

A Practical Framework for Curry-Style Languages

(Inspired by realizability semantics)

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Context: using realizability for programming languages

Last year's talk was about the PML language:

- ▶ A simple but powerful mechanism for program certification
- ▶ It is embedded in a (fairly standard) ML-style language
- ▶ Everything is backed by a (classical) realizability semantics
- ▶ Property: $v \in \phi^{\perp\perp} \Rightarrow v \in \phi$ for all ϕ closed under (\equiv)

Today's talk is about making Curry-style quantifiers practical:

- ▶ They are essential for PML (polymorphism, dependent types)
- ▶ But pose a practical issue due to non-syntax-directed rules
- ▶ Restricting quantifiers (prenex polymorphism) is not an option
- ▶ **Contribution:** a solution with subtyping inspired by semantics

In this talk we will stick to System F for simplicity

Quick reminder: Church-style versus Curry-style

Church-style System F:

$$\frac{}{\Gamma, x : A \vdash x : A}$$

$$\frac{\Gamma, x : A \vdash t : B}{\Gamma \vdash \lambda x : A. t : A \Rightarrow B}$$

$$\frac{\Gamma \vdash t : A \Rightarrow B \quad \Gamma \vdash u : A}{\Gamma \vdash t u : B}$$

$$\frac{\Gamma \vdash t : A \quad X \notin \Gamma}{\Gamma \vdash \lambda X. t : \forall X. A}$$

$$\frac{\Gamma \vdash t : \forall X. A}{\Gamma \vdash t B : A[X := B]}$$

Curry-style System F is obtained by removing the highlighted parts

A natural idea: using subtyping

We define a relation (\subseteq) on types and use rule:

$$\frac{\Gamma \vdash t : A \quad A \subseteq B}{\Gamma \vdash t : B}$$

This does help a bit already:

$$\frac{A \subseteq C}{\Gamma, x : A \vdash x : C}$$

$$\frac{A \Rightarrow B \subseteq C \quad \Gamma, x : A \vdash t : B}{\Gamma \vdash \lambda x. t : C}$$

$$\frac{\Gamma \vdash t : A \Rightarrow B \quad \Gamma \vdash u : A}{\Gamma \vdash t u : B}$$

Ideally we would want quantifiers to be handled by subtyping

Containment system [Mitchell]

Is standard containment enough?

$$\frac{\{Y_1, \dots, Y_m\} \cap FV(\forall X_1 \dots \forall X_n. A) = \emptyset}{\forall X_1 \dots \forall X_n. A \subseteq \forall Y_1 \dots \forall Y_m. A[X_1 := B_1, \dots, X_n := B_n]}$$

$$\frac{}{\forall X_1 \dots \forall X_n. A \Rightarrow B \subseteq (\forall X_1 \dots \forall X_n. A) \Rightarrow (\forall X_1 \dots \forall X_n. B)}$$

$$\frac{A_2 \subseteq A_1 \quad B_1 \subseteq B_2}{A_1 \Rightarrow B_1 \subseteq A_2 \Rightarrow B_2}$$

$$\frac{A \subseteq B \quad B \subseteq C}{A \subseteq C}$$

$$\frac{A \subseteq B}{\forall X. A \subseteq \forall X. B}$$

Can we derive the quantifier rules?

Yes we can derive the elimination rule:

$$\frac{\Gamma \vdash t : \forall X.A}{\Gamma \vdash t : A[X := B]} \triangleq \frac{\Gamma \vdash t : \forall X.A \quad \frac{\emptyset \cap FV(\forall X.A) = \emptyset}{\forall X.A \subseteq A[X := B]}}{\Gamma \vdash t : A[X := B]}$$

No we cannot derive the introduction rule:

$$\frac{\Gamma \vdash t : A \quad X \notin \Gamma}{\Gamma \vdash t : \forall X.A} \triangleq \frac{\Gamma \vdash t : A \quad \frac{???}{A \subseteq \forall X.A}}{\Gamma \vdash t : \forall X.A}$$

Let us take a step back...

All we want is adequacy:

- ▶ If $\vdash t : A$ is derivable then $t \in \llbracket A \rrbracket$
- ▶ If $A \subseteq B$ then $\llbracket A \rrbracket \subseteq \llbracket B \rrbracket$

The subtyping part is not as fine-grained as it could be:

$$\frac{\vdash t : A \quad A \subseteq B}{\vdash t : B} \quad \text{can be replaced by} \quad \frac{\vdash t : A \quad \vdash t : A \subseteq B}{\vdash t : B}$$

Local subtyping is interpreted as an implication

Approach 1

(inspired by semantics)

Main idea of the approach

Based on a fine-grained semantic analysis we:

- ▶ Get rid of context and only work with closed terms
- ▶ To this aim terms are extended with choice operators
- ▶ The same kind of trick is used for quantifiers in types

Theorem (Adequacy)

- ▶ *If $t : A$ is derivable then $\llbracket t \rrbracket \in \llbracket A \rrbracket$*
- ▶ *If $t : A \subseteq B$ is derivable and $\llbracket t \rrbracket \in \llbracket A \rrbracket$ then $\llbracket t \rrbracket \in \llbracket B \rrbracket$*

Terms are interpreted using “pure terms”
(satisfying the intended semantic property)

Typing and subtyping rules

Syntax-directed typing rules:

$$\frac{\varepsilon_{x \in A}(t \notin B) : A \subseteq C}{\varepsilon_{x \in A}(t \notin B) : C}$$

$$\frac{t : A \Rightarrow B \quad u : A}{t u : B}$$

$$\frac{\lambda x. t : A \Rightarrow B \subseteq C \quad t[x := \varepsilon_{x \in A}(t \notin B)] : B}{\lambda x. t : C}$$

Syntax-directed (local) subtyping rules:

$$\frac{}{t : A \subseteq A}$$

$$\frac{t : A[X := C] \subseteq B}{t : \forall X. A \subseteq B}$$

$$\frac{t : A \subseteq B[X := \varepsilon_X(t \notin B)]}{t : A \subseteq \forall X. B}$$

$$\frac{\varepsilon_{x \in A_2}(t x \notin B_2) : A_2 \subseteq A_1 \quad t \varepsilon_{x \in A_2}(t x \notin B_2) : B_1 \subseteq B_2}{t : A_1 \Rightarrow B_1 \subseteq A_2 \Rightarrow B_2}$$

Interpretation of terms and types

We interpret terms using “pure terms” (without choice operators)

$$\begin{aligned} \llbracket x \rrbracket &= x & \llbracket \lambda x. t \rrbracket &= \lambda x. \llbracket t \rrbracket & \llbracket t u \rrbracket &= \llbracket t \rrbracket \llbracket u \rrbracket \\ \llbracket \varepsilon_{x \in A} (t^* \notin B) \rrbracket &= \begin{cases} u \in \llbracket A \rrbracket \text{ s.t. } \llbracket t[x := u] \rrbracket \notin \llbracket B \rrbracket \text{ if it exists} \\ \text{any } t \in \mathcal{N}_0 \text{ otherwise} \end{cases} \end{aligned}$$

We interpret types as (saturated) sets of normalizing terms

$$\begin{aligned} \llbracket \Phi \rrbracket &= \Phi & \llbracket A \Rightarrow B \rrbracket &= \llbracket A \rrbracket \Rightarrow \llbracket B \rrbracket & \llbracket \forall X. A \rrbracket &= \bigcap_{\Phi \in \mathcal{F}} \llbracket A[X := \Phi] \rrbracket \\ \llbracket \varepsilon_X (t \notin A) \rrbracket &= \begin{cases} \Phi \in \mathcal{F} \text{ such that } \llbracket t \rrbracket \notin \llbracket A[X := \Phi] \rrbracket \text{ if it exists} \\ \mathcal{N}_0 \text{ otherwise} \end{cases} \\ \Phi \Rightarrow \Psi &= \{t \mid \forall u \in \Phi, t u \in \Psi\} \end{aligned}$$

Let us look at one case of the adequacy lemma

$$\frac{\lambda x.t : A \Rightarrow B \subseteq C \quad t[x := \varepsilon_{x \in A}(t \notin B)] : B}{\lambda x.t : C}$$

$$\llbracket \varepsilon_{x \in A}(t^* \notin B) \rrbracket = \begin{cases} u \in \llbracket A \rrbracket \text{ s.t. } \llbracket t[x := u] \rrbracket \notin \llbracket B \rrbracket \text{ if it exists} \\ \text{any } t \in \mathcal{N}_0 \text{ otherwise} \end{cases}$$

Approach 2

(using syntactic translations)

A more standard type system

Syntax-directed typing rules:

$$\frac{\Gamma, x : A \vdash x : A \subseteq C}{\Gamma, x : A \vdash x : C}$$

$$\frac{\Gamma \vdash t : A \Rightarrow B \quad \Gamma \vdash u : A}{\Gamma \vdash t u : B}$$

$$\frac{\Gamma \vdash \lambda x. t : A \Rightarrow B \subseteq C \quad \Gamma, x : A \vdash t : B}{\Gamma \vdash \lambda x. t : C}$$

Syntax-directed (local) subtyping rules:

$$\frac{}{\Gamma \vdash t : A \subseteq A}$$

$$\frac{\Gamma \vdash t : A[X := C] \subseteq B}{\Gamma \vdash t : \forall X. A \subseteq B}$$

$$\frac{\Gamma \vdash t : A \subseteq B \quad X \notin \Gamma}{\Gamma \vdash t : A \subseteq \forall X. B}$$

$$\frac{\Gamma, x : A_2 \vdash x : A_2 \subseteq A_1 \quad \Gamma, x : A_2 \vdash t x : B_1 \subseteq B_2}{\Gamma \vdash t : A_1 \Rightarrow B_1 \subseteq A_2 \Rightarrow B_2}$$

Elimination of subtyping: translation to System $F+\eta$

System $F+\eta$ is obtained by adding the rule:

$$\frac{\Gamma \vdash \lambda x.t \ x : A \Rightarrow B \quad x \notin t}{\Gamma \vdash t : A \Rightarrow B}$$

Theorem (Translation to $F+\eta$)

- ▶ If $\Gamma \vdash t : A$ is derivable then it is also derivable in System $F+\eta$
- ▶ If $\Gamma \vdash t : A \subseteq B$ is derivable then $\Gamma \vdash t : B$ is derivable in System $F+\eta$ given a derivation of $\Gamma \vdash t : A$

Translation of subtyping leads to a “piece of proof”:

$$\begin{array}{l} \text{If } \Gamma \vdash t : A \subseteq B \text{ is derivable then we get} \\ \Gamma \vdash t : A \\ \vdots \Pi \\ \Gamma \vdash t : B \end{array}$$

The most interesting case (arrow subtyping rule)

$$\frac{\Gamma, x : A_2 \vdash x : A_2 \subseteq A_1 \quad \Gamma, x : A_2 \vdash t x : B_1 \subseteq B_2}{\Gamma \vdash t : A_1 \Rightarrow B_1 \subseteq A_2 \Rightarrow B_2}$$

$$\frac{\frac{\Gamma \vdash t : A_1 \Rightarrow B_1}{\Gamma, x : A_2 \vdash t : A_1 \Rightarrow B_1} \text{ } x \text{ fresh} \quad \frac{\overline{\Gamma, x : A_2 \vdash x : A_2} \quad \vdots \quad \Pi_1}{\Gamma, x : A_2 \vdash x : A_1}}{\frac{\Gamma, x : A_2 \vdash t x : B_1 \quad \vdots \quad \Pi_2}{\Gamma, x : A_2 \vdash t x : B_2} \quad \frac{\Gamma \vdash \lambda x. t x : A_2 \Rightarrow B_2}{\Gamma \vdash t : A_2 \Rightarrow B_2} \quad x \notin t}$$

Translation from System $F+\eta$

Given the subsumption rule the translation is immediate

$$\frac{\Gamma \vdash t : A \quad \Gamma \vdash t : A \subseteq B}{\Gamma \vdash t : B}$$

A couple of remarks:

- ▶ We conjecture that subsumption is admissible
- ▶ The rule is useful anyway for ascription (rule below)
- ▶ (Remember that type-checking remains undecidable here)

$$\frac{\Gamma \vdash t : A \quad \Gamma \vdash t : A \subseteq B}{\Gamma \vdash (t : A) : B}$$

Thanks! Questions?

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