# Self-induced systems 

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Joint work with Nic Ormes, Samuel Petite

## A possible motivation for this talk

Question of Christian Mauduit (Ferenczi, 2006) :
What can be said of the following substitution on $A=\mathbb{Z}$ ?

- Drunken man substitution : $n \mapsto(n-1)(n+1)$


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But this is not the original motivation
We will come back to these substitutions later

## The question of this talk

What are the self-induced systems ?

## Induced map

$$
T: X \rightarrow X, U \subset X
$$



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$T: X \rightarrow X, U \subset X$

$T_{U}: U \rightarrow U$

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$T: X \rightarrow X, U \subset X$

$T_{U}: U \rightarrow U$
$\left(U, T_{U}\right)$ : induced system

## The framework

Dynamical system : $(X, T)$


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Dynamical system : $(X, T)$

- $X$ : compact metric space
- $T$ : homeomorphism
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(Moving) definition : $(X, T)$ is self-induced if $(X, T)$ if there exists $U \subsetneq X$ (???) such that $(X, T)$ is isomorphic (???) to $\left(U, T_{U}\right)$ (???).


## How to ensure $T_{U}$, and $\left(U, T_{U}\right)$, are well defined?

- Poincaré recurrence theorem : $T_{U}$ defined $\mu$-almost everywhere (for some fixed $T$-invariant measure $\mu$ with $\mu(U)>0)$


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- Poincaré recurrence theorem : $T_{U}$ defined $\mu$-almost everywhere (for some fixed $T$-invariant measure $\mu$ with $\mu(U)>0)$
- $(X, T)$ minimal and $U$ open.
- or any way to have $\left(U, T_{U}\right)$ well defined


## Some examples: minimal substitutions subshifts

Theorem. (Mossé 1992) Let $(X, S)$ be a subshift generated by the primitive substitution $\tau: A^{*} \rightarrow A^{*}$. Then,

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\tau: X \rightarrow X
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Proof: $U=\tau(X)$ is a clopen set.

## A too classical minimal substitutions subshifts

$\tau: 0 \mapsto 01,1 \mapsto 0, \tau(x)=x \in\{0,1\}^{\mathbb{Z}}, S$ the shift,

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$\tau(X)=[0]$

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\begin{array}{rl}
x=\tau(x) & =01 \\
0 & 0 \\
01 & 01 \\
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0 & 01 \\
\mathcal{D}_{0}(x) & =0
\end{array} 1
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- Observation: The subshift generated by $\mathcal{D}_{0}(x)$ is isomorphic to ([0], $S_{[0]}$ ).


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- Observation: The subshift generated by $\mathcal{D}_{0}(x)$ is isomorphic to ([0], $S_{[0]}$ ).
- $(X, S)$ is isomorphic to ([0], $\left.S_{[0]}\right)$ and is self-induced.


## An other classical minimal substitutions subshifts

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\begin{aligned}
\sigma: 0 \mapsto 01,1 \mapsto 10, \tau(x) & =x \in\{0,1\}^{\mathbb{Z}}, \\
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011 & 01 & 0 & 011 & 0 & 01 & 011 & 01 & 0 & 01 & 011 & 0 & \cdots \\
\mathcal{D}_{0}(x) & = & 1 & 2 & 0 & 2 & 1 & 0 & 1 & 2 & 1 & 0 & 2
\end{array} \\
0 & 1
\end{array}
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- Observation: The subshift generated by $\mathcal{D}_{0}(x)$ is isomorphic to ([0], $S_{[0]}$ ).
- $(Y, S)$ is not isomorphic to ([0], $\left.S_{[0]}\right)$ but is self-induced.


## Other induction properties of substitutions subshifts

- (Holton-Zamboni 1999) A minimal subshift is substitutive if, and only if, it has (up to isomorphism) finitely many induced systems on cylinder sets


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- Let $(X, S)$ be a minimal substitution subshift. For all clopen set $U \subset X$ there is a clopen set $V \subset U$ such that $(X, S)$ is topologically conjugate to $\left(V, S_{V}\right)$.


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- Let $(X, S)$ be a minimal substitution subshift. For all clopen set $U \subset X$ there is a clopen set $V \subset U$ such that $(X, S)$ is topologically conjugate to $\left(V, S_{V}\right)$.
- This property is equivalent to the self-induction property on clopen sets.


## Some examples: Rotations on the torus

Theorem. (Ornstein-Rudolph-Weiss 1982) Let ( $\mathbb{T}, R_{\alpha}$ ) and ( $\mathbb{T}, R_{\beta}$ ) be two non periodic rotations. There exists a Lebesgue set $U$, with $\operatorname{Leb}(U)>0$, such that $\left(U, R_{\alpha, U}\right)$ is (measure theoretically) isomorphic to ( $\mathbb{T}, R_{\beta}$ ).

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But, Sturmian subshifts are self-induced on clopen sets if, and only if, ... (can you expect?) the "slope" is quadratic.

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Let $\left(p_{n}\right)_{n}$ be a sequence of integers such that $p_{n}$ divides $p_{n+1}$

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\mathbb{Z}_{\left(p_{n}\right)}=\left\{\left(x_{n}\right) \in \prod_{n=1}^{\infty} \mathbb{Z} / p_{n} \mathbb{Z}: x_{n} \equiv x_{n+1} \quad \bmod p_{n}\right\}
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Exercise. The odometer $\left(\mathbb{Z}_{\left(p_{n}\right)}, z \mapsto z+1\right)$ is self-induced (on a clopen set) if, and only if,

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Example. If $\left(p_{n}\right)$ is the sequence of prime numbers then $\left(\mathbb{Z}_{\left(p_{n}\right)}, z \mapsto z+1\right)$ is not self-induced (on a clopen set)

## Some examples: the full shift

Exercise. (Example of G. Vigny) The full shift is (topologically) self-induced (on a closed set).

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Proof: $U=\left\{\left(x_{n}\right)_{n \in \mathbb{Z}} \mid x_{2 n} x_{2 n+1} \in\{00,11\}\right\}$ (closed set)

## Observation: Abramov formula

$$
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$$
\left.\begin{array}{l}
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## Observation: Abramov formula

$(X, T, \mu), \mu(U)>0$

$$
h\left(U, T_{U}, \mu_{U}\right)=\frac{h(X, T, \mu)}{\mu(U)}
$$

Consequence: if $\left(U, T_{U}, \mu_{U}\right)$ and $(X, T, \mu)$ are isomorphic then

$$
h(X, T, \mu) \in\{0,+\infty\}
$$

## Some answers: expansive case (subshifts)

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What about non-expansive and non-equicontinuous systems?

## Expansiveness and equicontinuity

$T: X \rightarrow X$ on a compact metric space $(X, d)$ is

- expansive if :

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\exists \delta>0, \forall x, y \in X, x \neq y, \exists n \in \mathbb{Z}, d\left(T^{n} x, T^{n} y\right)>\delta
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- equicontinuous if :

$$
\forall \epsilon>0, \exists \delta>0,\left(d(x, y) \leq \delta \Longrightarrow d\left(T^{n} x, T^{n} y\right)<\epsilon \forall n\right)
$$

## Some answers: all ergodic systems are self-induced

Definition. Let $(X, T)$ be a minimal Cantor system. We say that a nonempty closed set C is a Poincaré section for $(X, T)$ if the induced map $T_{C}: C \rightarrow C$ is a well-defined homeomorphism.

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Theorem. (Dahl-Molberg 2009) Let $(X, T)$ and $(Y, R)$ be minimal Cantor systems. Then, there exists a Poincaré section $C$ in $(Y, R)$ such that $\left(C, R_{C}\right)$ is topologically conjugate to $(X, T)$.

Proof: easy with Bratteli diagrams

## Bratteli diagrams

This book is the firs seff-comained exposition of the fascinating link between dynamical sysems and dimension gropsp The authors explore the
rich motrificy between tonolhachal properiks of dyamicel systems and rich metriny between topolegetcal propertes of dyamical systems rad the aleberate structires asocinted with then. whit in emphasis op sy, bolve sysens, particulaty subsitution systams. If is recomimended for
anybody with an incest in topolegical and symbolit dynamics, auonate anybody with at metest in topologe

Interded to serve as an mutrectuction far graduate studems and owher the book inclades a horvougl account of the background notions as well he derailed exposition -with full proos - of the major resuls of the subjeet A wealth of examples and exercives, with solutions serwe to build intuition while the many coen problems collceced at the end provide jumping-off points for future research
Cambridge Studies in Advanced Mathenatics mintuil somad
Jean Betan Drizrusy of Zarion


Ieke Moerdik Uirecha Uomuersip
Cheryl Pracger University of Wixarn Australia
Pelet Sanak Prinecour Lifivenio
 Burt Toam Universiy of Combertia Laxthreles

## Dimension Groups and Dynamical Systems

FABIEN DURAND DOMINIQUE PERRIN

The idea for Dahl-Molberg theorem


## Some corollaries

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Corollary. "Ergodic systems are self-induced" Proof: Vershik representation of ergodic systems

## Main result

Theorem. Let $(X, T)$ be a minimal Cantor system. It is a self-induced (on a clopen set) if, and only if, $(X, T)$ is conjugate to a recognizable, primitive, aperiodic, generalized substitution subshift.

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- $\sigma: K^{*} \rightarrow K^{*}$ where $K$ is a compact metric space (alphabet)
- For $w \in K^{+}$and $1 \leq j \leq|w|, \pi_{j}(w)$ is the $j$ th letter of $w$.


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- $\sigma: K^{*} \rightarrow K^{*}$ where $K$ is a compact metric space (alphabet)
- For $w \in K^{+}$and $1 \leq j \leq|w|, \pi_{j}(w)$ is the $j$ th letter of $w$. $\sigma$ is a generalized substitution if :


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- $a \mapsto|\sigma(a)|$ is continuous
- $\pi_{j} \circ \sigma$ is continuous on the set $\{a \in K:|\sigma(a)| \geq j\}$.


## Proof of the main result

Proof: Set $A=X$, define $\sigma: A \rightarrow A^{+}$by

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\sigma(x)=\varphi(x) T(\varphi(x)) T^{2}(\varphi(x)) \cdots T^{r u(\varphi(x))-1}(\varphi(x))
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where $r_{U}(\varphi(x))$ is the return time of $\varphi(x)$ to $U=\varphi(X)$ where $\varphi$ is the conjugacy. $\square$

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Question : Does there exist something else than "classical substitutions"?

## Primitive and recognizable substitutions

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- $\sigma$ is recognizable if for every $z \in X$, there is a unique set of integers $n_{k}: k \in \mathbb{Z}$ and a unique $x \in X$ such that $\sigma\left(x_{k}\right)=z\left[n_{k}, n_{k+1}-1\right]$ for all $k \in \mathbb{Z}$.


## Infini-Bonacci substitution

$$
\begin{array}{ll}
A=\{1, \ldots\} \cup\{\infty\} & \\
& n \mapsto 1(n+1), \infty \mapsto 1 \infty
\end{array}
$$

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- $\mathcal{A}_{i}=\{0,1, \ldots, i\}$ and

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\begin{aligned}
& \sigma_{i}: 0 \mapsto 01, i \mapsto i 0, \text { and } a \mapsto(a+1) 0, \text { for } a \neq 0, i, \\
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- The system it generates is not expansive nor equicontinuous


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$$
\sigma(x)= \begin{cases}S(x) z & \text { if } x_{0}=0 \\ S(x) z z & \text { if } x_{0}=1\end{cases}
$$

or more concisely,

$$
\sigma(x) \mapsto S(x) z z^{x_{0}} .
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## Proposition.

There exist self-induced (on clopen sets) minimal Cantor systems which are uniquely ergodic or not, and, with zero or infinite entropy.

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- $X$ orbit closure of some well-chosen $z \in \mathbf{K}$
- $(X, T)$ is self-induced of the clopen set $\varphi(X)$.

THANK YOU FOR YOUR ATTENTION

