

# Mesuring the microvibrations of a satellite on the disparity map

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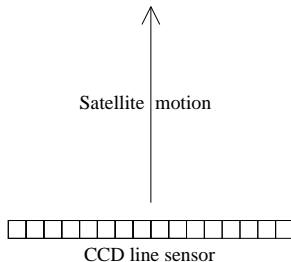
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Journée traitement de l'image  
Marseille - November 24 – 25<sup>th</sup> 2011

# Push-broom imaging system

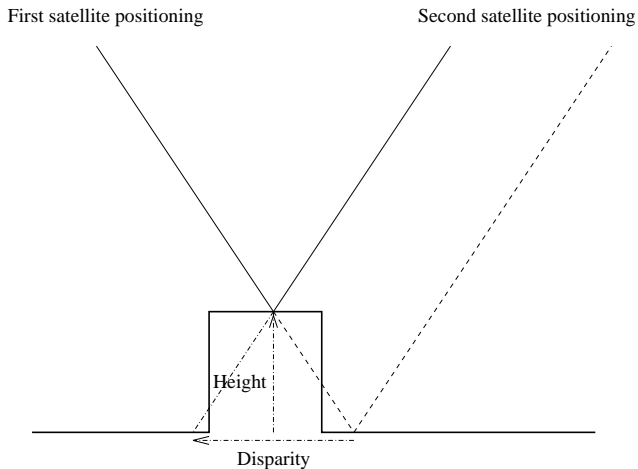


The image can be distorted by the satellite microvibrations.



But it can be restored if the microvibrations are known.

# stereoscopic acquisition



The measured disparity is proportional to the relief.

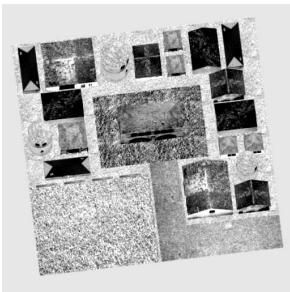


Image #1

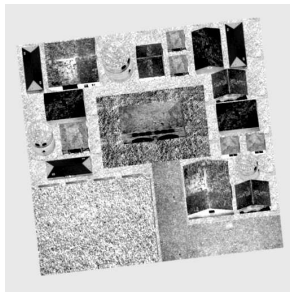
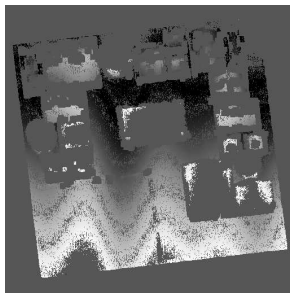


Image #2

The disparity map that is computed by MARC2 software [Sabater et al] is damaged by microvibrations



Keep the relief and microvibrations separate in order to

- obtain a good estimate of the relief,
- measure the microvibrations so as to restore the images.

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- obtain a good estimate of the relief,
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Two cases are considered

- **Case 1** : System with a single CCD line sensor  $\Rightarrow$  The satellite has to point backward for the second image acquisition  $\Rightarrow$  **Change of vibration mod.**
- **Case 2** : System with two CCD line sensors  $\Rightarrow$  The satellite does not have to point backward for the second image acquisitions  $\Rightarrow$  **Some vibration mod** for the two images (with time difference).

The vibrated stereoscopic image pair satisfy the following equations

$$\begin{aligned}I_1[k] &= P_1(k + V_1(k)), \\I_2[k] &= P_2(k + V_2(k)), \quad \forall k,\end{aligned}$$

where  $V_1$ ,  $V_2$  are the satellite microvibrations, and  $P_1$ ,  $P_2$  are the landscapes that are observed from the two positionings of the satellite.

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$$P_1(x) = P_2(x + H(x)), \quad \forall x,$$

where  $H$  is the height of the landscape (directed as the motion of the satellite). Then we have

$$l_1[k] = P_2(k + V_2(k) + H(k + V_1(k))), \quad \forall k.$$



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The disparity  $D$  is measured after image interpolation

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One obtains

$$D[k] = H(k + V_1(k)) + V_1(k) - V_2(k + D[k]).$$

$V_i(x) \approx \sum_l A_i[l] e^{i\frac{\pi}{T} l \cdot x}$ , where  $A_i$  is sparse,  $\forall i \in \{1, 2\}$ .

case 1 (Two vibration mods). Minimise

$$E_1(A_1, A_2) = \frac{1}{2} \|D - L_1 A_1 + L_2 A_2\|_2^2 + \lambda_1 \|A_1\|_1 + \lambda_2 \|A_2\|_1,$$

where  $\begin{cases} L_1 A[k] = \sum_l A[l] e^{i\frac{\pi}{T} l \cdot k}, \\ L_2 A[k] = \sum_l A[l] e^{i\frac{\pi}{T} l \cdot (k + D[k])}. \end{cases}$

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case 2 (One vibration mod). Minimise

$$E_2(A_1, A_2) = E_1(A_1, A_2) + \lambda_3 \|A_1 - S_\phi A_2\|_2^2,$$

or

$$E_3(A) = E_1(A, S_\phi A),$$

where  $S_\phi A[k] = e^{i\frac{\pi}{T} k \cdot \phi} A[k]$  car  $V_2(x) = V_1(x + \phi)$ .

- **Direct minimization scheme.**

$$E_1 = F_1 + F_2 \quad \text{where} \quad \begin{cases} F_1(A_1, A_2) = \frac{1}{2} \|D - L_1 A_1 + L_2 A_2\|_2^2, \\ F_2(A_1, A_2) = \lambda_1 \|A_1\|_1 + \lambda_2 \|A_2\|_1. \end{cases}$$

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## Iterative Shrinkage Thresholding Algorithm (ISTA)

$$\begin{aligned} (A_1, A_2)^{(n+\frac{1}{2})} &= (A_1, A_2)^{(n)} - \frac{1}{L} \nabla F_1((A_1, A_2)^{(n)}), \\ (A_1, A_2)^{(n+1)} &= \text{prox}_{\frac{1}{L} F_2}((A_1, A_2)^{(n+\frac{1}{2})}), \end{aligned}$$

$$\text{where} \quad \begin{cases} \nabla F_1(A_1, A_2) = (L_1, -L_2)^*(L_1 A_1 - L_2 A_2 - D), \\ \text{prox}_{\frac{1}{L} F_2}(A_1, A_2) = \tau_{\frac{(\lambda_1, \lambda_2)}{L}}(A_1, A_2) \text{ (soft thresholding)}. \end{cases}$$

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$$\text{where} \quad \begin{cases} \nabla F_1(A_1, A_2) = (L_1, -L_2)^* (L_1 A_1 - L_2 A_2 - D), \\ \text{prox}_{\frac{1}{L} F_2}(A_1, A_2) = \tau_{\frac{(\lambda_1, \lambda_2)}{L}}(A_1, A_2) \text{ (soft thresholding)}. \end{cases}$$

$L_1^* L_1$  and  $L_2^* L_2$  are Toeplitz matrices, but  $L_1^* L_2$  and  $L_2^* L_1$  are not.

- Alternating minimization scheme.

$$\begin{aligned}A_1^{(n+1)} &= \arg \min_A \frac{1}{2} \left\| D - L_1 A + L_2 A_2^{(n)} \right\|_2^2 + \lambda_1 \|A\|_1 \\A_2^{(n+1)} &= \arg \min_A \frac{1}{2} \left\| D - L_1 A_1^{(n+1)} + L_2 A \right\|_2^2 + \lambda_2 \|A\|_1\end{aligned}$$



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Each minimization is performed by **ISTA**.

$$\begin{aligned}A_1^{(n,k+\frac{1}{2})} &= A_1^{(n,k)} - \frac{1}{L} \nabla G_1 \left( A_1^{(n,k)} \right), \\A_1^{(n,k+1)} &= \text{prox}_{\frac{1}{L} G_2} \left( A_1^{(n,k+\frac{1}{2})} \right),\end{aligned}$$

$$\text{où } \begin{cases} \nabla G_1(A) = L_1^* L_1 A - L_1^* (L_2 A_2 + D), \\ \text{prox}_{\frac{1}{L} G_2}(A) = \tau_{\frac{\lambda_1}{L}}(A). \end{cases}$$

- Fast direct minimization scheme.

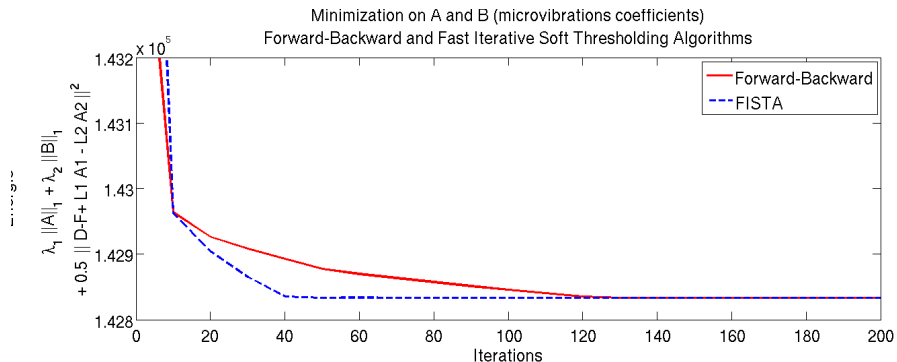
## Fast Iterative Shrinkage Thresholding Algorithm (FISTA)

$$\begin{aligned}(B_1, B_2)^{(n+\frac{1}{2})} &= (A_1, A_2)^{(n)} - \frac{1}{L} \nabla F_1 \left( (A_1, A_2)^{(n)} \right), \\(B_1, B_2)^{(n+1)} &= \text{prox}_{\frac{1}{L} F_2} \left( (B_1, B_2)^{(n+\frac{1}{2})} \right), \\(A_1, A_2)^{(n+1)} &= (B_1, B_2)^{(n+1)} + \frac{t_n - 1}{t_{n+1}} \left( (B_1, B_2)^{(n+1)} - (B_1, B_2)^{(n)} \right)\end{aligned}$$

où

$$\begin{aligned}F_1(A_1, A_2) &= \frac{1}{2} \|D - L_1 A_1 + L_2 A_2\|_2^2, \\F_2(A_1, A_2) &= \lambda_1 \|A_1\|_1 + \lambda_2 \|A_2\|_1, \\\nabla F_1(A_1, A_2) &= (L_1, -L_2)^* (L_1 A_1 - L_2 A_2 - D), \\\text{prox}_{\frac{1}{L} F_2}(A_1, A_2) &= \tau_{\frac{(\lambda_1, \lambda_2)}{L}}(A_1, A_2) \text{ (soft thresholding)}, \\t_{n+1} &= (1 + \sqrt{1 + 4t_n^2})/2.\end{aligned}$$

## Comparison between ISTA and FISTA

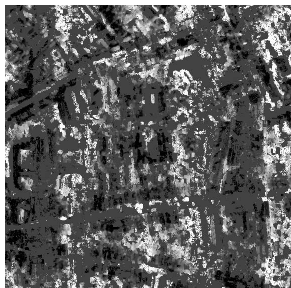


$E_2(A_1^n, A_2^n) / n$  (number of itérations)



*PLEIADES* pair

Disparity map  
computed by MARC2

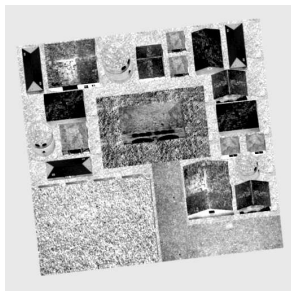
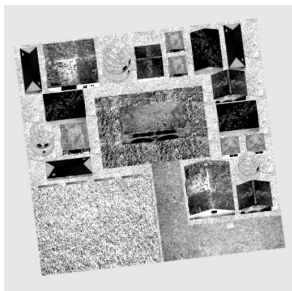


	$A_1, A_2$	Frequencies Magnitudes	<b>0,0048672</b> <b>0,25</b>	<b>0,008112</b> <b>0,25</b>
Case 1 ( $E_1$ )	$A_1$	Frequencies Magnitudes	0,00097 0,00879 0,0205 0,0209 0,018 0,042 0,039 0,016	
	$A_2$	Frequencies Magnitudes	0,0015 0,0044 <b>0,0049</b> 0,0068 <b>0,0073</b> 0,100 0,093 <b>0,40</b> 0,043 <b>0,19</b>	

Measured microvibrations

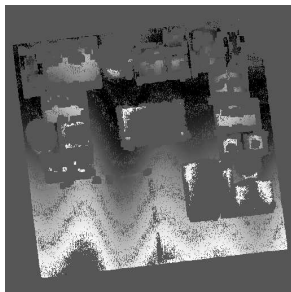
The method does not permit to keep the two microvibrations separate.

# Experimental results

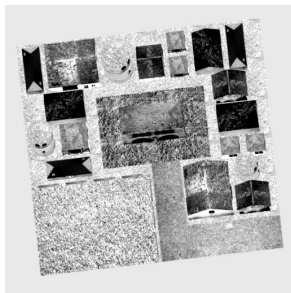
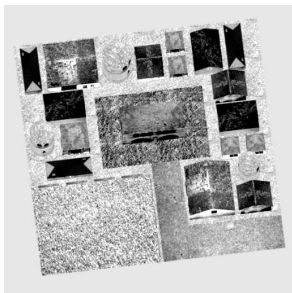


*Village pair*

Disparity map  
computed by MARC2

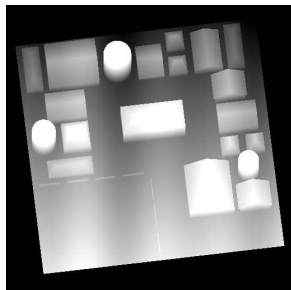


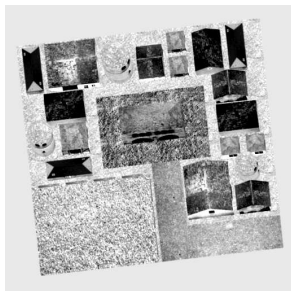
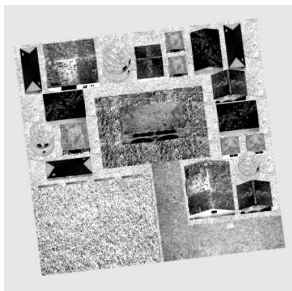
# Experimental results



*Village pair*

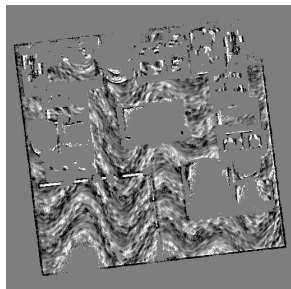
Simulated  
disparity map





*Village pair*

Difference between  
the computed map and  
the simulated map





# Experimental results

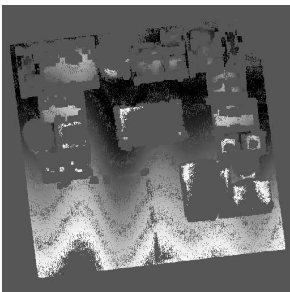
	$A_1, A_2$	Frequencies Magnitudes	<b>0,0048672</b> <b>0,25</b>	<b>0,008112</b> <b>0,25</b>
Case 1 ( $E_1$ )	$A_1$	Frequencies Magnitudes	<b>0,0049</b> <b>0,1523</b>	0,0098 0,0024
	$A_2$	Frequencies Magnitudes	0,0039 0,0001	<b>0,0068</b> <b>0,3306</b>

# Experimental results

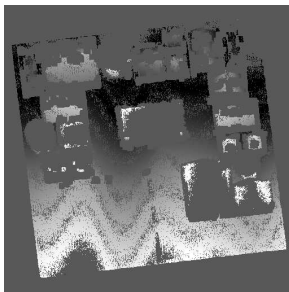
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	$A_2$	Frequencies Magnitudes	0,0039 0,0001	<b>0,0068</b> <b>0,3306</b>
Case 2 ( $E_2$ )	$A_1$	Frequencies Magnitudes	<b>0,0049</b> <b>0,066</b>	<b>0,0069</b> <b>0,16</b>
	$A_2$	Frequencies Magnitudes	0,0039 0,0025	<b>0,0049</b> <b>0,064</b>

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Case 3 ( $E_3$ )	$A_1, A_2$	Frequencies Magnitudes	<b>0,0049</b> <b>0,066</b>	<b>0,0068</b> <b>0,16</b>

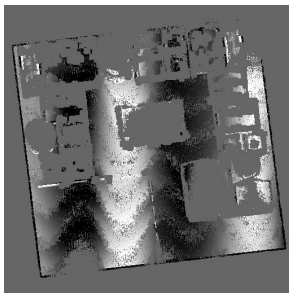


Disparity computed by MARC2



Minimizer of  $E_3$

Difference between the minimizer  
and the ground truth



# Correction of the magnitudes

The  $\ell^1$  criterion lessen the magnitude of microvibrations  
 $\Rightarrow$  Approximate the  $\ell^0$  criterion.

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<i>PLEIADES</i> pair	$A_1, A_2$	Frequencies Magnitudes	<b>0,0048672</b> <b>0,25</b>	<b>0,008112</b> <b>0,25</b>		
A contrario method	$A_1$	Frequencies Magnitudes	0,00097 361,36	0,0014 141,85	0,0044 8,68	0,0049 8,65
	$A_2$	Frequencies Magnitudes	0,00097 361,36	0,0014 141,83	0,0044 8,65	0,0049 8,61

The a contrario method detects low frequency outliers that arise from the relief (the white noise hypothesis is false).

# Correction of the magnitudes

The  $\ell^1$  criterion lessen the magnitude of microvibrations  
 $\Rightarrow$  Approximate the  $\ell^0$  criterion.

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- Change the soft thresholding into a **hard thresholding**

<i>Village pair</i>	$A_1, A_2$	Frequencies Magnitudes	<b>0,0048672</b> <b>0,25</b>	<b>0,008112</b> <b>0,25</b>
Case 3 ( $E_3$ )	$A_1, A_2$	Frequencies Magnitudes	<b>0,0049</b> <b>0,30</b>	<b>0,0068</b> <b>0,34</b>

The magnitude of microvibrations is no longer lessen. But the measure is still disrupted by the relief.

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$\Rightarrow$  **Insert the relief into the model**



# New method with regularization on the relief

One assumes that the relief is affine on each connected component of the disparity map.

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case 1 . Minimise

$$E_4(A_1, A_2, H) = \frac{1}{2} \|D - H - L_1 A_1 + L_2 A_2\|_2^2 + \lambda_1 \|A_1\|_1 + \lambda_2 \|A_2\|_1 + \lambda_4 \|\nabla^2 H\|_1,$$

where  $\nabla^2 H$  denotes the second derivative of  $H$ .

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where  $\nabla^2 H$  denotes the second derivative of  $H$ .

## case 2 . Minimise

$$E_5(A_1, A_2, H) = E_4(A_1, A_2, H) + \lambda_3 \|A_1 - S_\phi A_2\|_2^2,$$

ou

$$E_6(A, H) = E_4(A, S_\phi A, H).$$

## Alternating minimization scheme

$$(A_1, A_2)^{(n+1)} \\ = \arg \min_{A_1, A_2} \frac{1}{2} \|D - H^{(n)} - L_1 A_1 + L_2 A_2\|_2^2 + \lambda_1 \|A_1\|_1 + \lambda_2 \|A_2\|_1$$

$$H^{(n+1)} \\ = \arg \min_H \frac{1}{2} \|D - H - L_1 A_1^{(n+1)} + L_2 A_2^{(n+1)}\|_2^2 + \lambda_4 \|\nabla^2 H\|_1$$

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The first minimization is performed by **FISTA**,

## Alternating minimization scheme

$$(A_1, A_2)^{(n+1)} \\ = \arg \min_{A_1, A_2} \frac{1}{2} \|D - H^{(n)} - L_1 A_1 + L_2 A_2\|_2^2 + \lambda_1 \|A_1\|_1 + \lambda_2 \|A_2\|_1$$

$$H^{(n+1)} \\ = \arg \min_H \frac{1}{2} \|D - H - L_1 A_1^{(n+1)} + L_2 A_2^{(n+1)}\|_2^2 + \lambda_4 \|\nabla^2 H\|_1$$

The first minimization is performed by **FISTA**,

The seconde minimization is performed by a **dual method**.

$$H^{(n+1)} = U - P_K(U)$$

where  $U = D - L_1 A_1^{(n+1)} + L_2 A_2^{(n+1)}$  and  $P_K$  is the projection onto

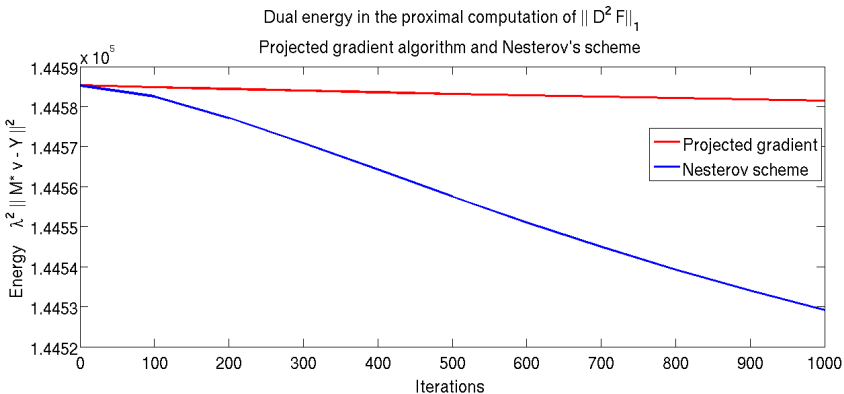
$$K = \left\{ (\nabla^2)^* V : V \in (\mathbb{R}^N)^4 \text{ et } V'[k] \in [-\lambda_4, \lambda_4], \forall k, \forall l \in \{1, \dots, 4\} \right\}.$$

Computation of the projection  $P_K$  by

- **Projected gradient**

Computation of the projection  $P_K$  by

- Projected gradient
- Nesterov's scheme



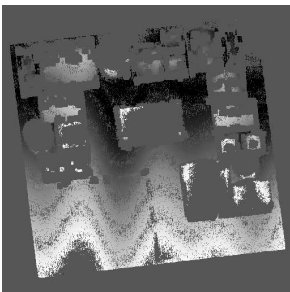


## Case 1. Two vibration mods

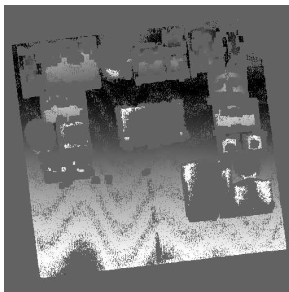
	$A_1, A_2$	Frequencies Magnitudes	<b>0,0048672</b> <b>0,25</b>	<b>0,008112</b> <b>0,25</b>	
$E_1$	$A_1$	Frequencies Magnitudes	<b>0,0049</b> <b>0,1523</b>	0,0098 0,0024	
	$A_2$	Frequencies Magnitudes	0,0039 0,0001	<b>0,0068</b> <b>0,3306</b>	
$E_4$	$A_1$	Frequencies Magnitudes	<b>0.0049</b> <b>0.2274</b>	<b>0.0078</b> <b>0.3153</b>	<b>0.0088</b> <b>0.1108</b>
	$A_2$	Frequencies Magnitudes	<b>0.0049</b> <b>0.0668</b>		

## Case 2. One vibration mod

	$A_1, A_2$	Frequencies Magnitudes	<b>0,0048672</b> <b>0,25</b>	<b>0,008112</b> <b>0,25</b>	
$E_2$	$A_1$	Frequencies Magnitudes	<b>0,0049</b> <b>0,066</b>	<b>0,0069</b> <b>0,16</b>	
	$A_2$	Frequencies Magnitudes	0,0039 0,0025	<b>0,0049</b> <b>0,064</b>	<b>0,0068</b> <b>0,16</b>
$E_5$	$A_1$	Frequencies Magnitudes	<b>0.0049</b> <b>0.21</b>	<b>0.0078</b> <b>0.17</b>	<b>0.0088</b> <b>0.08</b>
	$A_2$	Frequencies Magnitudes	<b>0.0048</b> <b>0.21</b>	<b>0.0078</b> <b>0.17</b>	<b>0.0088</b> <b>0.08</b>



Disparity computed by MARC2



Minimizer of  $E_5$

Difference between the minimizer  
and the ground truth

