\partial_c(M_{c,L}^{-1}(K(v,c,L)))(\tilde{c}) &= -M_{c,L}^{-1}(\partial_\xi M_{c,L}^{-1}(K(v,c,L)))\tilde{c} + M_{c,L}^{-1}(\phi'_0 + L\chi\phi''_0)\tilde{c} \\ &= -\tilde{c}M_{c,L}^{-1}\left(\partial_\xi(M_{c,L}^{-1}(K(v,c,L)) - \phi_0 - L\chi\phi'_0)\right) \text{ for all } \tilde{c} \in \mathbb{R}.\end{aligned}$$

Hence, the function $G(v,c,L)$ is Fréchet differentiable with respect to (v,c) with derivative

$$\begin{aligned}\partial_{(v,c)}G(v,c,L)(\tilde{v},\tilde{c}) \\ = \left(\begin{array}{c} \tilde{v} + M_{c,L}^{-1}((\partial_u f(y, v + \phi_0 + L\chi\phi'_0) + \beta)\tilde{v}) - \tilde{c}M_{c,L}^{-1}\left(\partial_\xi(M_{c,L}^{-1}(K(v,c,L)) - \phi_0 - L\chi\phi'_0)\right) \\ 2 \int_{\mathbb{R}^+ \times \mathbb{T}} (\phi_0 + v + L\chi\phi'_0)\tilde{v} \end{array} \right). \quad (6.10)\end{aligned}$$

Similarly, for $L = 0$, G is Fréchet differentiable with respect to (v,c) and for every $(v,c) \in H^1(\mathbb{R} \times \mathbb{T}) \times (0, +\infty)$ and $(\tilde{v}, \tilde{c}) \in H^1(\mathbb{R} \times \mathbb{T}) \times \mathbb{R}$,

$$\partial_{(v,c)}G(v,c,0)(\tilde{v},\tilde{c}) = \left(\begin{array}{c} \tilde{v} + M_{c,0}^{-1}\left(\overline{(\partial_u f(y, v + \phi_0) + \beta)\tilde{v}}\right) - \tilde{c}M_{c,0}^{-1}\left(\overline{\partial_\xi(M_{c,0}^{-1}(K(v,c,0)) - \phi_0)}\right) \\ 2 \int_{\mathbb{R}^+ \times \mathbb{T}} (\phi_0 + v)\tilde{v} \end{array} \right). \quad (6.11)$$

Finally, we prove that $\partial_{(v,c)}G : H^1(\mathbb{R} \times \mathbb{T}) \times (0, +\infty) \times \mathbb{R} \rightarrow \mathcal{L}(H^1(\mathbb{R} \times \mathbb{T}) \times \mathbb{R}, H^1(\mathbb{R} \times \mathbb{T}) \times \mathbb{R})$ is continuous. Since the continuity of $\partial_{(v,c)}G_2$ is obvious from the Cauchy-Schwarz inequality, we only need to show that $\partial_{(v,c)}G_1$ is continuous. Let (v,c,L) be any point in $H^1(\mathbb{R} \times \mathbb{T}) \times (0, +\infty) \times \mathbb{R}$ and let $(v_n)_{n \in \mathbb{N}}$ in $H^1(\mathbb{R} \times \mathbb{T})$, $(c_n)_{n \in \mathbb{N}}$ in $(0, +\infty)$ and $(L_n)_{n \in \mathbb{N}}$ in \mathbb{R} be such that $\|v_n - v\|_{H^1(\mathbb{R} \times \mathbb{T})} \rightarrow 0$, $c_n \rightarrow c$ and $L_n \rightarrow L$ as $n \rightarrow +\infty$. In the case $L = 0$, by Lemma 3.2 and by (6.10) and (6.11), for the continuity of $\partial_c G_1$ at $(v,c,0)$, it is sufficient to prove that, whether L_n be 0 or not,

$$\left\{ \begin{array}{l} \partial_\xi\left(M_{c_n, L_n}^{-1}(K(v_n, c_n, L_n)) - \phi_0 - L_n\chi\phi'_0\right) \xrightarrow{n \rightarrow +\infty} \partial_\xi\left(M_{c,0}^{-1}(\overline{K(v,c,0)}) - \phi_0\right) \text{ in } L^2(\mathbb{R} \times \mathbb{T}), \\ \frac{\partial_\xi\left(M_{c_n, L_n}^{-1}(K(v_n, c_n, L_n)) - \phi_0 - L_n\chi\phi'_0\right)}{\partial_\xi\left(M_{c_n, 0}^{-1}(\overline{K(v_n, c_n, 0)}) - \phi_0\right)} \xrightarrow{n \rightarrow +\infty} \frac{\partial_\xi\left(M_{c,0}^{-1}(\overline{K(v,c,0)}) - \phi_0\right)}{\partial_\xi\left(M_{c,0}^{-1}(\overline{K(v,c,0)}) - \phi_0\right)} \text{ in } L^2(\mathbb{R}). \end{array} \right.$$

In fact, these limits follow from Lemma 3.2 and the fact that $K(v_n, c_n, L_n) \rightarrow K(v, c, 0)$ in $L^2(\mathbb{R} \times \mathbb{T})$ (whence $\overline{K(v_n, c_n, L_n)} \rightarrow \overline{K(v, c, 0)}$ in $L^2(\mathbb{R})$) as $n \rightarrow +\infty$. By Lemmas 3.1, 3.2 and by (6.10) and (6.11), for the continuity of $\partial_v G_1$ at $(v,c,0)$, it is sufficient to show that

$$(\partial_u f(y, v_n + \phi_0 + L_n\chi\phi'_0) + \beta)\tilde{v} \xrightarrow{n \rightarrow +\infty} (\partial_u f(y, v + \phi_0) + \beta)\tilde{v} \text{ in } L^2(\mathbb{R} \times \mathbb{T})$$

(whence the same property for the averaged functions with respect to y), uniformly with respect to $\|\tilde{v}\|_{H^1(\mathbb{R} \times \mathbb{T})} \leq 1$. Since the function $f(y, u)$ is of class $C^{1,1}$ in $u \in \mathbb{R}$ uniformly for $y \in \mathbb{T}$, these convergences follow from similar arguments as (6.9).

In the case $L \neq 0$, as in the previous paragraph, one has

$$\left\{ \begin{array}{l} \partial_\xi(M_{c_n, L_n}^{-1}(K(v_n, c_n, L_n)) - \phi_0 - L_n\chi\phi'_0) \xrightarrow{n \rightarrow +\infty} \partial_\xi(M_{c,L}^{-1}(K(v,c,L)) - \phi_0 - L\chi\phi'_0) \\ (\partial_u f(y, v_n + \phi_0 + L_n\chi\phi'_0) + \beta)\tilde{v} \xrightarrow{n \rightarrow +\infty} (\partial_u f(y, v + \phi_0 + L\chi\phi'_0) + \beta)\tilde{v} \end{array} \right.$$

in $L^2(\mathbb{R} \times \mathbb{T})$, uniformly with respect to $\|\tilde{v}\|_{H^1(\mathbb{R} \times \mathbb{T})} \leq 1$. Thus, the continuity of $\partial_{(v,c)}G_1$ at (v,c,L) with $L \neq 0$ follows from Lemma 3.3.

Step 3: the invertibility of $Q = \partial_{(v,c)}G(0, c_0, 0)$. We first observe that, from (6.11) and $\overline{K(0, c_0, 0)} = 0$, the operator Q is given by

$$Q(\tilde{v}, \tilde{c}) = \left(\tilde{v} + M_{c_0,0}^{-1}(\overline{(\partial_u f(y, \phi_0) + \beta)\tilde{v}}) + \tilde{c}M_{c_0,0}^{-1}(\phi'_0), 2 \int_{\mathbb{R} \times \mathbb{T}} \phi_0 \tilde{v} \right) \text{ for all } (\tilde{v}, \tilde{c}) \in H^1(\mathbb{R} \times \mathbb{T}) \times \mathbb{R}. \quad (6.12)$$

Let us now show that Q has a closed range $R(Q)$. Let $(\tilde{v}_n)_{n \in \mathbb{N}}, (\tilde{g}_n)_{n \in \mathbb{N}}$ in $H^1(\mathbb{R} \times \mathbb{T})$ and $(\tilde{c}_n)_{n \in \mathbb{N}}, (\tilde{d}_n)_{n \in \mathbb{N}}$ in \mathbb{R} be such that $Q(\tilde{v}_n, \tilde{c}_n) = (\tilde{g}_n, \tilde{d}_n) \rightarrow (\tilde{g}, \tilde{d})$ in $H^1(\mathbb{R} \times \mathbb{T}) \times \mathbb{R}$ as $n \rightarrow +\infty$. Define $v_n = \tilde{v}_n - \tilde{g}_n$. One can see from (6.12) that $v_n = -M_{c_0,0}^{-1}(\overline{(\partial_u f(y, \phi_0) + \beta)\tilde{v}_n}) - \tilde{c}_n M_{c_0,0}^{-1}(\phi'_0) \in H^2(\mathbb{R})$. Then, by definition of H and since v_n is independent of y , it follows that

$$\begin{aligned} H(v_n) &= M_{c_0,0}v_n + (\overline{f'}(\phi_0) + \beta)v_n = -\overline{(\partial_u f(y, \phi_0) + \beta)\tilde{v}_n} - \tilde{c}_n \phi'_0 + \overline{(\partial_u f(y, \phi_0) + \beta)v_n} \\ &= -\overline{(\partial_u f(y, \phi_0) + \beta)\tilde{g}_n} - \tilde{c}_n \phi'_0 \end{aligned} \quad (6.13)$$

Testing it with $0 \neq w \in \ker(H^*)$ implies that $\tilde{c}_n \int_{\mathbb{R}} w \phi'_0 = - \int_{\mathbb{R} \times \mathbb{T}} (\partial_u f(y, \phi_0) + \beta) w \tilde{g}_n$. Notice now that $\int_{\mathbb{R}} w \phi'_0 \neq 0$. Indeed, otherwise, ϕ'_0 would be in the orthogonal of $\mathbb{R}w = \ker(H^*)$, that is in the closed range $R(H)$. But the property $\phi'_0 \in R(H)$ is impossible since $\ker(H) = \mathbb{R}\phi'_0$ and 0 is an algebraically simple eigenvalue of H . Then, since $\tilde{g}_n \rightarrow \tilde{g}$ in $H^1(\mathbb{R} \times \mathbb{T})$ as $n \rightarrow +\infty$, it follows that \tilde{c}_n converges to some $\tilde{c} \in \mathbb{R}$ and then, by (6.13), $H(v_n)$ converges to some g in $L^2(\mathbb{R})$ with

$$-\overline{(\partial_u f(y, \phi_0) + \beta)\tilde{g}} - \tilde{c}\phi'_0 = g. \quad (6.14)$$

Since $R(H)$ is closed, there is $v \in H^2(\mathbb{R})$ such that $H(v) = g$. Set $\tilde{v} = v + \eta\phi'_0 + \tilde{g} \in H^1(\mathbb{R} \times \mathbb{T})$, where $\eta \in \mathbb{R}$ is chosen as the unique real number satisfying $2 \int_{\mathbb{R} \times \mathbb{T}} \phi_0 \tilde{v} = \tilde{d}$. Since $\tilde{v} - \tilde{g} = v + \eta\phi'_0 \in H^2(\mathbb{R})$ and $H(\tilde{v} - \tilde{g}) = H(v + \eta\phi'_0) = g$, one has $M_{c_0,0}(\tilde{v} - \tilde{g}) + \overline{(\partial_u f(y, \phi_0) + \beta)(\tilde{v} - \tilde{g})} = g$. Then, by composing by $M_{c_0,0}^{-1}$ and using (6.14), one gets that $\tilde{v} + M_{c_0,0}^{-1}(\overline{(\partial_u f(y, \phi_0) + \beta)\tilde{v}}) + \tilde{c}M_{c_0,0}^{-1}(\phi'_0) = \tilde{g}$. Therefore, $(\tilde{g}, \tilde{d}) = Q(\tilde{v}, \tilde{c})$, and $R(Q)$ is closed.

Next, we prove that Q has a trivial kernel. Suppose that $Q(\tilde{v}, \tilde{c}) = (0, 0)$ for some $(\tilde{v}, \tilde{c}) \in H^1(\mathbb{R} \times \mathbb{T}) \times \mathbb{R}$. Since $M_{c_0,0}^{-1}$ is a map from $L^2(\mathbb{R})$ to $H^2(\mathbb{R})$, then $\partial_y \tilde{v} = 0$ and $\tilde{v} \in H^2(\mathbb{R})$ by (6.11). Furthermore, $M_{c_0,0}(\tilde{v}) + \overline{(\partial_u f(y, \phi_0) + \beta)\tilde{v}} = -\tilde{c}\phi'_0$, that is, $H(\tilde{v}) = -\tilde{c}\phi'_0$. Since 0 is an algebraically simple eigenvalue of H with kernel $\mathbb{R}\phi'_0$, it follows that $\tilde{c} = 0$ and $\tilde{v} = \sigma\phi'_0$ with $\sigma \in \mathbb{R}$. Since $0 = 2\sigma \int_{\mathbb{R} \times \mathbb{T}} \phi_0 \phi'_0 = -\sigma(\phi_0(0))^2$ and $\phi_0(0) \neq 0$, one infers that $\sigma = 0$. Thus, the kernel of Q is reduced to $\{(0, 0)\}$.

Finally, we prove that the kernel of the adjoint operator Q^* is also reduced to $\{(0, 0)\}$. Let $(\tilde{v}, \tilde{c}) \in H^1(\mathbb{R} \times \mathbb{T}) \times \mathbb{R}$ such that $Q^*(\tilde{v}, \tilde{c}) = 0$, that is,

$$\begin{aligned} 0 &= \langle Q(\tilde{w}, \tilde{d}), (\tilde{v}, \tilde{c}) \rangle_{H^1(\mathbb{R} \times \mathbb{T}) \times \mathbb{R}} \\ &= \left(\tilde{w} + M_{c_0,0}^{-1}(\overline{(\partial_u f(y, \phi_0) + \beta)\tilde{w}}) + \tilde{d}M_{c_0,0}^{-1}(\phi'_0), \tilde{v} \right)_{H^1(\mathbb{R} \times \mathbb{T})} + 2\tilde{c} \int_{\mathbb{R} \times \mathbb{T}} \phi_0 \tilde{w} \end{aligned} \quad (6.15)$$

for all $(\tilde{w}, \tilde{d}) \in H^1(\mathbb{R} \times \mathbb{T}) \times \mathbb{R}$, where $(v_1, v_2)_{H^1(\mathbb{R} \times \mathbb{T})} = \int_{\mathbb{R} \times \mathbb{T}} v_1 v_2 + \partial_\xi v_1 \partial_\xi v_2 + \partial_y v_1 \partial_y v_2$ for all $v_1, v_2 \in H^1(\mathbb{R} \times \mathbb{T})$. We notice that

$$\phi'_0 + M_{c_0,0}^{-1}(\overline{(\partial_u f(y, \phi_0) + \beta)\phi'_0}) = \phi'_0 + M_{c_0,0}^{-1}(\overline{(\overline{f'}(\phi_0) + \beta)\phi'_0}) = M_{c_0,0}^{-1}(H(\phi'_0)) = 0.$$

Therefore, taking $(\tilde{w}, \tilde{d}) = (\phi'_0, 0)$ in (6.15) yields $0 = 2\tilde{c} \int_{\mathbb{R} \times \mathbb{T}} \phi_0 \phi'_0 = -\tilde{c}(\phi_0(0))^2$, whence $\tilde{c} = 0$. Next, by choosing $(\tilde{w}, \tilde{d}) = (0, 1)$ in (6.15), it follows that

$$0 = (M_{c_0,0}^{-1}(\phi'_0), \tilde{v})_{H^1(\mathbb{R} \times \mathbb{T})} = (M_{c_0,0}^{-1}(\phi'_0), \tilde{v})_{H^1(\mathbb{R})} \quad (6.16)$$

since $M_{c_0,0}^{-1}(\phi'_0) \in H^1(\mathbb{R})$. On the other hand, if $\tilde{w} \in H^2(\mathbb{R})$ is independent of $y \in \mathbb{T}$ and $\tilde{d} = 0$ in (6.15), then

$$\begin{aligned} 0 &= (\tilde{w} + M_{c_0,0}^{-1}(\overline{(\partial_u f(y, \phi_0) + \beta)\tilde{w}}), \tilde{v})_{H^1(\mathbb{R} \times \mathbb{T})} \\ &= (M_{c_0,0}^{-1}(M_{c_0,0}(\tilde{w}) + (\tilde{f}'(\phi_0) + \beta)\tilde{w}), \tilde{v})_{H^1(\mathbb{R})} = (M_{c_0,0}^{-1}(H(\tilde{w})), \tilde{v})_{H^1(\mathbb{R})}. \end{aligned} \quad (6.17)$$

Since the closed image $R(H)$ of H is orthogonal to $\ker(H^*)$ and since $\phi'_0 \notin R(H)$ (as already emphasized), it follows from (6.16) and (6.17) that $(M_{c_0,0}^{-1}(P(\phi'_0)), \tilde{v})_{H^1(\mathbb{R})} = 0$, where $P(\phi'_0) \neq 0$ is the orthogonal projection of ϕ'_0 onto $\ker(H^*)$. Since 0 is an algebraically simple whence geometrically simple eigenvalue of H^* , it follows that $\ker(H^*) = \mathbb{R}P(\phi'_0)$ and $(M_{c_0,0}^{-1}(w), \tilde{v})_{H^1(\mathbb{R})} = 0$ for all $w \in \ker(H^*)$. This together with (6.17) and the fact that $R(H)$ is orthogonal to $\ker(H^*)$ implies that $(M_{c_0,0}^{-1}(w), \tilde{v})_{H^1(\mathbb{R})} = 0$ for all $w \in L^2(\mathbb{R})$. Then, back to equation (6.15), one gets that

$$\begin{aligned} 0 &= (\tilde{w}, \tilde{v})_{H^1(\mathbb{R} \times \mathbb{T})} + (M_{c_0,0}^{-1}(\overline{(\partial_u f(y, \phi_0) + \beta)\tilde{w}}), \tilde{v})_{H^1(\mathbb{R} \times \mathbb{T})} \\ &= (\tilde{w}, \tilde{v})_{H^1(\mathbb{R} \times \mathbb{T})} + (M_{c_0,0}^{-1}(\overline{(\partial_u f(y, \phi_0) + \beta)\tilde{w}}), \tilde{v})_{H^1(\mathbb{R})} = (\tilde{w}, \tilde{v})_{H^1(\mathbb{R} \times \mathbb{T})}, \end{aligned}$$

for all $\tilde{w} \in H^1(\mathbb{R} \times \mathbb{T})$. Thus, $\tilde{v} = 0$ and Q^* has a trivial kernel. The proof of Lemma 3.4 is thereby complete. \square

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